SOAC

STATE-OF-THE-ART CAR DEVELOPMENT PROGRAM FINAL TEST REPORT

VOLUME 3: ACCEPTANCE TESTING

Boeing Vertol Company

(A division of The Boeing Company)
Surface Transportation Systems Branch
Philadelphia, Pa. 19142



APRIL 1974 FINAL REPORT

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	ttractiveness of rapid rai	
		vehicles that are as com-

fortable, reliable, safe and economical as possible. The SOAC is one phase of this program.

All Performance, Ride Quality, Noise and EMI Acceptance Tests were conducted by Boeing Vertol Company, St. Louis Car Division, and GSI Castings Division of General Steel Industries, Inc. at the High Speed Ground Test Center at Pueblo, Colorado.

This document, Volume III plus the following additional volumes comprise Boeing Vertol Report D174-10024, State-of-the-Art Car Final Test Report as specified in Section 17.1.4.2 of the SOAC Detail Specification

Component Testing

Volume II Subsystem Functional Testing

Volume IV Simulated Demonstration Test

Volume V Post Repair Testing

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APPENDICES

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- II. TEST DATA SHEETS Performance, Ride Quality, Noise, EMI Tests
- III. RIDE QUALITY TEST REPORT D174-10025-1
 - IV. ELECTROMAGNETIC INTERFERENCE TEST REPORT (WO 1152-T)

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1. INTRODUCTION

The U.S. Department of Transportation, Urban Mass Transportation Administration (UMTA), under CONTRACT DOT-UT-10007, has engaged the Boeing Vertol Company to act as Systems Manager of the Urban Rapid Rail Vehicle and Systems Program. This program is an integrated development program directed toward improving high speed, frequent-stop urban rail systems. The overall objective is to enhance the attractiveness of rail transportation to the urban traveler by providing service that is as comfortable, reliable, safe and economical as possible.

The objective of the State-of-the-Art Car (SOAC) is to demonstrate the best state-of-the-art in rapid railcar design, with two new improved cars using existing proven technology. Primary goals for the cars are passenger convenience and operating efficiency.

This report presents the results of acceptance tests performed on the SOAC low and high-density cars individually and as a two-car train. These tests were conducted on the two cars at the U.S. Department of Transportation High Speed Ground Test Center in Pueblo, Colorado during the period November 1972 to April 17, 1973. Final acceptance testing was initiated on March 9, 1973 and completed on April 12, 1973.

The 80 mph transit oval, 9.1 miles in length, was utilized for all performance tests. Third rail power at a nominal 650 VDC was provided by DOT Locomotive No. 001, and two 500 KW auxiliary generators.

The SOAC final acceptance tests are outlined in Table I. The test program plan and procedures are described in Boeing Vertol Report D174-10007-1. The acceptance test procedures and test instrumentation were designed to prove compliance with Section 2.2 of the SOAC Detail Specification IT-06-0026-73-2.

This document, Volume III - Acceptance Testing, plus the following additional volumes comprise Boeing Vertol Report D174-10024, State-of-the-Art Car Final Test Report as specified in Section 17.1.4.2 of the SOAC Detail Specification.

Volume I - Component Testing

Volume II - Subsystem Functional Testing Volume IV - Simulated Demonstration Test

Volume V - Post Repair Testing

TABLE I

FINAL ACCEPTANCE TESTS

Car Weight 105,000 lb. Nominal 600 Volts dc

	TYPE OF TEST	TRAIN CONFIGURATION
0	Visual	L-D and H-D Cars
0	Acceleration - Initial Rate - Time-Speed-Distance	L-D Car; H-D Car; 2-Car Train-Both Directions
0	Maximum Speed	L-D Car; H-D Car; 2-Car Train-Both Directions
0	Automatic Speed Maintaining System	L-D Car; H-D Car
o	Blended Braking - Deceleration Rate - Stopping Distance	L-D Car; H-D Car; 2-Car Train-Both Directions
0	Dynamic Braking Only - Deceleration Rate - Stopping Distance	L-D Car; H-D Car; 2-Car Train-Both Directions
0	Service Friction Braking -Deceleration Rate -Stopping Distance	L-D Car; H-D Car; 2-Car Train-Both Directions
0	Emergency Braking - Deceleration Rate - Stopping Distance	L-D Car; H-D Car; 2-Car Train-Both Directions
0	Service Duty Cycle - Blended Braking - Service Friction Braking	L-D Car H-D Car
0	Ride Quality	H-D Car 2-Car Train
0	Noise	L-D Car H-D Car
0	EMI-Electromagnetic Interference	2-Car Train

2. SUMMARY OF TEST RESULTS

2.1 PERFORMANCE DATA

The results of the final acceptance performance tests are summarized in Table II for the low-density car, the high-density car, and the two-car train. The data contained in these summaries are the results of car performance averaged over several data records.

For example, the acceleration rates and times to 700 feet distance are based on a two-direction average (forward and reverse) with two data records in each direction. Braking rates and distances are based on two stops in each car direction from four separate initial speeds. In addition to averaging rates over several data records, both a longitudinal accelerometer and a time differentiation of the speedometer instrumentation were used for each record.

Test instrumentation is outlined in Section 4. As noted in Table II, the individual cars and the two-car train meet the specified acceleration and braking performance. Actual test data showing the cars' performance characteristics are contained in Section 6.

2.2 RIDE QUALITY DATA

Figures 2-1, 2-2 and 2-3 summarize the results of the ride quality measurements taken on the cars following structural modifications to the motor-alternator support structure. The complete ride quality acceptance data package is contained in the Appendix III Test Report. Results of the later engineering tests are reported in the Engineering Test Report, D174-10026-1.

Test data for a 90,000-lb. single car is shown in Figure 2-1. Data for a 105,000-lb. car singly and in a two-car train are shown in Figures 2-2 and 2-3 respectively. At the 90,000-lb. car weight (empty car) the SOAC essentially met the ride quality goal in the frequency range associated with the rigid body suspension frequencies: 1-2 Hz. In the higher frequency range associated with car body flexible modes: 7-15 Hz, the goal could not be met with the existing car body structural characteristics. The vibration investigation program reported in Appendix III did result in a reduction of the maximum vibration levels in the 15 Hz range from .26g to .10g. Although this exceeds the design goal of .055g at this frequency, the SOAC is considered satisfactory by passenger observations.

TABLE II

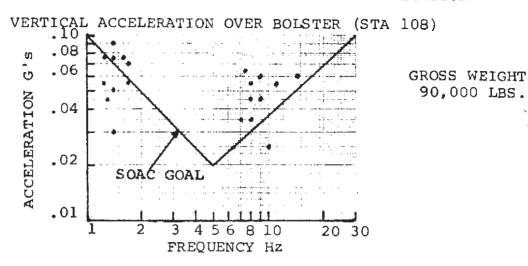
SOAC ACCEPTANCE TESTS

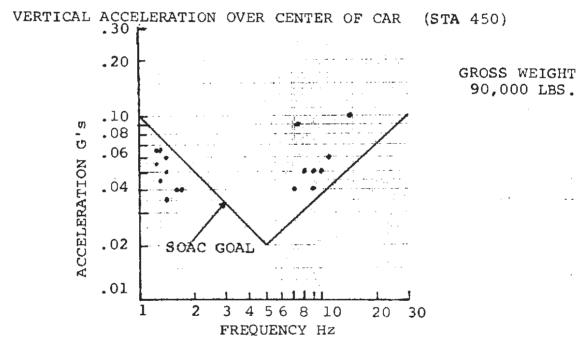
[105,000 LB CAR WEIGHT] 600 Volts

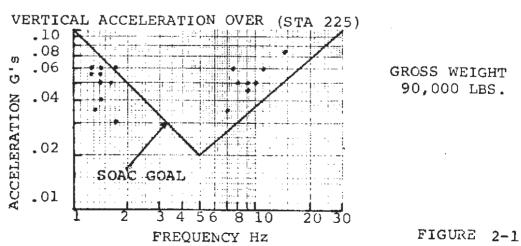
DEDECOMANCE THEM			SPECIFICATION	R	ESULTS		
PERFORMANCE ITEM		REQUIREMENT	LOW-DENSITY	HIGH-DENSITY	2-CAR TRAIN		
1.	PEAK (INITIA	L) ACCELERATION	ON RATE	2.7-3.3 MPH/SEC	2.7 *	2.7 *	2.7*
2.		EL 700' FROM / VEL TANGENT TI		20 SEC	19.4	19.0	20.0
3.	SPEED ON A 39	% ADVERSE GRAI	DE	70 MPH	>75	>75	N/A
4.	MAXIMUM SPEE	0		80 MPH	80	80	80
		BLENDED	SERVICE	2.7-3.3 MPH/SEC	3.2	3.2	3.2
5.	DECELERATION RATES (PEAK)	} { DYNAMIC	ONLY	2.7-3.3 MPH/SEC	3.0	3.0	3.1
			FRICTION	2.7-3.3 MPH/SEC	3.1	3.2	3.2
6	JERK RATE	ACCELERATION		2.5 MPH/SEC ²	1.9	2.3	1.8
0.	OLKK KATE	BRAKING		2.5 MPH/SEC ²	2.9	2.6	2.6
7	STOPPING DIST	TANCENBLENDED PH) ∫\SERVICE	SERVICE	4 50 FT	430	445	430
	(FROM 40 MI	PH) ĴSERVICE	FRICTION	450 FT	440	425	420
	STOPPING DIS	TANCE] BLENDED	SERVICE	2250 FT	1650	1660	1660
8.	(FROM 80 MI	PH) SERVICE		2250 FT	1960	2000	1925
		STOP FROM 40	MPH	425 FT	365	350	335
9.	EMERGENCY) BRAKING	STOP FROM 80	MPH	2200 FT	1630	1600	1635
	DIAKING)	DECELERATION	RATE	2.88-3.52 MPH/SEC	3.5	3.4	3.5

^{*} Initial rates of 3.0 mph/sec. were recorded during Acceptance Testing prior to final current limit adjustments.



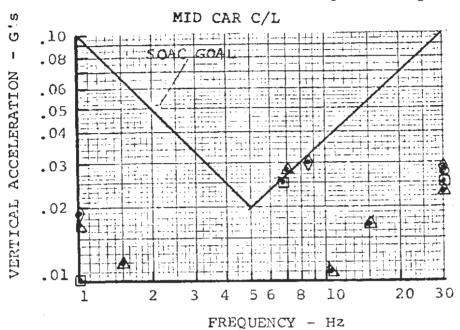






SOAC RIDE QUALITY

Resilient Wheels
Track Section = I
Gross Weight = 105,000 LBS.
High Density Car



O= 20 MPH O= 35 MPH \diamond = 45 MPH \triangle = 55 MPH \triangle = 80 MPH

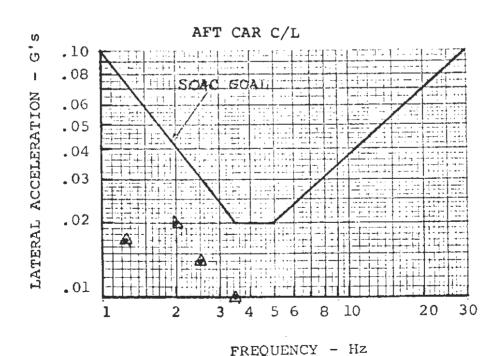
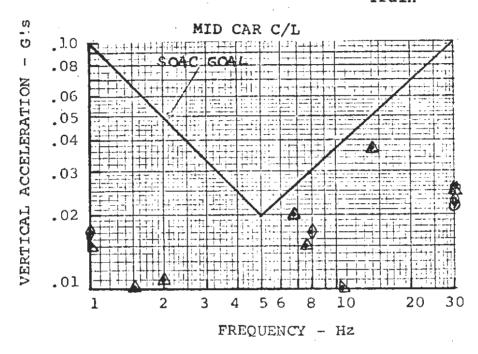


FIGURE 2-2

SOAC RIDE QUALITY

Resilient Wheels
Track Section = I
Gross Weight - 105,000LBS.
Train



O = 20 MPH O = 35 MPH \diamondsuit = 45 MPH \triangle = 55 MPH \triangle = 80 MPH

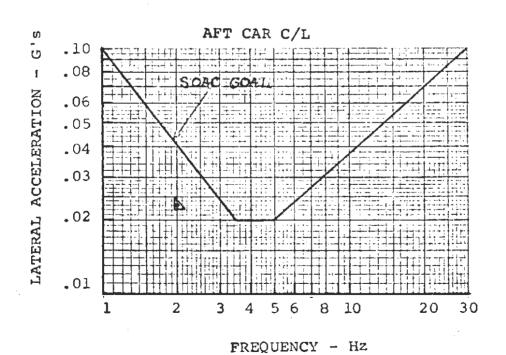


FIGURE 2-3

The results of testing the SOAC at the 105,000-lb. weight (100 passenger load) are shown in Figures 2-2 and 2-3. As noted in these figures the ride quality measurements show compliance with the SOAC goals over the frequency range at both mid and aft car centerlines. These data were obtained during later car tests and are based on the instrumentation system used during the Engineering Test Program.

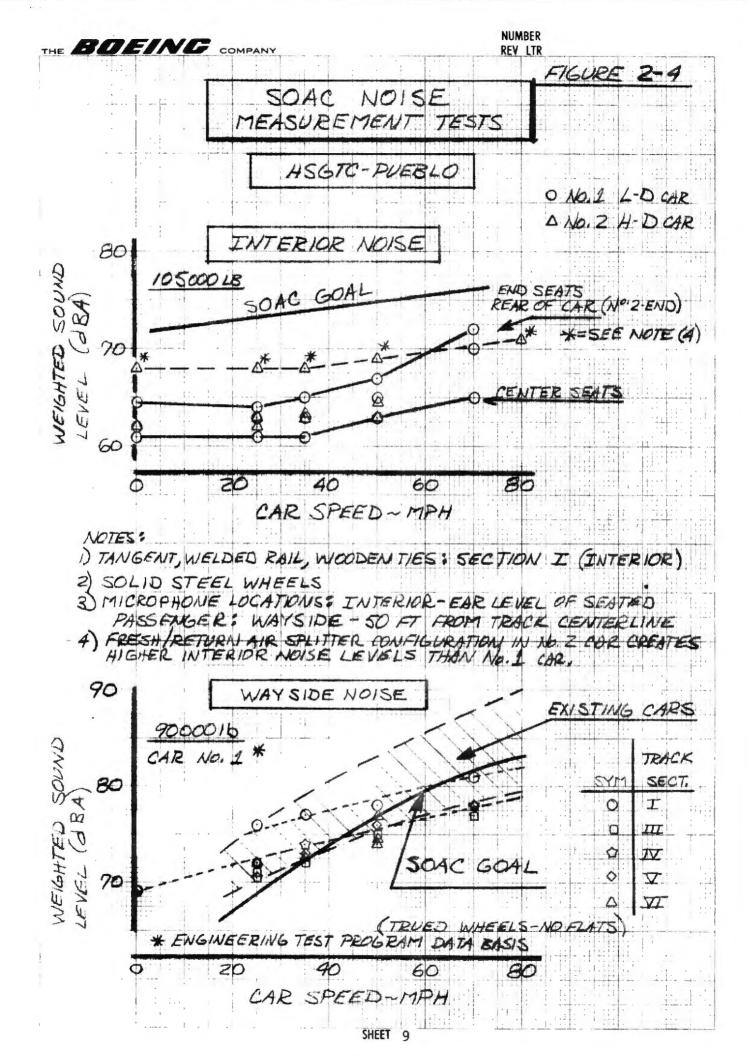
Based on the above data the SOAC is capable of meeting all the ride quality goals under a loaded car condition representing normal operating car weights. The ride quality requirements were originally expressed as goals rather than as acceptance requirements due to the scope of the program which used a basic R44 car body.

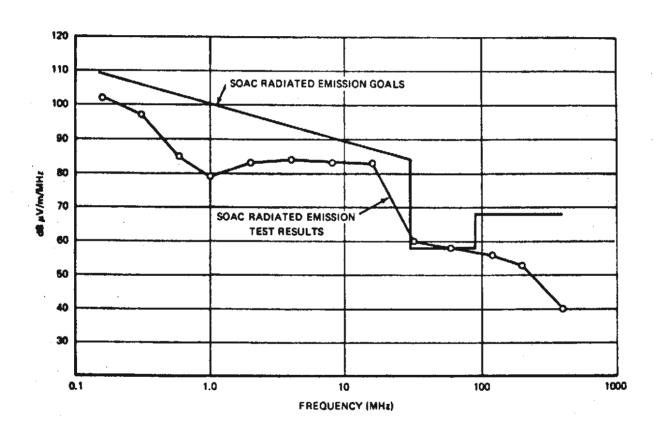
2.3 NOISE DATA

Figure 2-4 presents a summary of interior and wayside noise data taken during the acceptance and engineering test programs on the SOAC. As noted in the upper portion of Figure 2-4, the interior noise measurements show that both cars meet the noise goal at all speeds. The SOAC also meets the wayside noise goal at speeds above 35 to 40 mph on Pueblo track Sections III to VI but only above 65 mph on Section I. Due to the increased rail roughness of this track section at speeds below those noted above, the car equipment noise level (cooling fans, motoralternator set) results in a wayside sound level somewhat greater than the goal. A band of wayside noise levels for existing transit cars is also shown on Figure 2-4 for comparison with the SOAC data. As noted, the SOAC noise level is comparable to the lower level for contemporary equipment. The SOAC noise goal was based mainly on wheel-rail noise with little allowance for the actual car equipment required for the SOAC propulsion system (69 dBA at zero speed). Paragraph 6.10 presents a discussion of the noise tests.

2.4 <u>ELECTROMAGNETIC INTERFERENCE DATA (EMI)</u>

Testing to determine the electromagnetic field strength inside the SOAC as well as at the wayside was performed at the HSGTC on April 2 and 3, 1973. As shown in Figure 2-5 test data indicate the SOAC is within field limits from a frequency range of 150 KHz to 400 MHz. Since there was no substantial noise peak within the car body, it was not necessary to track down corresponding sources.





SOAC Electromagnetic Field Test Data

FIGURE 2-5

3. CONFIGURATION

Acceptance tests were conducted on the low-density car (No. 1) and the high-density car (No. 2) individually and as a two-car train. Both cars were ballasted with lead weights to the normal load (AW1) of 105,000 lb., representing the light car plus 100 passengers at 150 lb. each. The weight breakdown for each car is presented in Table III.

TABLE III

CAR WEIGHTS - SOAC

	HDC	LDC
Light Weight at St. Louis Car	88,320#	89,080#
Pantograph Scale Weight, March 15, 1973	775#	775#
*Equipment Brackets added at Pueblo	320 #	320#
Miscellaneous	169#	114#
Light Weight at Rail Ready to Run	89,584#	90,289#
Lead Bars (HDC 328) (LDC 313)	15,416#	14,711#
AW1	105,000#	105,000#

^{*}Equipment Brackets - estimated weight.

HDC and LDC were loaded to AW1 night of March 13, 1973.

4. TEST EQUIPMENT AND INSTRUMENTATION

The following facilities, equipment and instrumentation were used during the acceptance testing.

4.1 FACILITIES AND EQUIPMENT

The 80 mph Rail Transit Test Track at the High Speed Ground Test Center consisting of 9.1 miles of running rails and electrified third rail was used for all performance, ride quality, noise, and EMI tests. The test track is powered by a modified General Electric U30C Diesel-Electric Locomotive rated at 3000 hp for traction or 3400 amps at 600 VDC. Two auxiliary caterpillar diesel-generator sets rated at 500 KW each (600-700 VDC) were positioned around the oval to minimize track voltage drops during high-power acceleration testing.

Figure 4-1 illustrates the basic electrical layout of the track and the locations of the power supplies.

Figure 4-2 illustrates the relationship of the running and third rails. The following additional facilities were also used:

- o General Electric 44-ton, 380 hp switch engine and gondola-transition car.
- o Transit maintenance building: 200 ft. long by 40 ft. wide with AC and 600 VDC power, and a 6 ft. maintenance pit.
- o Office facilities in the Project Management Bldg.
- Track communications: Four-channel Motorola walkie-talkies.

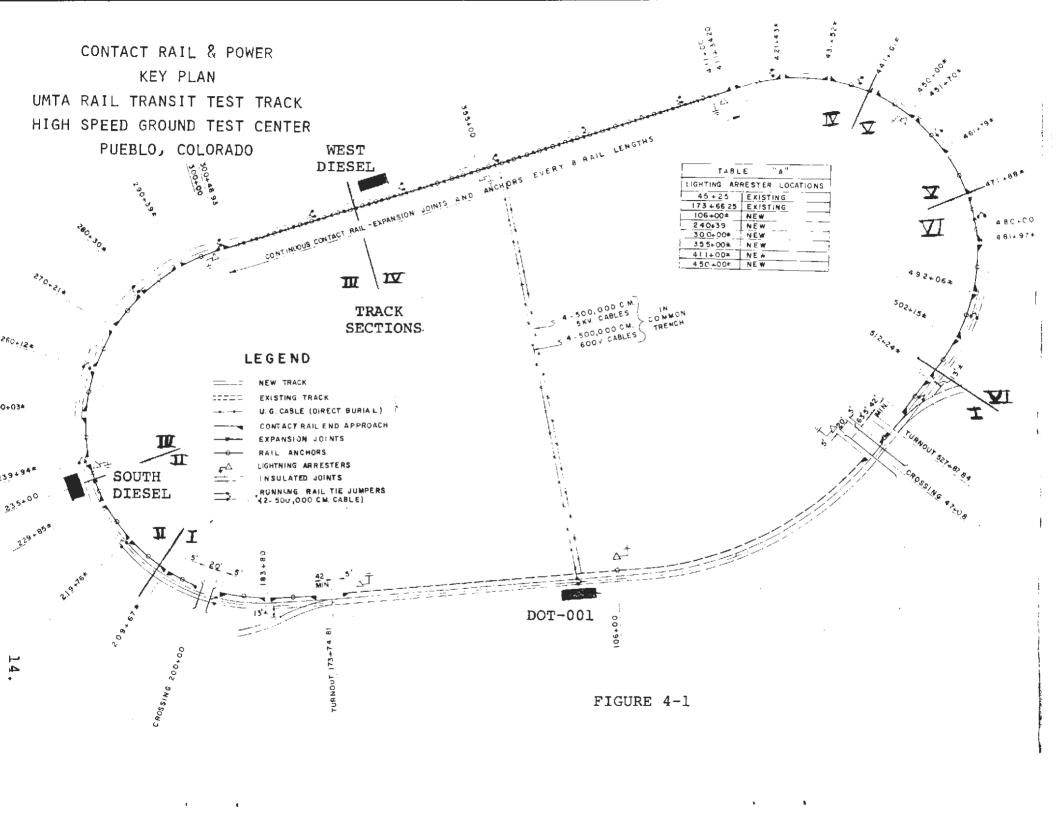
4.2 INSTRUMENTATION - PERFORMANCE TESTS

4.2.1 Static test and checkout equipment used to modify and adjust the propulsion, brake components and systems at the test facility were as follows:

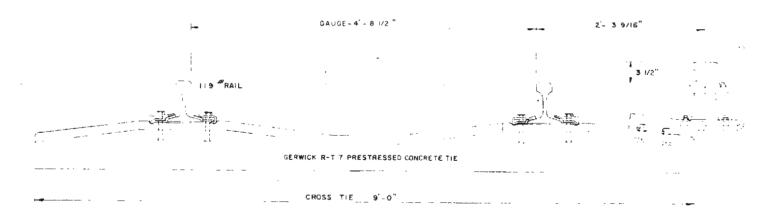
Equipment Manufacturer

Oscilloscope Simulator	Tektronix		
SOAC System Simulator	AiResearch	(Figure	4-3)
SOAC System Monitor	AiResearch	(Figure	4-4)

4.2.2 Carborne instrumentation used in the acceptance testing is outlined in the following paragraphs.



UMTA RAIL TRANSIT TEST TRACK HIGH SPEED GROUND TEST CENTER PUEBLO, COLORADO



CROSS SECTION OF TRACK ASSEMBLY SECTION IX, X & XI

FIGURE 4-2

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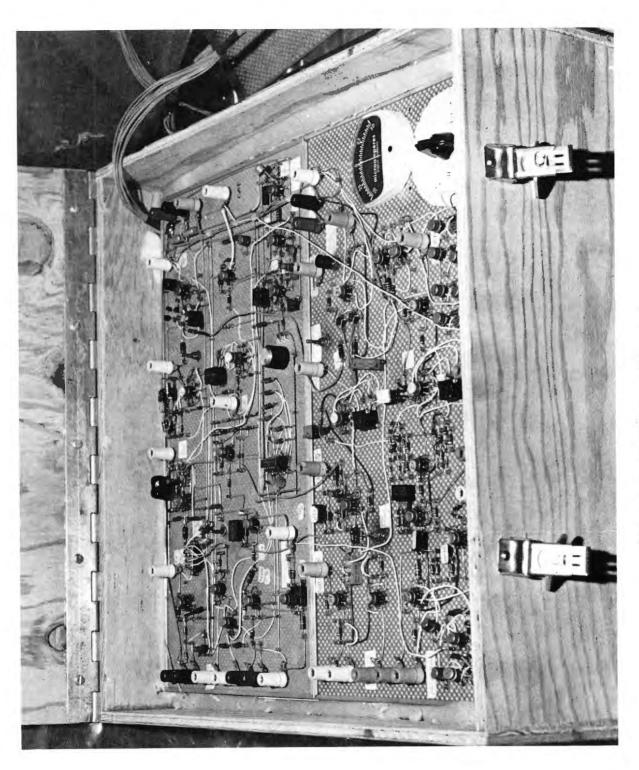


Figure 4-1. SOAC System Simulator

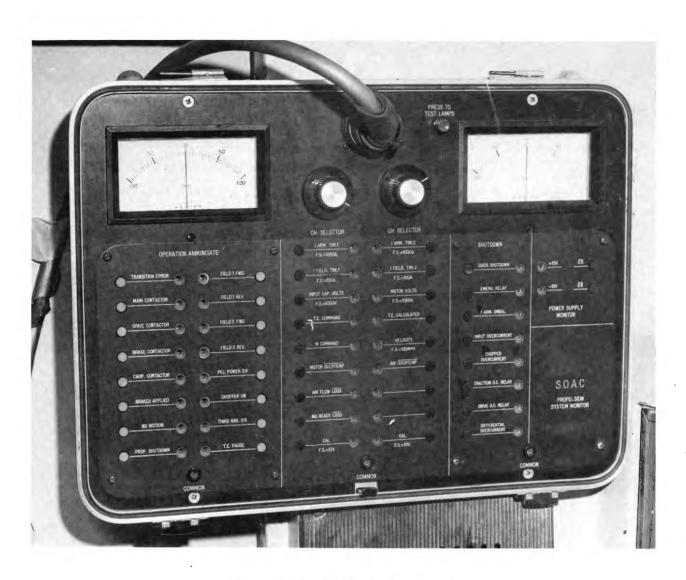


Figure 4—2. SOAC Monitor Panel

4.2.2.1 Garrett/SOAC Propulsion System Monitor Panel

This panel was temporarily mounted in the operator's cab of each car and was connected to the various low-voltage logic and feedback circuits contained in the SOAC propulsion control system.

The monitor panel performs several functions:

- o Annunciator lights for indication of propulsion and braking events and modes.
- o Fault indicator lights.
- o Calibrated meters for indication of the following:

Armature currents Field currents Capacitor bank voltage Motor voltage Car speed
Calculated tractive effort
Thyristor firing (0) command
Tractive effort command

Plus additional internal system functions.

o Terminals for connecting the above parameters with a recording oscillograph.

4.2.2.2 CEC Recording Oscillograph (5-124A)

This recorder uses direct print, light-sensitive paper and has a maximum of 18 channels of output. Nine channels were utilized for data during the SOAC testing. Several data channels were taken directly from the output of the monitor panel with scale factors derived from the calibrated meters on the panel. The following parameters were recorded.

- o P-signal
- o Armature current (forward and aft)
- o Field current
- o Capacitor bank voltage (third rail)
- o Longitudinal acceleration
- o Car speed
- o Analog brake current (BCP command signal)

4.2.2.3 Accelerometer and Signal Conditioning Units

The longitudinal accelerometer for performance data and its power and signal conditioning unit were supplied by AiResearch. The accelerometer was secured to a 47-lb. ballast bar and oriented longitudinally in the car interior over the forward truck.

4.2.2.4 The Garrett/SOAC monitor panels remained in their respective cabs during all tests. The CEC oscillograph and accelerometer/signal conditioner were moved from car to car for the various tests. Scale factors remained essentially constant throughout the testing.

4.2.2.5 Calibration

As previously noted, the two armature currents, field current and capacitor bank voltage were calibrated from the monitor panel meters (+5 percent accuracy). The longitudinal accelerometer was calibrated using a level surface and angular displacement equivalent to several "g" values. Car speed was calibrated during constant speed runs over a measured distance. Both cab indicator error and oscillograph calibrations were determined in this manner.

The tractive effort reference or "P" wire was calibrated directly off the cab "P" wire meter. Analog brake current (BCP command) was referenced to the cab BCP gauge and gauge installed on the rear truck. The event mark was used both as a baseline reference for trace deflection and as a track distance or event reference.

The oscillograph was operated during each test record with a paper speed sufficient to detail the specific car characteristic being tested. Generally, paper speeds of .25 and 1.0 inches per second were used. Timing lines printed on the paper during recording were calibrated against a stopwatch, using the event marker.

Time and distance data were obtained using stopwatches and actual ground distance measurements.

4.3 INSTRUMENTATION - RIDE QUALITY

(See Appendix III)

4.4 INSTRUMENTATION - NOISE MEASUREMENTS

(See Paragraph 6.10)

4.5 INSTRUMENTATION - EMI TESTS

(See Appendix IV)

5. TEST PROCEDURES

Test procedures used during the SOAC acceptance tests generally follow the procedures outlined in Section V.C. of the D174-10007-1 SOAC Test Document. They are summarized as follows:

5.1 ACCELERATION (Maximum)

- o Position car on one end of the 400 ft. level tangent track (station 298 + 00 59 338 + 00).
- o Put master controller handle in full power position while still in "deadman" position.
- o Start recorder.
- o Twist handle from "deadman" to operating condition.
- o Record data as required.
- o Maintain controller position until maximum speed of 80 mph is attained.

5.2 AUTOMATIC SPEED MAINTAINING SYSTEM (ASMS)

- o Select speed limit of 3 mph.
- o Put master controller handle in full power position while still in "deadman" position.
- o Start recorder.
- Twist handle from "deadman" to operating condition.

 Handle remains in full power position for remainder

 of ASMS Tests.
- o Record data as required.
- o Select additional speed limits in following sequence: 15, 25, 35, 50, 70, 80, 70, 50, 35, 25, 15, 3.
- o Maintain each above speed a sufficient time to record system speed accuracy.

5.3 BRAKING TESTS (Full Service Rates)

- o Approach braking course (station 298 + 00 to 338 + 00) with tractive effort handle in position to stabilize at test speed.
- Start recorder.
- o At the outer marker for the course release the handle to its "deadman" position for full service braking.
- o Bring car to complete "hands-off" stop.
- o Record time and distance to stop.

The above procedure is used for blended braking, dynamic braking only, and with slight modification for service friction braking only. For friction braking the dynamic brake must be cancelled by a switch (airflow "loss") for test purposes just prior to initiating braking.

5.4 BRAKING TESTS (Emergency)

o Procedure similar to paragraph 5.3 except at the outer marker for the course, activate the motorman's "Emergency Stop" pushbutton.

5.5 SERVICE DUTY CYCLES

The service duty cycles are repetitive driving cycles consisting of acceleration to 80 mph at maximum rate, immediate transition to full service braking followed by a 30-second station stop. The cycle is repeated 24 times with blended braking and 24 times with service friction braking only.

5.6 RIDE QUALITY

(See Appendix III)

- 5.7 NOISE TESTS INTERIOR
- 5.8 NOISE TESTS WAYSIDE

5.9 EMI TESTS

(See Appendix IV)

6. TEST RESULTS

6.1 VISUAL TESTS

The following visual and check tests were performed on each car prior to the start of the performance acceptance tests.

- 6.1.1 Place car on trucks over a pit which will allow safe access to undercar equipment. Set handbrake.
- 6.1.2 Remove motor cooling air exhaust covers, shipping covers, freight service adapters and coupler adapters.
- 6.1.3 Visually inspect for damage, loose parts or missing items.
- 6.1.4 Install traction motor brushes and disconnect traction motor flexible ducts. Tighten all drain plugs, drain cocks and inspection covers.
- 6.1.5 Turn on "BATT", "CAB LIT", "MAIN LT", "RADIO" circuit breakers on LVCBP and HVCBP. Observe that lighting and radio function.
- 6.1.6 Provide 600 VDC. Turn on one at a time the following, and check for function and unusual noise or vibration.

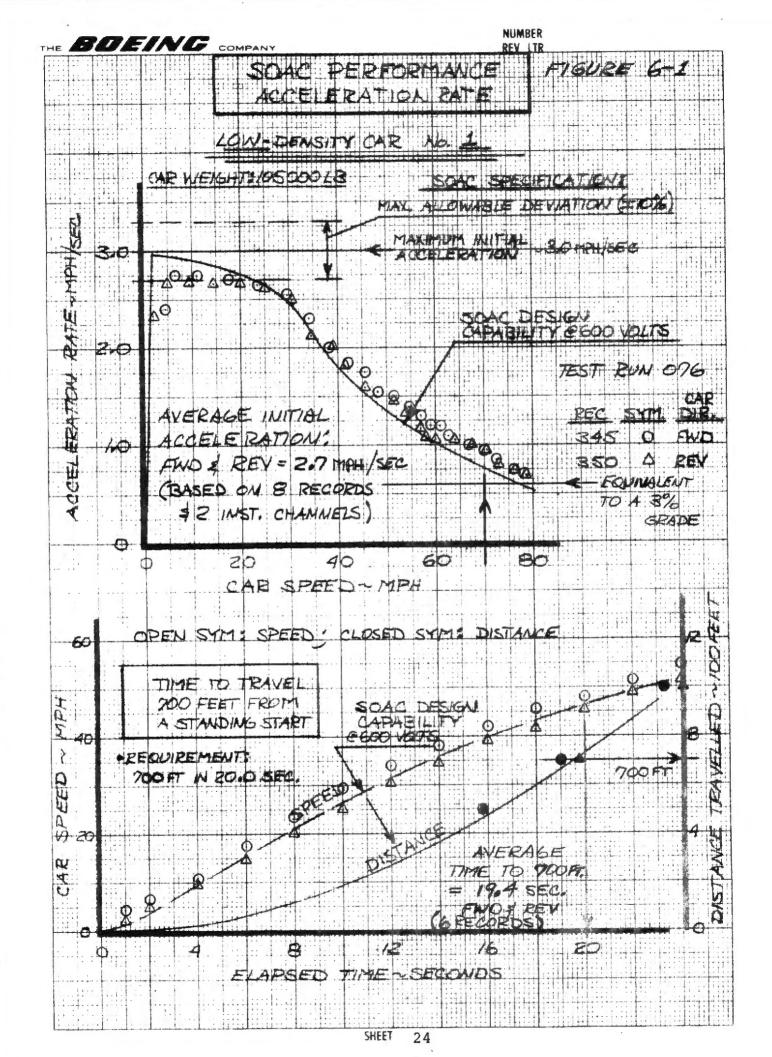
Alternator field
Motor alternator field
Dynamic brake
Battery charger
Traction motor cooling #1
Traction motor cooling #2
Air brake
Brake compressor

- 6.1.7 Turn on motor alternator and traction cooling blowers and allow to run for 15 minutes (or until traction cooling ducts are free of debris).
- 6.1.8 Disable third rail power and reconnect motor flexible ducts.
- 6.1.9 Restore third rail power and turn on all circuit breakers and observe the following:
 - o Motor alternator running
 - o Traction motor cooling blowers running
 - o Air compressor running
 - o All lights on
 - o Headlights and taillights function
 - o Side doors function
 - o Main reservoir pressure 150 psi
 - o Air conditioning blower running

- o Windshield wiper, washer and defroster function
- o Horn blows
- o Emergency valve functions
- o Track trip functions
- o Trainline functions for cars coupled
- o Hostling mode operation
- o Pantograph extension and retraction
- o End door operation
- 6.1.10 Set tread brakes (58-64 psi control pressure, 90,000-1b. and 91-97 psi control pressure, 132,000 lb. car).
- 6.1.11 Turn on instruments and release handbrake.
- 6.1.12 Rolling Checkout Tests
- 6.1.12.1 Put direction control switch in FORWARD.
- 6.1.12.2 Move controller to 1/4 power position. Accelerate to 10 mph; monitor motor current. Stop the test if motor current exceeds 500-amp peak.
- 6.1.12.3 Brake car by moving controller to 1/4 brake position. Motor current should not exceed 250 amps.
- 6.1.13 Performance Setup Tests
- 6.1.13.1 Accelerate car in full power position to 20 mph. Monitor motor current and acceleration rate. Stop test if:
 - o Motor current exceeds 1700 amps.
 - o Acceleration rate exceeds 3.0 mphps.
 - o Peak acceleration rate is less than 2.5 mphps.
 - o Any circuit breaker trips.
 - o Wheels slide.
- 6.1.13.2 Brake car in full service position. Stop test if:
 - o Motor current exceeds 1900 amps.
 - o Motor current is zero.
 - o Wheels slide; circuit test only.
 - o Deceleration rate exceeds 3.0 mphps.
 - o Deceleration rate is less than 2.0 mphps.
- 6.1.13.3 Repeat step 6.1.13 adjusting acceleration and deceleration rate to within 2.7 to 3.3 mphps peak values.

6.2 ACCELERATION

The acceleration performance and time to travel 700 feet from a standing start are shown on Figure 6-1 for the low-density car.



Acceleration testing was completed on the 4000-ft. section of level tangent track with a maximum speed of 79 mph reached at the end of the section. During the test, third rail voltage was a nominal 620 volts (±). Tests were made in the forward and reverse car direction for two runs to the 700-ft. point and one run to 80 mph in each direction. Figure 6-2 presents a complete time-and-distance-to-speed characteristics for the low-density car.

The initial SOAC design capability is shown on Figures 6-1 and 6-2 as a comparison to the test data. The acceleration capability of the car is equal to or better than the initial design capability above the motor base speed of approximately 30 mph. The reduced acceleration rate below 30 mph is based on the revised current limits selected to maintain the braking rate within allowable tolerances.

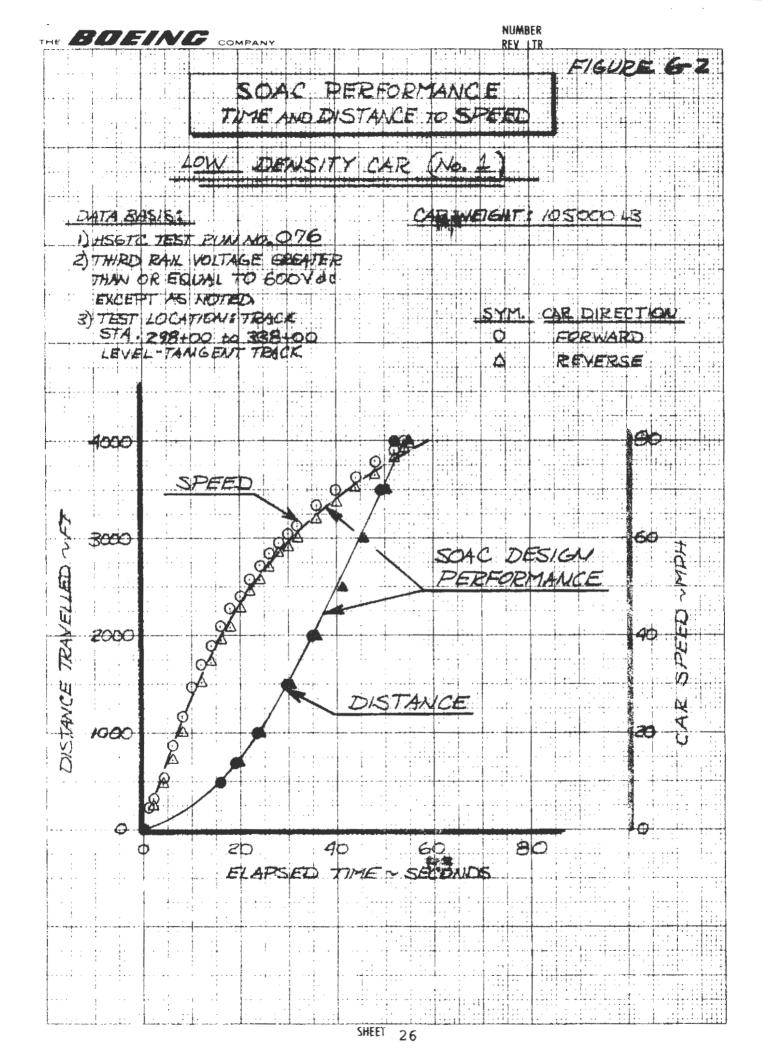
The acceleration performance of the high-density SOAC is presented in Figures 6-3 and 6-4 in formats similar to Figures 6-1 and 6-2 previously shown for the low-density SOAC. The performance is essentially similar to the low-density car. The initial SOAC design capability is shown on Figures 6-3 and 6-4 for comparison.

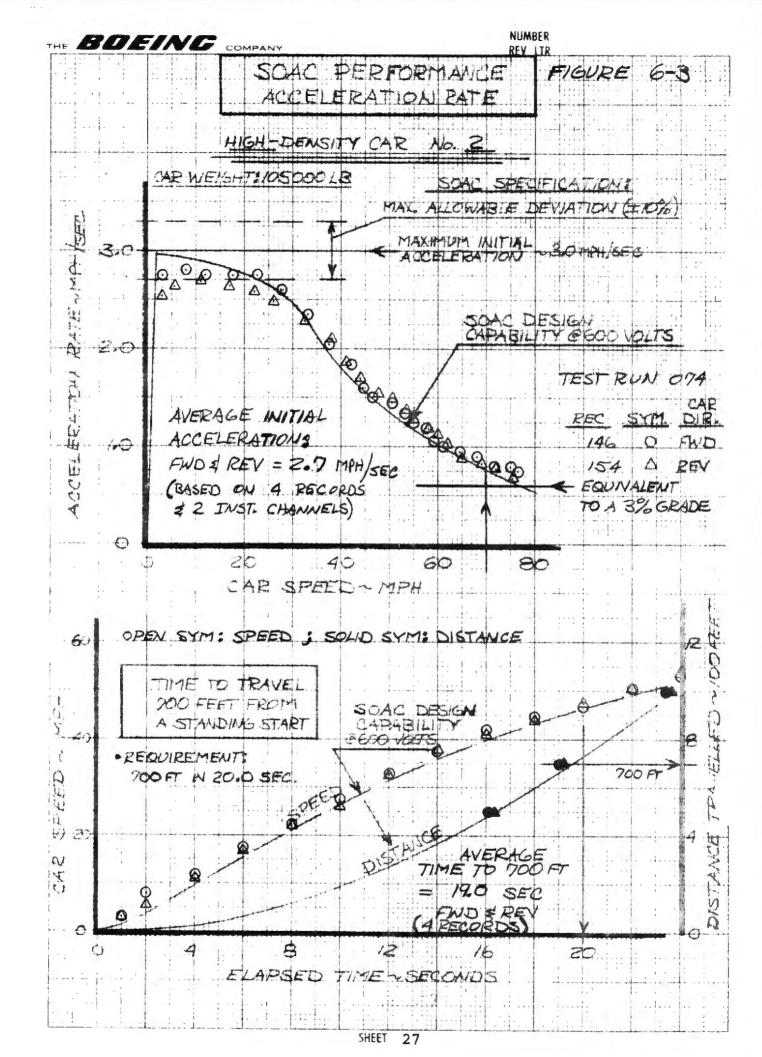
Two-car train acceleration testing was performed to determine the peak initial rate and the time to 700 ft. distance. The large power demand of the two cars (3000-3200 amps) resulted in a large track voltage drop from the nominal 600-650 volts. Test run voltages of 500-550 volts were experienced which resulted in a reduced performance level above about 30 mph. Because of this fact the performance curves for the two-car train are not included in this report. The data of Table II verify that the initial acceleration rate and time to 700 ft. are within specifications and that the two-car train performance is similar to each car operated separately.

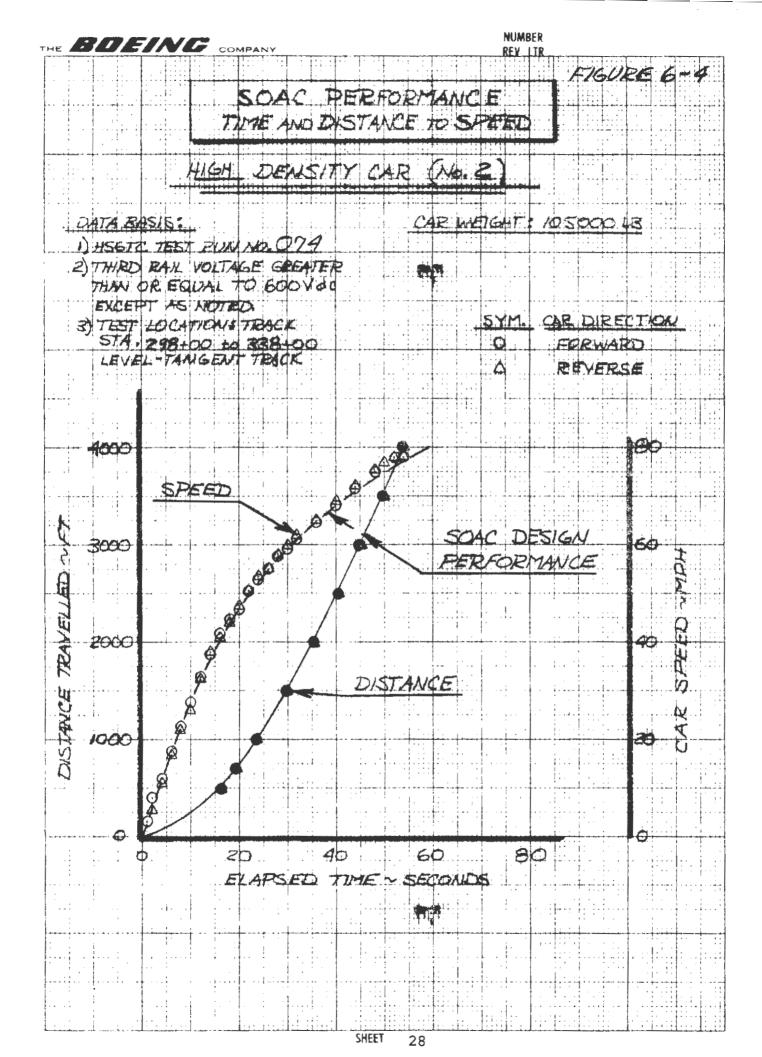
6.3 MAXIMUM SPEED AND ASMS

The service maximum speed of the cars is 80 mph based on the test data of Figures 6-1 and 6-3, an acceleration rate of approximately .65 mphps is available at 80 mph. Both cars have exceeded 90 mph in a two-car consist during controlled test conditions.

The Automatic Speed Maintaining System (ASMS) provides the capability to control and limit car speed to the 80 mph maximum or additional speeds of 3, 15, 25, 35, 50, or 70 mph. This system was tested using the procedures contained in paragraph 5.2. With the control handle in the full power position the car will accelerate to the selected speed at the maximum acceleration rate for the car's weight. (Rates for a 105,000-lb. car are shown in Figures 6-1 and 6-3.







As the selected speed is approached within 2 to 3 mph the tractive effort reference signal ("P" signal) is automatically reduced until the desired speed is maintained to within +1 mph. The P signal is then adjusted automatically to regulate the tractive (or brake) effort required to maintain the selected speed on various track grades or curves. The control handle may remain in the full power position at all times, or it may be set at a reduced level which results in at least the P signal required to produce the "balancing" tractive effort. The P signal meter in the cab reads the P value associated with the ASMS and not the actual control handle position. The band for speed regulation enlarges as the controller is decreased from the P = 1.0 amp position: +1 mph at P = 1.0 to approximately -2 to -3 mph at "balancing" P value.

The ASMS pushbuttons may also be used to decrease speed from a previously selected value. With the control handle still in the full power position, activating a command for a lower speed will automatically aupply full service blended braking until the car speed has been reduced to the selected value. Speed regulation about the new value is again +1 mph.

A speedometer calibration curve for the low density car is shown in Figure 6-5. The actual speed was determined over a timed, measured course on level tangent track.

The ASMS on the high-density car performs similarly to that on the low-density car as previously stated. The complete range of tests noted for the low-density car were conducted on the high-density car; speed regulation was again within +1 mph of selected speed with the tractive effort handle in the full power position. A speedometer calibration for the high-density car is shown in Figure 6-6.

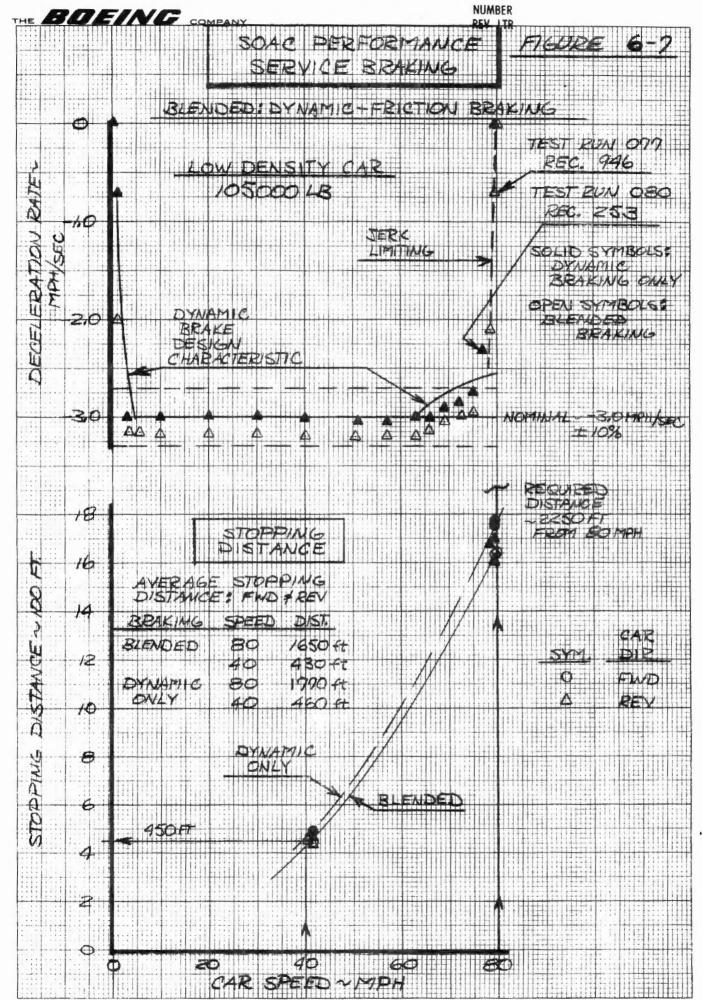
6.4 BLENDED AND DYNAMIC BRAKING

Figure 6-7 presents the blended service braking and dynamic braking (only) capability for the low-density car in terms of deceleration rate and stopping distance. The upper scale illustrates the blended and dynamic brake rates during two test records from 80 mph. The design characteristics of the dynamic brake system are shown on this upper scale in comparison to the test data.

The dynamic brake alone, without service friction braking, is capable of providing the SOAC's nominal deceleration rate of 3 mphps (±10%) down to a speed of approximately 3 mph. The increased brake rate associated with the normal configuration of blended dynamic/friction braking is due to the inshot pressure of approximately 8 psi sent to the friction brake cylinders under all braking commands.

NUMBER BOEING COMPANY REV LTR osculograpa AAU/BEAVAWYZESO Hour Corner 20 4/4/23 60 CAB TODICATED 50 40 30 20 TRUE SPEED AMPH P. BRUEN SHEET 31

3/10/2



Stop distances from speeds of 40 mph and 80 mph are shown on the lower scale of Figure 6-7. Data was taken at the specification speeds of 40 and 80 mph for the final acceptance test. The shape of the stopping distance curves is based on additional preliminary data when the propulsion system was adjusted to a lower braking rate (armature current).

Figure 6-8 presents the results of the blended braking and dynamic braking (without friction brakes) tests, or the high-density cars; Figure 6-9 for the two-car train.

6.4.1 System Response Characteristics - Blended Braking

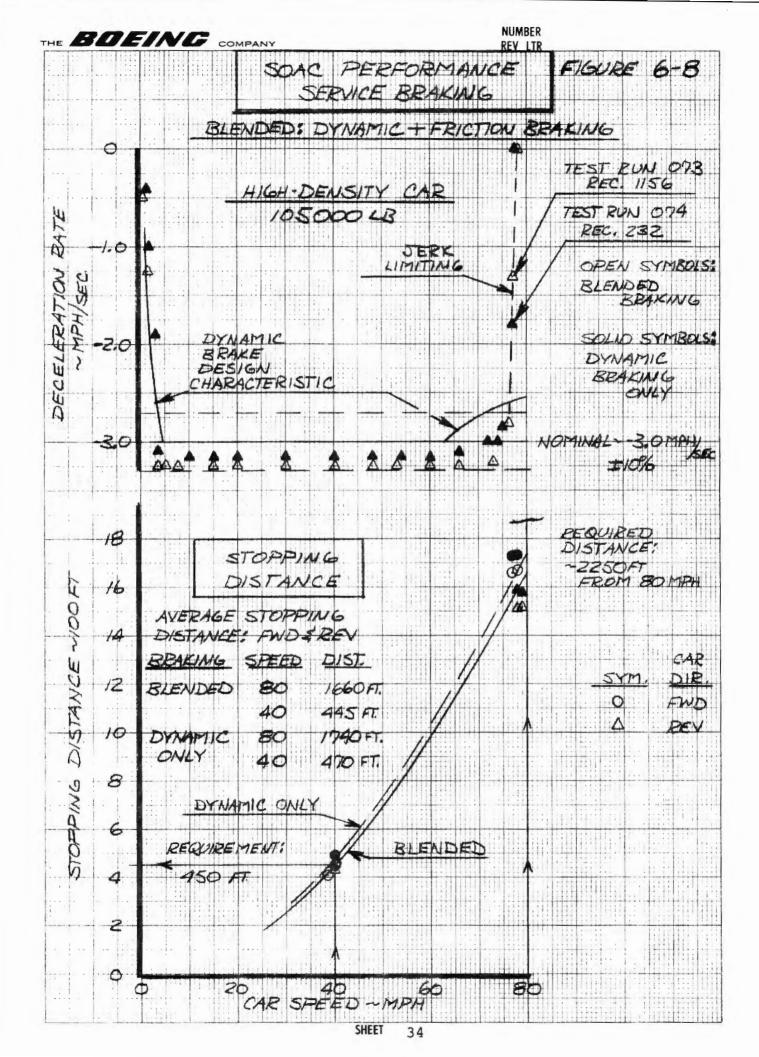
Figure 6-10 illustrates a typical transition from the propulsion mode to the blended braking mode at 40 mph car speed. At time t = 0, the master controller "deadman" handle is released, providing a step input to the traction system. In the next .5 second, the jerk rate limiting circuit removes the tractive effort at a rate of 425 amps per second until zero armature current is attained.

During the .7 second "control dead time" the field current is reduced to zero, the "drive" contactors open, the "brake" contactors close, and the motor field current is reversed in sense by the field control. After the "dead time", the jerk limit circuitry again limits the rate of change of (braking) current, the field current is ramped to maximum value, and the chopper controls the armature current to achieve the selected braking effort (deceleration rate). Full service rate is attained approximately 2.5 seconds after release of the "deadman". The stopping distances shown in the performance plots reflect the jerk rates and dead times as shown in Figure 6-10.

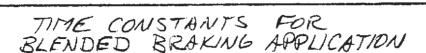
6.4.2 Dynamic Brake Failure Simulation

During the test program, but prior to the final adjustment of blended braking rates, several simulated dynamic brake failures during normal blended braking from 80 mph were completed. These tests were accomplished to determine the time and rate response of the friction brake backup system and the impact on stopping distance. These tests were performed on the high-density car and Figure 6-11 illustrates a time history of one simulated dynamic brake failure. Since this data was obtained during testing prior to the final adjustments of the dynamic brake current limits, the performance thus reflects slightly lower deceleration rates and slightly longer stopping distances than the data of Table II and Figure 6-8.

Two stops with simulated dynamic brake failures were accomplished; both stops within the 2250 ft. required distance from 80 mph. The following table outlines the test results.

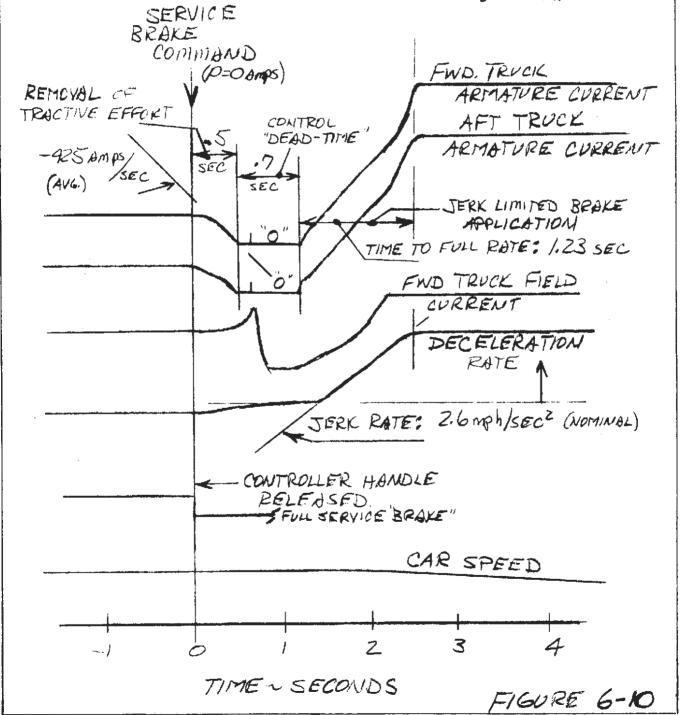


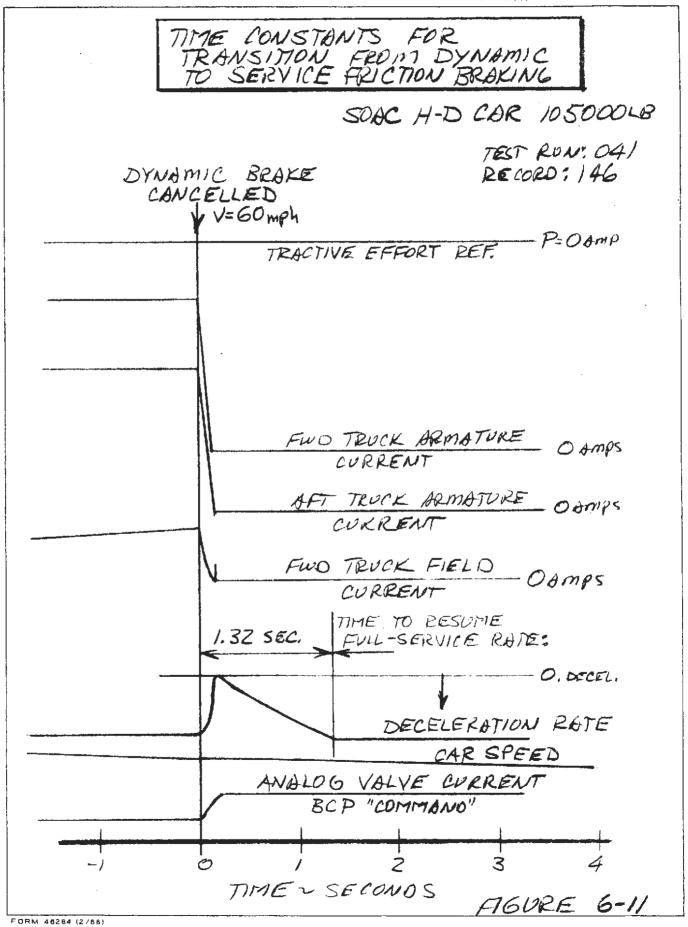
SHEET 35



SOUC TWO-CORTRAIN DOTA

TEST KUN: 078 RECORD: 1243 Vi: 40 MPH





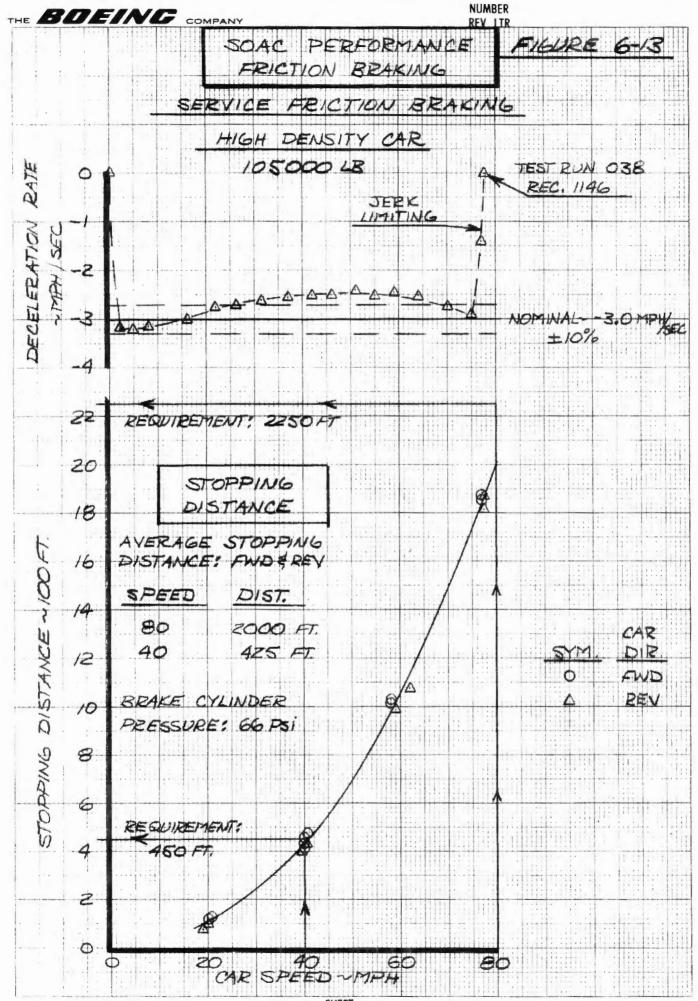
INITIAL						
SPEED	FAIL DYN	AMIC	TIME	TO	DISTAN	CE TO
(TRUE)	BRAKE @	SPEED	STOP)	STC	P
		FORWARD D	DIRECTI	ON		
76 mph	59 mph		29.0	sec.	1852	ft.
, ,	.					•*
76 mph	Blended	Svc.	29.3	sec.	1698	ft.
•						
REVERSE DIRECTION						
		AEVERSE I	DIVECTI	LOW		
77 mph	60 mph		28.8	sec.	1766	ft.
, , <u>r</u>						
77.5 mph	Blended	Svc.	29.2	sec.	1719	ft.
=						

In each of the above car directions, the stop with the simulated failure is compared with a similar stop with blended braking. As noted above, the stopping distance is increased by approximately 50 to 150 ft. from 76-77 mph. The reduced time-to-stop noted on the "failure" stops may be attributed to the different brake rate vs. speed characteristic between blended and friction brake systems (see Figures 6-8 and 6-12). Test procedure for the simulated dynamic brake failures was similar to the procedure used for friction braking (paragraph 5.3) except that the dynamic brake was cancelled at 60 mph instead of just prior to initiating braking at 80 mph. The stops were completed using service friction brakes only following the simulated dynamic brake failure at 60 mph.

6.5 SERVICE FRICTION BRAKING

The service friction brake capability (without dynamic brake) is shown in Figure 6-12 for the low-density car. Sample test data from a stop from 80 mph is shown on the upper scale and stopping distances from speeds of 20, 40, 60 and 80 mph are shown on the lower scale. Two stopping tests in each direction from each speed were used to determine the specification compliance at 40 and 80 mph and the general shape of the stopping distance curve. Brake cylinder pressure is set to 68 psi as measured on the cab pressure indicator. Figures 6-13 and 6-14 present similar data for the high-density car and the two-car train.

The deceleration rates shown on Table II are based on average over the speed range of all test points shown in Figures 6-12, 6-13 and 6-14. The deceleration rate for each stop was determined using both the accelerometer and by differentiating the calibrated speedometer channel on the oscillograph. A time period of 10 seconds or greater was used where possible to determine the average deceleration rate during a test record.



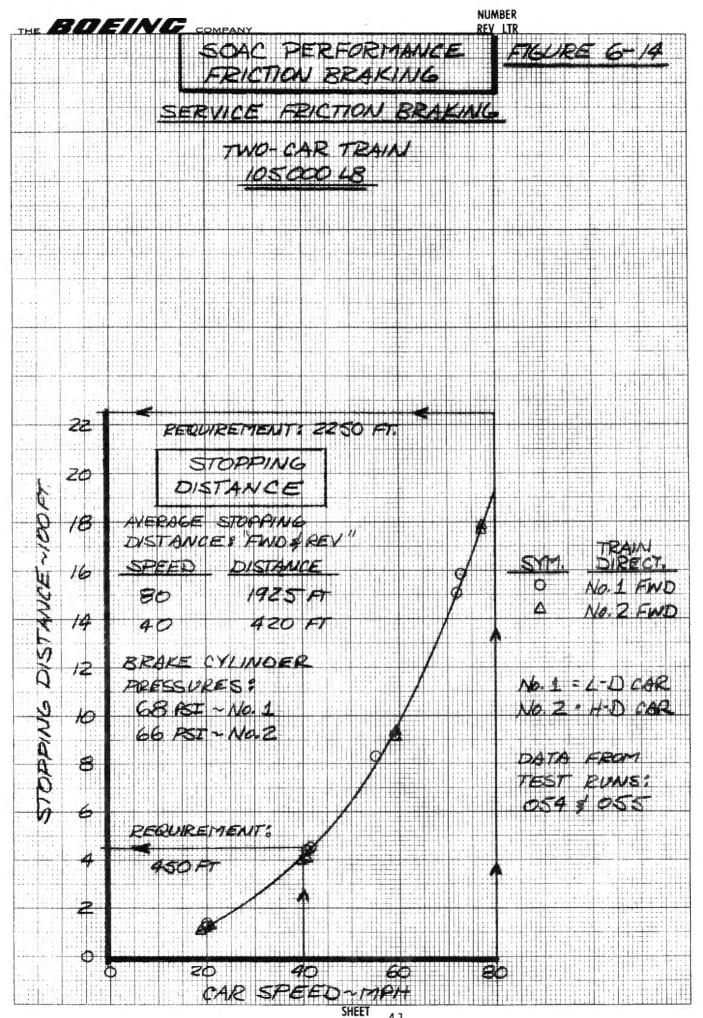


Figure 6-15 illustrates the time constants and jerk rates associated with application of full service friction braking using a step input command.

6.6 EMERGENCY FRICTION BRAKING

Figure 6-16 presents the results of brake on the low-density car tests using the emergency brake system which consists of friction brakes only. As before, the upper scale illustrates a typical test stop from 80 mph while the lower scale shows the resulting stopping distances for the 14 emergency stops performed during the tests. Emergency brake cylinder pressure is set at 78 psi for both cars.

Test results for the high-density car and the two-car train are shown in Figures 6-17 and 6-18 respectively. As with the service friction and blended braking data, the deceleration rate shown in Table II is an average of all runs shown in Figures 6-16, 6-17 and 6-18.

The time constants associated with an emergency brake application are shown in Figure 6-19. As noted, full brake pressure (and deceleration rate) are reached in seconds.

6.7 JERK RATE

The time rate of change of acceleration or deceleration while under control of the jerk rate limiting system was determined by evaluating the time-slope of the accelerometer channel on the oscillograph. Jerk rate measurements were made on all acceleration and service blended braking tests for both cars, and an average rate for each mode is shown on Table II. Illustrations of jerk rate limiting are shown in Figures 6-10 and 6-15 for the braking mode.

6.8 SERVICE DUTY CYCLE

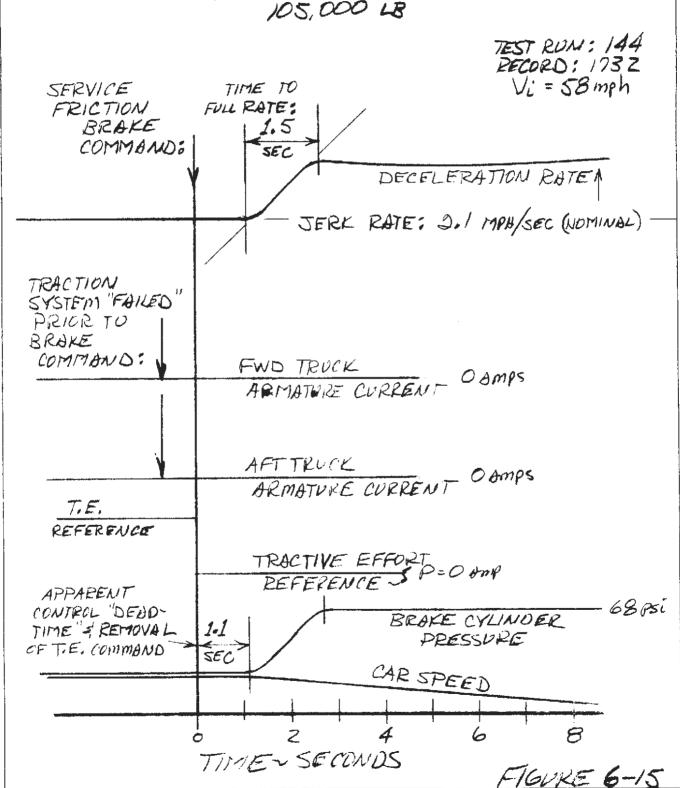
The SOAC traction system was designed for a duty cycle of repetitive 0 to 80 mph to 0 runs with a 30-second dwell time after each stop as shown in Figure 6-20. At the design weight of 105,000 lb. these repeated cycles resulted in an RMS armature current of 637 amps. The design continuous current is 460 amps; the one-hour current is 600 amps. Thus the duty cycle represents operation at a performance level somewhat above the one-hour rating of the traction motors, but well below the peak current rating of 750 amps.

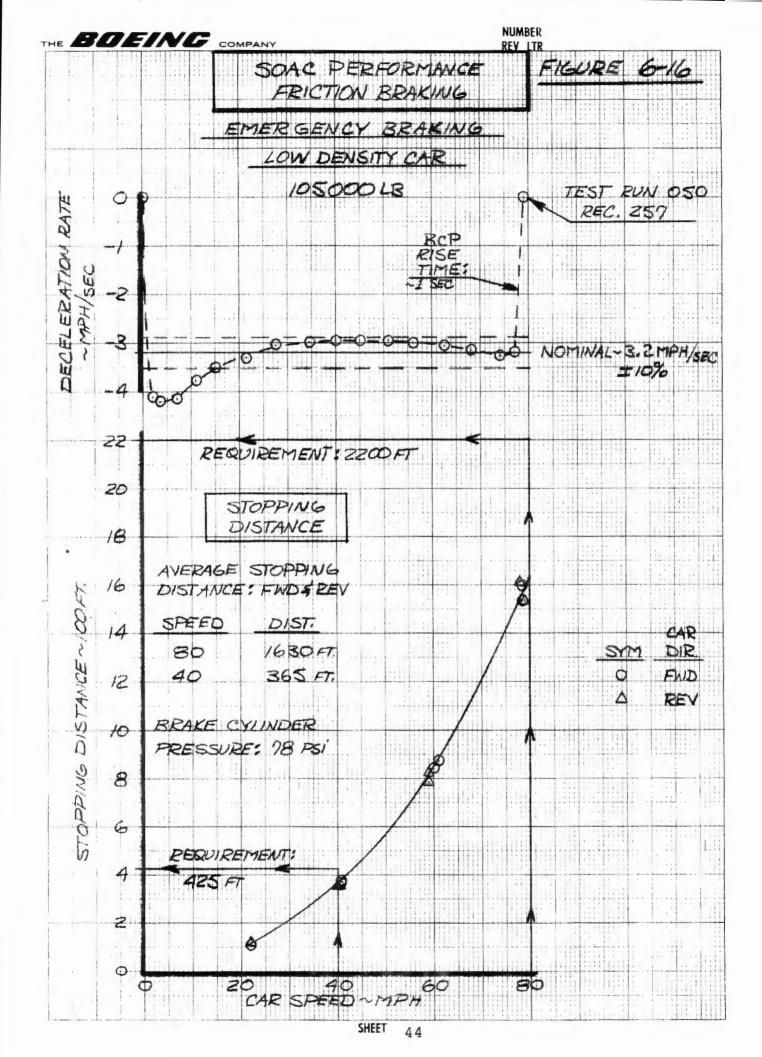
6.8.1 Blended Braking Cycles - Service Configuration

Table IV summarizes the results of the 24 cycles of blended braking performed on each car. A summary duty cycle plot is shown in Figure 6-21 based on measured car performance on level tangent track. The cycle of Figure 6-21 differs from Figure 6-20 due to the higher level of performance measured

TIME CONSTANTS FOR SERVICE FRICTION BRAKE APPLICATION

SOAC HIGH-DENSITY CAR 105,000 LB

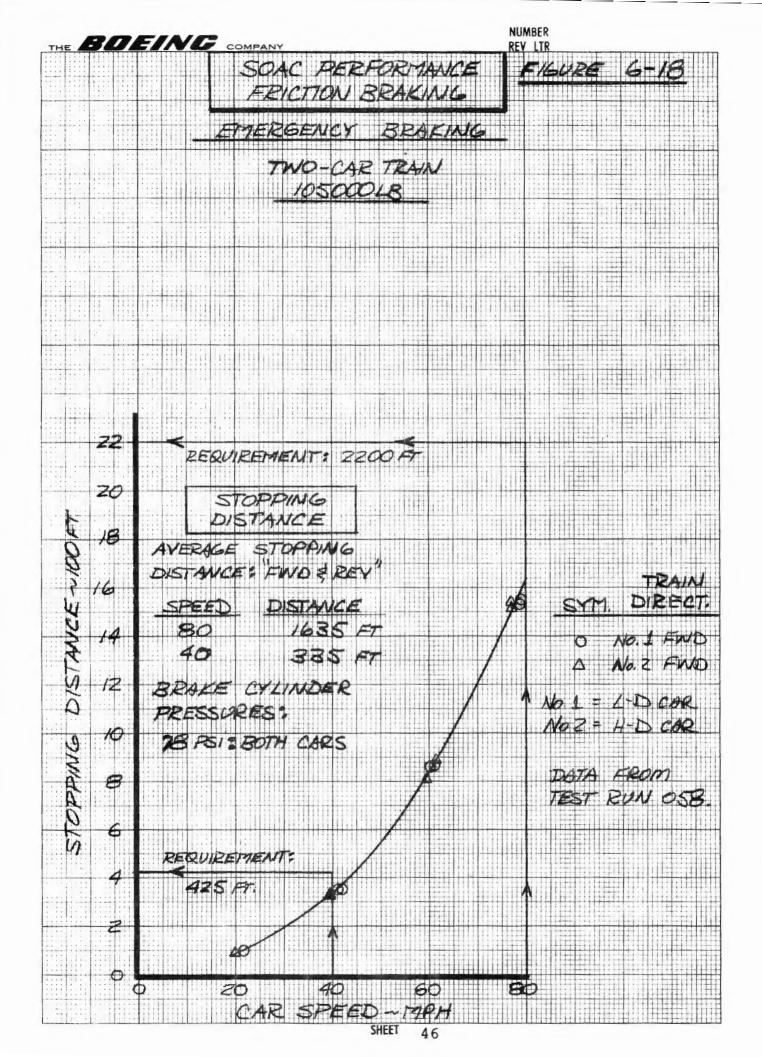




SHEET

45

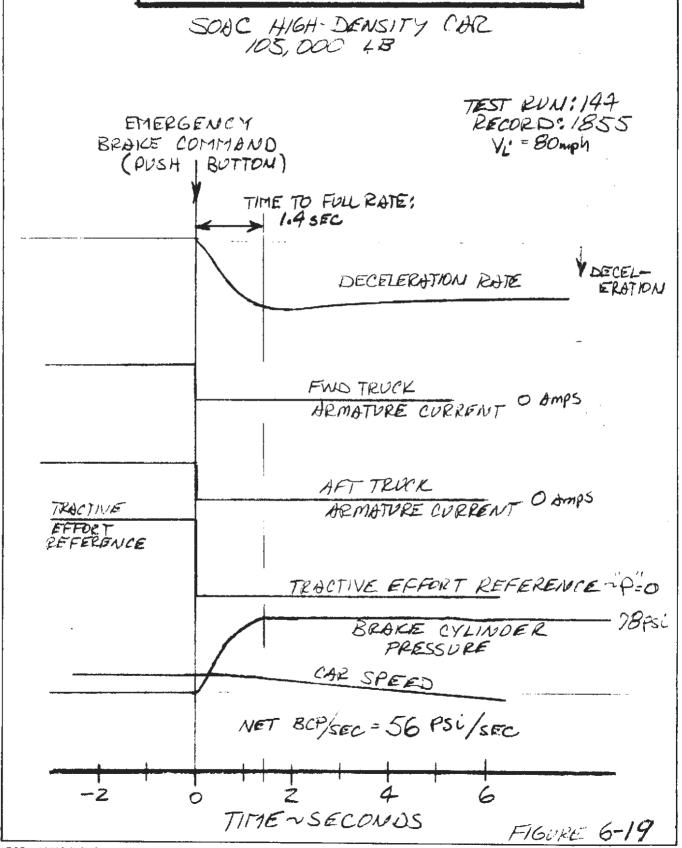
NUMBER



PREPARED BY: CHECKED BY: DATE:

NUMBER REV LTR MODEL NO.

TIME CONSTANTS FOR EMERGENCY BRAKE APPLICATION



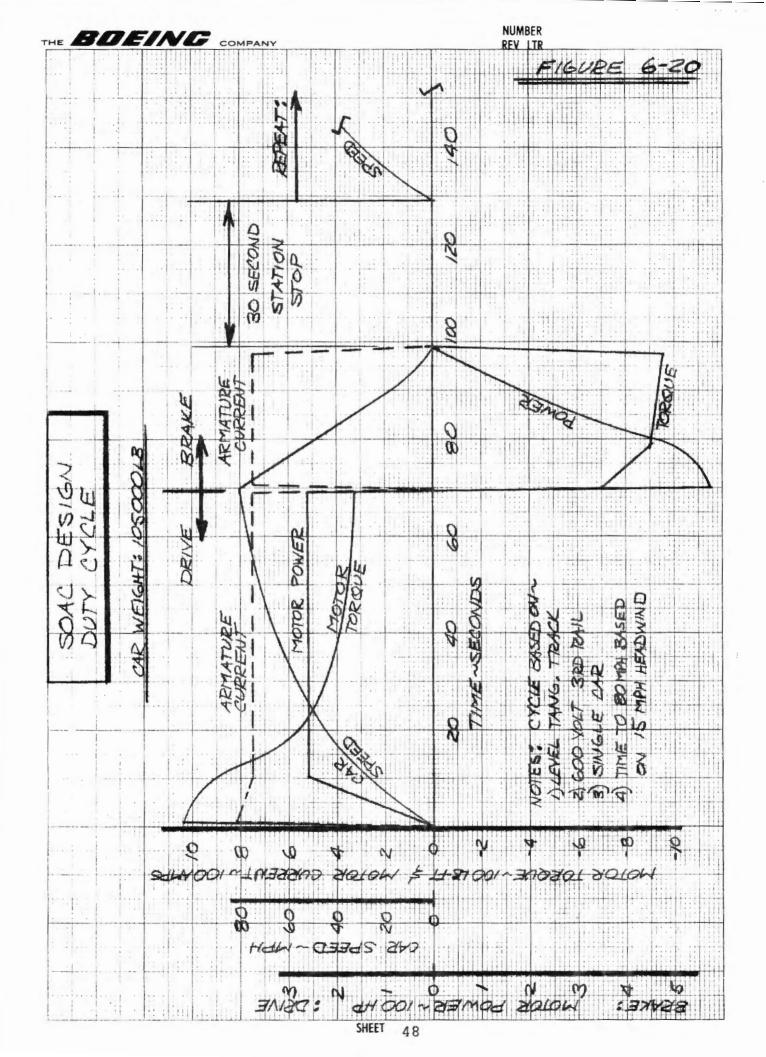


TABLE IV

SERVICE DUTY CYCLES - BLENDED BRAKING

I. LOW-DENSITY CAR

24 CYCLES (STOP TO 80 MPH TO STOP) WITH A 30-SECOND STOP TIME.

RESULTS: DISTANCE TRAVELED 28.9 MILES

TOTAL TIME 47.0 MINUTES

MILES PER CYCLE 1.2 MILES

MINUTES PER CYCLE 1.9 MINUTES

SCHEDULED SPEED 37.0 MPH

(RUN COUNTERCLOCKWISE ON TEST OVAL)

II. HIGH-DENSITY CAR

24 CYCLES (STOP TO 80 MPH TO STOP) WITH A 30-SECOND STOP TIME.

RESULTS: DISTANCE TRAVELED 26.0 MILES

TOTAL TIME 42.9 MINUTES

MILES PER CYCLES 1.08 MILES

MINUTES PER CYCLE 1.8 MINUTES

SCHEDULE SPEED 36.0 MPH

(RUN CLOCKWISE ON TEST OVAL)

ACCEPTANCE TEST

Car Weight: AWl = 105,000 Lbs.

NOTES

- Single car.
- 2. Level tangent track.
- 3. Zero wind.
- 4. Gear ratio: 4.78
- 5. Wheel Dia.: 30 in. (new)
- 6. Gear losses included.
- Data Basis: HSGTC Acceptance tests - 4/73.

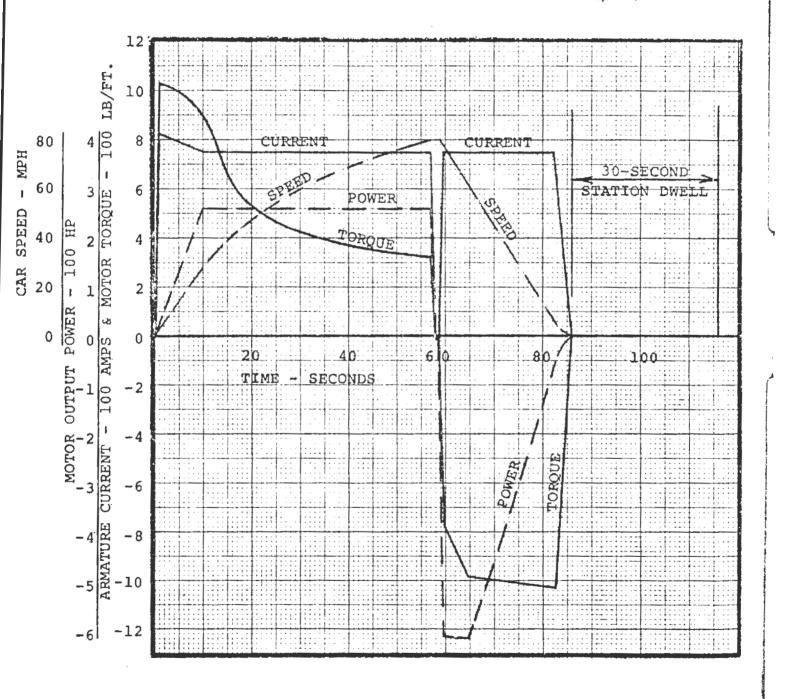


FIGURE 6-21

on the cars and the deletion of the 15 mph wind condition (not included in test data). The RMS armature current resulting from Figure 6-21 is 623 amps compared to 637 amps for Figure 6-20 and the 600 amp one-hour rating. No propulsion system problems were encountered during the duty cycle tests.

6.8.2 Service Friction Braking Cycles - No Dynamic Brake

Table V presents a summary of the 24 cycles of friction braking performed on each car following the tests of paragraph 6.8.1 The friction braking cycles were run to determine the effects of operating a car with the electric traction system cutout but with service friction brakes in operation. This condition simulates the worst case operation of a two-car train with one dead car (propulsion system).

Wheel tread temperatures were measured following several stops using an infrared pyrometer. The tabulated temperatures were recorded following the stop and thus do not represent a peak temperature. Stopping rates and distances measured at the end of the 24 cycles were within the specifications shown in Table II.

Brake pad smoking and some pad ignition were noted on the last four or five cycles. The stopping distance on the last stop with the low-density car was measured at 2010 ft. compared to an average 1960 ft. distance recorded earlier in the same car direction. The friction characteristics of the SOAC cobra composition brake show results in relatively consistent stopping performance throughout the temperature range generated by the severe duty cycles tested.

6.9 RIDE QUALITY

The results of the ride quality testing are summarized in paragraph 2.2 and detailed in the Appendix III report and the D174-10026-1 Engineering Test Report.

TABLE V

SERVICE DUTY CYCLES FRICTION BRAKING

I. Low-Density Car

-24 Cycles - (Stop to 80 mph to stop) with a 30 second stop time.

RESULTS:	Distance Travelled -	32.9	Miles
	Total Time -	58.0	Minutes
	Miles Per Cycle -	1.37	Miles
	Minutes Per Cycle -	2.4	Minutes
	Schedule Speed -	33.0	MPH
	Energy Per Stop -	22.4	Million FtLb.
	Maximum Tread Temp	320°	F
	Maximum Rim Temp	280°	F

(Run counter-clockwise on test oval)

II. High-Density Car

-24 Cycles - (Stop to 80 mph to stop) with a 30 second stop time.

RESULTS:	Distance Travelled -	27.4	Miles
	Total Time -	51.0	Minutes
	Miles Per Cycle -	1.14	Miles
	Minutes Per Cycle -	2.1	Minutes
	Scheduled Speed -	32.0	MPH
	Energy Per Stop -	22.4	Million FtLb.
	Maximum Tread Temp	250°	F
	Maximum Rim Temp	170°	F

(Run clockwise on test oval)

6.10 NOISE MEASUREMENTS

Noise level tests were completed on the two SOAC vehicles in November 1972. All measurements were made with a Bruel & Kjaer Precision Sound Level Meter Type 2203, using the I.E.C. "A" weighting network scales, with manual recording of meter readings.

For the interior noise tests, the vehicles were ballasted to 105,000 pounds and operated at a steady speed around the UMTA transit test track. No significant differences were noted for track construction types. Interior measurements were made at a standing and seated passenger ear level for three car locations: over the front truck, over the rear truck, and in the center of the car. Exterior noise measurements were made at a height of 3 ft. above the rail and 50 ft. from the car side.

Data for the low-density car, SOAC No. 1, was completed during Test Run 5 and is shown on Table VI. Data for the high-density car, SOAC No. 2 was completed during Test Run 10 and is shown on Table VII.

Wayside noise data is from Test Runs 87, 89 and 110, for Pueblo Track Sections I, III, IV, V and VI. The data of Figure 6-22 show compliance of the SOAC vehicles with the interior noise goal at all speeds, and the wayside goal at speeds above 35 to 40 mph. Also shown on Figure 6-22 is the band of wayside noise levels for contemporary transit cars for comparison to the SOAC goal and the test data. As noted on the figure, the wayside data for Section I is approximately 3 dBA higher than that for Sections III through VI. This lower level is used to show compliance above 35 to 40 mph and also as a favorable comparison with the lower level for existing cars. The wayside noise data was taken with "trued" solid steel wheels at a car weight of 90,000 lbs.

Figure 6-22 presents a summary of SOAC noise levels in comparison to the SOAC goals. As noted, the measured interior noise data band is significantly lower than the SOAC goal. Figure 6-22 also presents the results of the wayside noise tests conducted at the beginning of the Engineering Test Program. As noted, at zero car speed the wayside noise level of the traction motor cooling fans (2) and the self-ventilated motor alternator set are higher than the SOAC goal which was primarily based on wheel-rail noise. Analysis of equipment noise data is contained in the Engineering Test Report D174-10026-1, parts 10 and 11. As previously noted in the summary, the SOAC noise requirements were considered a goal rather than an acceptance criterion.

TABLE VI - INTERIOR NOISE LEVELS SOAC #1 LOW DENSITY CAR

'A' WEIGHTED SOUND LEVEL dB(A)

ALL EQUIPMENT OPERATING WT = 105 Klb.

Run #5 - 11/16/72

		FRONT OVER #1 Trk.	CENTER	REAR OVER #2 Trk.	
	ACCELERATION	63	62.5	65	(2)
SEATED	0	62	61	64.5	
(Ear	25	63	61	64	
Level)	35	63	61	65	
	50	65	63	67	
	70	72	65	70	
STANDING (Ear Level)	ACCELERATION	63	62.5	66	(2)
	0	62	62	65	
	25	63	61.5	64	
	35	63	62	65	
	50	65	63	67	
	70	72	65	70	

⁽¹⁾ Effect of track location not considered.

⁽²⁾ Acceleration noise levels are a function of speed.

TABLE VII - INTERIOR NOISE LEVELS SOAC #2 HIGH DENSITY CAR

'A' WEIGHTED SOUND LEVEL dB(A)

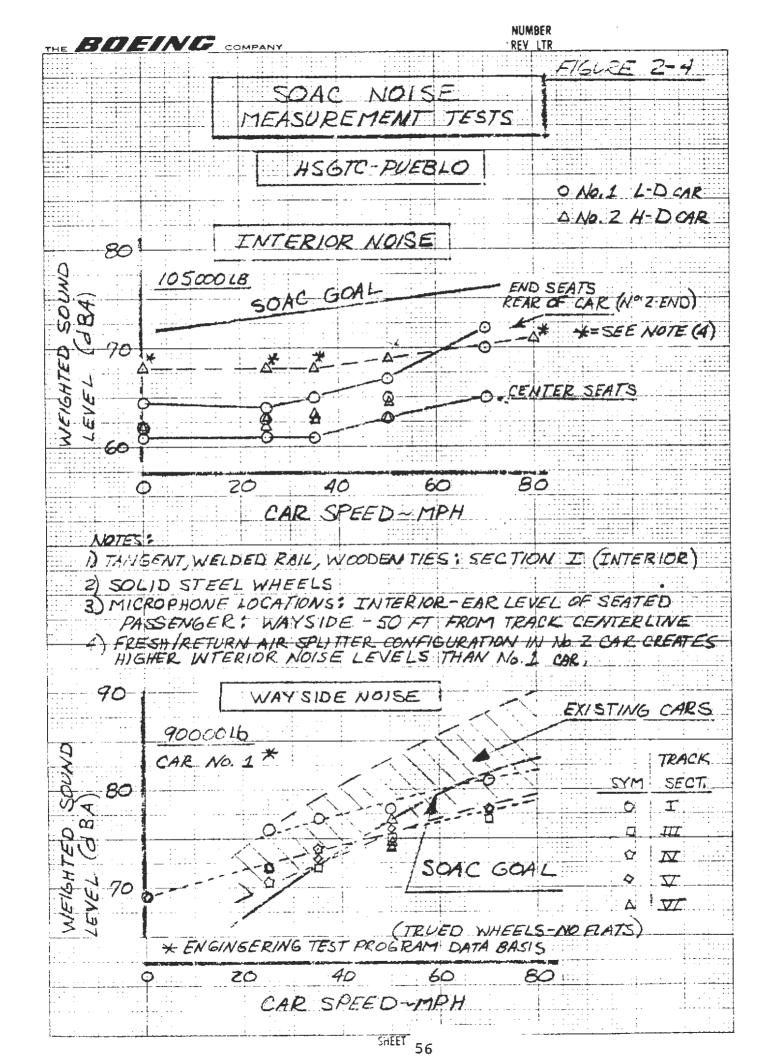
ALL EQUIPMENT OPERATING

WT = 105,000 Lb. Run #10 - 11/29/72

		FRONT	CENTER	REAR
		OVER #1 Trk.		OVER #2 Trk.
	ACCELERATION	(2)	(2)	(2)
SEATED	0	_	62	68
(Ear Level)	25	63	62	68
	35	63.5	63	68
	50	64.5	63	69
	80	-	-	71
STANDING (ear Level)	ACCELERATION	(2)	(2)	(2)
	0	-	62	64
	25	63	62	65
	35	63	63	67
	50	64	63	66
(1) 755	80			71

⁽¹⁾ Effect of track location not considered.

⁽²⁾ Acceleration Noise levels were determined to be a function of speed.



6.11 ELECTROMAGNETIC INTERFERENCE

Results of the EMI testing are summarized in paragraph 2.4 and detailed in the Appendix IV EMI Test Report.

7. CONCLUSIONS

7.1 PERFORMANCE

The SOAC cars, individually and as a two-car train, met all specification performance goals for acceleration and braking. Test results are summarized in Table II, page

7.2 RIDE QUALITY

Initial ride quality acceptance testing confirmed an observed mild vibration near 64 MPH and a severe vibration near 80 MPH. Car body vertical accelerometer wave forms indicated that the severe vibration near 80 MPH was caused by a high amplitude vibration with a 9 second beat at the center of the car. Subsequent diagnostic tests and analyses (Appendix III) led to a structural beef-up of the motor alternator support structure.

The modification to the motor alternator support structure eliminated the vibration near 64 MPH and the beating phenomenon near 80 MPH. Data taken at the light car weight (90,000 lbs.) show maximum vibration levels at the higher frequencies (15 Hz) reduced from .26 g's to .1 g. Although this exceeds the design goal of .055 g's at this frequency, this is probably the result of manual reduction of the 90,000 lb. data as explained in Appendix III, Section 2.4 Data taken at the Normal Load Car Weight (100 passengers - 105,000 lbs.) using the Engineering Test instrumentation system meet or better the design goals for all frequencies at both mid and aft car centerlines.

7.3 NOISE DATA

Interior noise level measurements show that both cars meet the interior noise level goals at all speeds.

The SOAC also meets the wayside noise goal at speeds above 35 to 40 mph and is comparable to the quietest of existing transit cars. Below 35 mph the SOAC noise level exceeds the design goal. This is attributable to the noise generated by the undercar equipment in comparison to a noise goal based mainly on wheel-rail noise. The magnitude of the equipment noise level is illustrated by a 69 dBA level measured at zero car speed.

7.4 ELECTRO MAGNETIC INTERFERENCE (EMI)

The wayside and interior test data results plotted as a composite graph in Figure 2-5 demonstrate compliance with the specified limits of Section 9.9.2 (Figure 9-2) of the SOAC Detail Specification. Appendix IV presents the EMI test report and the recorded data.

APPENDIX I
TEST RUN LOG

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	DATE	RUN No.	PURPOSE - CONFIGURATION	ODOMETER READING
	11-14-72	001	105,000 LB CARS: TWO CAR TRAIN NO. 1 (L-D) CAR UNDER POWER: NO. 2 (H-D) NO POWER	
	11-14-72	002	105,000 LB CARS: TWO CAR TRAIN - VIP RUN NO. 1 POWER: NO. 2 NO POWER	
	11-15-72	003	105,000 LB CAR: NO. 2 CAR ONLY SPEEDOMETER CALIBRATION	
Į.	11-15-72	004	105,000 LB CAR: NO. 2 CAR ONLY BRAKING TESTS	
	11-16-72	005	105,000 LB CAR: NO. 1 CAR ONLY: ACCEL. & DECEL. & NOISE TESTS: MOTOR FLASH-OVER EVALUATION (#2 CAR PDR)	
	11-16-72	006	105,000 LB CARS: TWO CAR TRAIN - VIP RUN NO. 1 POWER: NO. 2 NO POWER	
	11-17-72	007	105,000 LB CAR: NO. 1 CAR ONLY: MOTOR EVAL. AT HIGH SPEED: SET-UP THIRD RAIL SHOES	<u> </u>
	11-25-72	008	105,000 LB CAR: NO. 2 CAR ONLY: THEN 2 CAR TRAIN: RUN-IN BRUSHES (LOST THIRD RAIL SHOE-ADJUSTED) CHECK TRAIN	
	11-26-72	009	105,000 LB CARS: TWO CAR TRAIN: NO. 1 CAR DRIVING, (FAILED PDR) THEN NO. 2 CAR DRIVING-VIP RUNS	
	11-29-72	010	105,000 LB CARS: TWO CAR TRAIN THEN NO. 2 CAR ONLY: VIP RUNS: SPEED LIMITING, RIDE QUALITY, NOISE TESTS	

NO. 1 CAR (LOW DENSITY): NO. 2 CAR (HIGH DENSITY)

	DATE	RUN No.	PURPOSE - CONFIGURATION	ODOMETER READING
	11-30-72	011	105,000 LB CAR: NO. 2 CAR ONLY: RIDE QUALITY AND NOISE TESTS	
	12-1-72	012	105,000 LB CAR: NO. 2 CAR ONLY: BRAKING PERFORMANCE	
	2-8-73	013	105,000 LB CAR: NO. 2 CAR ONLY: INSTRUMENTATION CHECK OUT: MOTOR FLASH-OVER INVESTIGATION	
7	2-9-73	014	105,000 LB CAR: NO. 2 CAR ONLY: FLASH-OVER INVESTIGATION	
٥	2-12-73	015	105,000 LB CAR: NO. 1 CAR ONLY: EVALUATE INSTALLATION OF NEW MOTORS	
	2-13-73	016	105,000 LB CAR: NO. 1 CAR ONLY: EVALUATE MOTORS AND MOTOR INSTABILITY	
	2-13-73	017	105,000 LB CAR: NO. 1 CAR ONLY: INVESTIGATE MOTOR INSTABILITY	
	2-14-73	018	105,000 LB CAR: NO. 1 CAR ONLY: MOTOR INSTABILITY TESTING, EVALUATE SPEED LIMITING	
	2-20-73	019	105,000 LB CAR: NO. 1 CAR ONLY: VARIOUS SYSTEM CHECKS AND BRUSH RUN-IN	
	2-21-73	020	105,000 LB CAR: NO. I CAR ONLY: VARIOUS SYSTEM CHECKS	

NO. 1 CAR (LOW DENSITY): NO. 2 CAR (HIGH DENSITY)

PURPOSE - CONFIGURATION

ODOMETER

READING

	2-21-73	021	105,000 LB CAR: NO. 1 CAR ONLY: SPIN-SLIDE SYSTEM CHECKS: PRELIMINARY BRAKE TESTS	
	2-22-73	022	105,000 LB CAR: NO. 1 CAR ONLY: MAX. ACCELERATION CAPABILITY CHECKS	
	2-22-73	023	105,000 LB CAR: NO. 1 CAR ONLY: MAX. ACCELERATION CAPABILITY CHECKS	
н	2-26-73	024	105,000 LB CAR: NO. 1 CAR ONLY: RUN-IN NEW SET OF BRUSHES, MONITOR MOTOR VIBRATION	
- 3	2-27-73	025	105,000 LB CAR: NO. 1 CAR ONLY: ACCEPTANCE TESTING- BLENDED BRAKING (INCOMPLETE)	
	2-28-73	026	105,000 LB CAR: NO. 2 CAR ONLY: RUN-IN NEW SET OF BRUSHES: MANY PROPULSION TRIPS: CHOPPER PROBLEM	
	2-28-73	027	105,000 LB CAR: NO. 1 CAR ONLY: BRAKING TESTS, FRICTION, BLENDED, DYNAMIC: SPIN-SLIDE PROBLEMS	
	3-1-73	028	105,000 LB CAR: NO. 1 CAR ONLY: MOTOR VIBRATION TESTS: FRICTION BRAKING: SPIN-SLIDE PROBLEMS	
				_

105,000 LB CAR: NO. 2 CAR ONLY: CONTROLS PROGRAM CHECK-OUT: LURCHING AT BASE SPEED AND LOW CURRENT

105,000 LB CAR: NO. 2 CAR ONLY: BRUSH RUN-IN PROGRAM: ACCEL. & DECEL. TESTS: SPIN-SLIDE IS OK

NO. 1 CAR (LOW DENSITY): NO. 2 CAR (HIGH DENSITY)

DATE

3 - 1 - 73

3-2-73

RUN No.

029

030

DATE	TE RUN No. PURPOSE - CONFIGURATION					
3-2-73	031	105,000 LB CAR: NO. 1 CAR ONLY: CHECK CAR FOR CHOPPER LURCH PROBLEM (RUN 029): NOT FOUND				
3-5-73	032	105,000 LB CAR: NO. 2 CAR ONLY: BRUSH RUN-IN: FULL SERVICE BLENDED BRAKE TESTS: SEEMS OK				
3-6-73	033	105,000 LB CAR: NO. 1 CAR ONLY: TROUBLESHOOT SPIN-SLIDE SYSTEM: INDICATES SLIDES ABOVE 50 MPH				
3-6-73	034	105,000 LB CARS: TWO CAR TRAIN: CHECK-OUT TRAINLINES: DRIVE FROM NO. 2: MANY PROPULSION TRIPS				
3-7-73	035	105,000 LB CARS: TWO CAR TRAIN: CHECK TRAINLINES, C/S RELAY PROBLEM, CHOPPER LURCHES AT V BASE, CURRENT UN- BALANCE TRIPS IN NO. 1 DRAGGED NO. 1 HANDBRAKE				
3-8-73	036	105,000 LB CARS: TWO CAR TRAIN: SPEED CALIB. E&I CHECK WITH LOCO, HOSTLER OPS, COUPLE/UNCOUPLE, CURRENT UN- BALANCE TRIPS IN BRAKING (WET RAILS)	~2241 /			
3-9-73	037	105,000 LB CAR: NO. 2 CAR ONLY: BL END ED BRAKING ACCEL. TESTS (0 TO 700 FT.)				
3-10-73	038	105,000 LB CAR: NO. 2 CAR ONLY: BLENDED BRAKING, FRICTION BRAKING, SPEEDOMETER CALIBRATION	2345			
3-10-73	039	105,000 LB CAR: NO. 2 CAR ONLY: BRAKING TESTS, FRICTION AND DYNAMIC ONLY	1			
3-12-73	. 040	105,000 LB CAR: NO. 2 CAR ONLY: ASMS TESTING IN DRIVE AND BRAKE: ACCEL. TESTS (0 TO 700 FT.)				

NO. 1 CAR (LOW DENSITY): NO. 2 CAR (HIGH DENSITY)

DATE	RUN No.	PURPOSE - CONFIGURATION	ODOMETER READING
3-12-73	041	105,000 LB CAR: NO. 2: DYNAMIC BRAKE "FAILURES" FROM 80 MPH - EMERGENCY BRAKING	
3-13-73	042	130,000 LB CAR: NO. 2: CHECK-OUT OF 130K LB. VMAX = 50 MPH WET RAIL S/SLIDES, INITIAL ACCEL. (CHECK AND SERVICE BRAKE FROM 40 MPH	
3-14-73	043	105,000 LB CAR: NO. 1: CHECK-OUT PROPULSION SYSTEM MODIFICATIONS - INOPERATIVE FIELD PDR AT END, REDUCED DEAD TIME TO .7 SEC.	
3-14-73	044	105,000 LB CAR: NO. 1: CHECK-OUT NEW PDR FIELD SUPPLY: CHECK NEW SLIP/SLIDE SETTING (UNSTABLE FIELD SUPP.)	
3-15-73	045	105,000 LB CAR: NO. 1: SPEED-CALIB: TRAIL RUNS FOR BLENDED BRAKING, INITIAL ACCEL. MANY SLIP/SLIDES	
3-15-73	046	105,000 LB CAR: NO. I: CHECK-OUT SLIP/SLIDE PROBLEMS BY INTERCHANGING CARDS IN PCU - FOUND NOISY S/S CARD: BLENDED BRAKE	
3-16-73	047	105,000 LB CAR: NO. 1: DYNAMIC BRAKE ONLY TESTS: FRICTION BRAKING: BCP TOO HIGH - S/SLIDES	
3-16-73	048	105,000 LB CAR: NO. 1: INITIAL ACCEL. & TIME TO 700 FT. AT 600 VOLT LINE FRICTION AND EMERGENCY BRAKING AT VARIOUS BCP SETTINGS	
3 - 17-73	049	105,000 LB CAR: NO. 1: FRICTION BRAKING WITH REVISED BCP'S SIMILAR TO NO. 2 CAR: ASMS TESTS	
3-17-73	050	105,000 LB CAR: NO. 1: EMERGENCY BRAKING: CHECK OUT NEW PDR: BLENDED BRAKING CHECKS: INITIAL ACCEL.	

I-5

DATE	RUN No.	PURPOSE - CONFIGURATION	ODOMETER READING
3-19-73	051	105,000 LB CAR: NO. 2: CHECK-OUT PROPULSION MODS: CHECK LOW I, BASE-SPEED CHOPPER LURCHING: CHECK EMERG. BCP	
3-19 - 73	052	105,000 LB CAR: NO. 2: INITIAL ACCEL. TIME TO 700 FT. 0-VMAX: BRAKING-EMERGENCY AND BLENDED, SPEED CALIBRATION	
3-20-73	053	105,000 LB CAR: TWO CAR TRAIN: CHECKED OUT 2-CAR TRAIN CONFIGURATION COMPATIBILITY, CHECKED ACCEL. & BRAKE FUNC-TION - OPER. FROM #1 & 2 CAB, LOCO OFF LINE,	
3-20-73	054	105,000 LB CAR: TWO CAR TRAIN: RUN FROM #1 CAB - BRAKE TESTS BLENDED, FRICTION AND EMERGENCY - NO 80 MPH DATA: WEST DIESEL ONLY. RUN FROM #2 CAB-BRAKE TESTS -BLENDED 80MP	Н
3-21-73	055	105,000 LB CAR: TWO CAR TRAIN: BRAKE TESTS FROM BOTH DIRECTIONS, COMPLETED BLENDED AND FRICTION	
3-21-73	056	105,000 LB CAR: TWO CAR TRAIN: BLENDED, FRICTION & DYN. BRAKING FOR BOTH DIRECTIONS - ONE ACCELERATION RUN	
3-22-73	057	105,000 LB CAR: TWO CAR TRAIN: ASMS RUNS AND RIDE QUALITY TESTS FOR GSI	
3-22-73	058	105,000 LB CAR: TWO CAR TRAIN: TWO CAR EMERGENCY BRAKE TESTS & TWO ACCEL. RUNS-COMPLETED RIDE QUALITY RUNS FOR GS	I
3-26-73	059	105,000 LB CAR: TWO CAR TRAIN: CHECK-OUT OF CHOPPER MOD. & PDR STABILITY CHECKS	
3-26-73	060	105,000 LB CAR: TWO CAR TRAIN: CONTINUED CHECK OUT OF CHOPPER FIXES & INITIAL BUMP (LURCH) ELIMINATION	

9

DATE	RUN No. PURPOSE - CONFIGURATION			
3 -28- 73	061	105,000 LB CAR: NO. 1 CAR: ARMATURE CURRENT CHECKS ON FWD & AFT TRUCKS IN BOTH DIRECTIONS & BRAKE GRID TEMP.DATA		
3-28-73	062	105,000 LB CAR: NO. 2 CAR: ARMATURE CURRENT CHECKS ON FWD & AFT TRUCKS IN BOTH DIRECTIONS & RIDE QUALITY TESTS FOR GSI WITH 3" SHIMS REMOVED FROM TRUCKS		
3 - 29-73	063	105,000 LB CAR: NO. 2 CAR: STARTING LURCH CHECK AND ADDITIONAL RIDE QUALITY DATA FOR GSI	3100	
3-29-73	064	105,000 LB CAR: NO. 2 CAR: CONTINUED RIDE QUALITY TEST- ING FOR GSI WITH 3" SHIMS REMOVED		
3-31-73	3-31-73 065 105,000 LB CAR: NO. 1 CAR: MEASURED FWD TRUCK ARM CURRENTS FOR ACCELERATION FIX 4-3-73 066 105,000 LB CAR: TWO CAR TRAIN: EMI TESTS AND ARMA			
4-3-73				
4-2-73	067	105,000 LB CAR: TWO CAR TRAIN: MEASURED ARMATURE CURRENTS ON ALL TRUCKS WITH SHUNT- CONTINUED EMI TESTS		
4-3-73	068	105,000 LB CAR: TWO CAR TRAIN: EMI TESTS COMPLETED /		
4-4-73	105,000 LB CAR: NO. 2 CAR: CHECKED OUT INCREASE CHOPPE 4-73 069 CURRENT LIMIT PROBLEMS WITH PROPULSION TRIPS - DIFFERENTIAL CURRENT TRIP LIGHT		3401	
4-4-73	070	105,000 LB CAR: NO. 2 CAR: CONTINUED CHECK OUT WITH DIFF. CURRENT RELAY DISABLED AND RUN ACCEL. & BRAKE CHECK		

<u>___/</u>

DATE	RUN No.	PURPOSE - CONFIGURATION	ODOMETER READING
4-6-73	071	105,000 LB CAR: NO. 2 CAR: SHUNT ON FWD TRUCK: CURRENT SENSOR CHECKS	
4-6-73	072	105,000 LB CAR: NO. 2 CAR: SHUNT ON AFT TRUCK: CURRENT SENSOR CHECKS	
4-9-73	073	105,000 LB CAR: NO. 2 CAR: SHUNT ON AFT: THEN FWD TRUCK CURRENTS OK: BLENDED BRAKING: INITIAL ACCEL. RATES	
4-9-73	074	105,000 LB CAR: NO. 2 CAR: SHUNTS OFF: INITIAL ACCEL'S & TIME TO 700 FT: 0-80 MPH (3) DIESELS ON-LINE: DYNAM. BRAKING: DUTY CYCLE	
4-10-73	075	105,000 LB CAR: NO. 1 CAR: CURRENT CALIBRATION CHECK S/ SLIDE: LURCHING AT 20 MPH: TROUBLESHOOT PROP. TRIPS	
4-10-73	076	105,000 LB CAR: NO. 1 CAR: CURRENT CALIBRATION AND TROUBLESHOOTING	
4-11-73	077	105,000 LB CAR: NO. 1 CAR: BLENDED BRAKING TESTS	
4-11-73	078	105,000 LB CAR: TWO CAR TRAIN: ACCEL. & BLENDED BRAKING TESTS	
4-11-73	079	105,000 LB CAR: NO. 1 CAR: DYNAMIC BRAKING; SERVICE DUTY CYCLE	
4-12-73	080	105,000 LB CAR: NO. 1 CAR: DYNAMIC BRAKING, BLENDED/ FRICTION DYNAMIC BRAKING ONLY	

DATE	TE RUN No. PURPOSE - CONFIGURATION		ODOMETER READING
4-16-73	081	90,000 LB CAR: TWO CAR TRAIN: MINOR TRAIN CHECKS: PANTOGRAPH OPERATION	
4-16-73	082	90,000 LB CAR: TWO CAR TRAIN: PANTOGRAPH CHECKS RADIO AND P-WIRE CHECKS	
4-17-73	083	90,000 LB CAR: TWO CAR TRAIN: LT. WT. DEMO RUN AND CHECK OUT	
4-17-73	084	90,000 LB CAR: TWO CAR TRAIN: DEMO. TO TRANSIT AUTHORITY PERSONNEL: ACCEPTANCE DEMO.	
4-17-73	085	90,000 LB CAR: TWO CAR TRAIN: DEMO. TO TRANSIT AUTHORITY SPECIAL RUNS & TRANSIT DRIVERS	
4-19-73	086	90,000 LB CAR: TWO CAR TRAIN: VOLTAGE MEASUREMENTS (ENGINEERING TEST PROGRAM: ETP)	
4-24-73	087	90,000 LB CAR: CAR NO. 1: NOISE TESTING SINGLE CAR INTERNAL-WAYSIDE (ETP) (ACCEPTANCE)	
4-24-73	088	90,000 LB CAR: NO. 2 CAR: NOISE TESTING SINGLE CAR INTERIOR-WAYSIDE (ETP)	
4-26-73	089	90,000 LB CAR: CAR. NO. 1: NOISE TESTING - STRUCTURAL INTERNAL-WAYSIDE (ETP)	
4-26-73	090	90,000 LB CAR: NO. 1 & NO. 2 CARS: VIBRATION ACCEPTANCE ONE CAR DEAD - INSTR. NO. 2 CAR (ETP)	

I-9

DATE	RUN No.	PURPOSE - CONFIGURATION	ODOMETER READING
4-27-73	091	90,000 LB CAR: TWO CAR TRAIN: VIBRATION INVESTIGATION - VERT. DAMPERS REMOVED (ACCEPTANCE)	
4-27-73	092	90,000 LB CAR: TWO CAR TRAIN: VIBRATION INVESTIGATION - WITH AND WITHOUT SHIMS (ACCEPTANCE)	
5-18-74	110	90,000 LB CAR: NO. 1 CAR ONLY: (WAYSIDE NOISE TEST (ETP AND ACCEPTANCE)	
		90,000 LB CAR: NO. 2 CAR ONLY: CAR CHECK OUT AND RIDE	
7-5-73	129	QUALITY TESTS (GSI)	
7-5-73	130	90,000 LB CAR: NO. 2 CAR ONLY: CAR CHECK OUT AND RIDE QUALITY TESTS (GSI)	5996
		• .	
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I-10

APPENDIX II

TEST RUN SHEETS

Section 1: Performance Tests

Section 2: Ride Quality Tests

Section 3: Noise Measurement Tests

Section 4: EMI Tests

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SECTION 1: PERFORMANCE TESTS

SOAC ACCEPTANCE TESTS

PERFORMANCE

LOW DENSITY CAR (No. 1)

	CAR	TEST		
PERFORMANCE	DIRECTION	RUN	RECORD NUMBERS	NOTES
Acceleration:	Forward	076	345; 353; 421	Also:
& 700 ft.	Reverse	076	350; 356; 422; 437; 443	Jerk
T & D to 80 mph		07 6	345	rates
	Reverse	07 6	350	
V max.	Forward	076 &		Also:
	Reverse	others		ASMS
Braking:				Jerk Rate
Blended:	Forward	076	40 mph → 404; 458	"
	Reverse	076	40 mph> 415; 453	71
	Forward	077	80 mph → 920; 928	
	Reverse	077	80 mph → 940; 946	
Dynamic	Forward	080	231 thru 247) 253 thru 307) 40 & 80 mph	
only	Revers e	080	253 thru 307) 40 & 60 mpn	
Service	Forward	049	1059 thru 1125	rı
Friction	Reverse	049	1134 thru 1201	"
Emergency	Forward	050	235 thru 315	
Braking	Reverse	050	320 thru 341	
Duty	Forward	080	311 thru 358 (Blended)	
Cycles			411 thru 509 (Friction)	
,			,	
			II-1	
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SOAC ACCEPTANCE TESTS PERFORMANCE

HIGH DENSITY CAR (No. 2)

PERFORMANCE	DIRECTION	TEST RUN	RECORD NUMBERS	NOTES
FLKI OKMANOL	DIRECTION	KON	· · · · · · · · · · · · · · · · · · ·	110120
Acceleration	Forward	074	146; 200	Also:
& 700 Ft.	Reverse	074	154; 202	Jerk
T & D to 80 mph	Forward	074	146	Rates
n 0 11 0 11 0	Reverse	074	154	11
V Max.	F & R	074	Various Runs	Also: ASMS
Braking:				Jerk Rate
Blended:	Forward	073	1116 thru 1145	∫ H
Brended.	Reverse	073	1156 thru 1211	11
Dynamic	Forward	074	213 thru 228	
only:	Reverse	074	232 thru 246	
Service	Forward	039	159 thru 254	
Friction:	Reverse	038	1116 thru 1154	
Emergency	Forward	052	346 thru 407	
Braking:	Reve rs e	052	318 thru 340	
Duty	Forward	074	252 thru 336 (Blended)	
Cycles:			346 thru 437 (Friction)	
			II-2	•

SOAC ACCEPTANCE TESTS

PERFORMANCE

TWO-CAR TRAIN (No. 1 & 2)

TWO-CAI	R TRAIN (No.	1 & 2)	- Forward = #1 Forward; Reverse =	= #2 Forward
PERFORMANCE	CAR DIRECTION	TEST RUN	RECORD NUMBERS	NOTES
Acceleration: & 700 Ft. T & D to 80 mph	Forward Reverse Forward Reverse	078 078 078 078	1123; 1131 1209; 1215 1123 (less than 600 volts) 1209	Also: Jerk Rate
V Max.	F & R	078	Various	
Braking: Blended:	Forward Reverse	078 078	1141 thru 1157 1229 thru 1246	11
Dynamic only:	Forward Reverse	078 078	115 thru 132 1254 thru 108	
Service Friction:	Forward Reverse	054 055	330 thru 430 1043 thru 1118	II .
Emergency Braking:	Forward Reverse	058 058	312 thru 350 223 thru 302	
Duty Cycles:		Not done	(Low track voltage with 2-car train.)	
,			II-3	

SOAC ACCEPTANCE TESTS

RIDE QUALITY, NOISE, EMI

			LBS.
TEST TYPE	CAR NO.	TEST RUNS	CAR WEIGHT
			<u> </u>
RIDE QUALITY	2 (H-D)	10, 11	105,000
(Section 2)	1&2 Train	57, 58	105,000
(50552511 2)	2 (H-D)	62, 63, 64	105,000
	1&2 Train	90, 91, 92	90,000
	2 (H-D)	129, 130	90,000
	2 (11 5)	123, 130	307000
NOISE MEASUREMENT			
Interior/Wayside	1 (L-D)	005	105,000
Interior/Wayside	2 (H-D)	010	105,000
	2 (H-D)	087, 089	90,000
(Section 3)	2 (H-D)	110	90,000
(bección 3)	2 (11 5)	110	30,000
EMI TESTS	1&2 Train	66, 67, 68	105,000
	Toz Ilain	00, 07, 00	103,000
(Section 4)			

SECTION 1. PERFORMANCE TESTS

SCIECTEST RUM 038
1.ATE: 3/10/73 TIME: 51/15 1215
EXERCISE STREET BRAKING CEN FRICTION BICAKING COW
WEATHER CONDITION:
WIND SPEED 5-15 BAROMETRIC AMBIENT AIR START 46 PRESSURE TEMPERATURE STOP
CREN: TEST CONTROLLER R. PARKER
OPERATIONS DIRECTOR ROPEN MOTORMAN BILL CURRAN DATA CONTROLLER P. BROWN GROUND CONTROLLER DUE HOSKILL INSTRUMENTATION REAR MONITOR GREY DAILS:
ADDITIONAL PERSONNEL
VEHICLE CONFIGURATION:
CAR 1 (AR 2) 105000 48 ±.5%

THE FOLLOWING PAGES CONTAIN THE METHOD. GUICK-LOOK INDICATORS. TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

FRICTION BRAILING

SOAC #2

COUNTER CLOCKWISE

Rus Osiz

INITAL SPEED (ASITE)	TIME SEC	TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD OR NUMBER TIME OF DAY	DERK BATE SEC
Actua Tuok T= 20 19		6.3	78	/1/6 ///3 BAO SPOT	
20. 21		610	100	1121	
40 42		13	431	1124	
40 37		12.2	398 BAD SPOT. 5 /5	1132	
60 64	,	22.2	1079	//36	
60 61		21.	987	1141	
80 79		31.5	/873	1146	
80 79)	30,5	1819	1154	

320

319 90 7 316

327 zi

PERONN

SOAC BRAKING

the SE NO.

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TYPE: HI-DEN

ACCEPTANCE TEST DATA

			TY	PES	HI-D	EN		,00							= 63	T. CB	2W7	= 10	5000	LG
	' '		DIRE , 101	v	SPI	AVG TRUE PSC	DA T _{ME}	TA Ps _T	TIME	PATE	DEC	E	DEC	社。	इश्ह	D_	ARM CURI FLO TRX Smp	ant Aft	JEST JEST NO VI	ACCE!
					mph	mph	SEC	Q.	SEC	mory a	;				700	SEC	<u>Smp</u>	Amp	\$5€ C	TIME
0	37	444	FWD	cw	28	76	29,3	1698	1.4	2.6	2.5	30	2,7	10+	2.8	10	290	255	2.4	٠ سا
		452	H	11	79	125	30,3	1822	1.4	2.6	26	3. J	215	10+	2.8	D	180	250	2.9	
		502	11	11	60	58	22.8	1043	1.4	3.0	30	3,0	2,8	10+	2,9	8	185	150	2.1	-
_) - -		50)	in .	H	60	58	228	1020	1.E	3,0	30	3,2	28	10+	2.8	8	290 .	755	206	V
)	.,.	512	<u>It</u>	-11	41	3,5	15.6	188	/.2	3.1	3,0	3.25	2.95	10+	295	8	290	250	2.2	NO*
727		5/5	1,	11	42	40,5	15.9	497	43	3.1	3,0	3, 2	2,8	10+	2.8	8	190	250	2.0	NO#
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- o	38	1033	ŘEV	ccw	80	78.	28,7	1670	1.5	2.5	3,0	3.1	3.0	10+	2.9	10	290	180	2.5	/
		1042	: 11	11	195	125	29.2	1719	1.6	2.6	305	3.1	3.05	10+	2.95	10	290	190	2.6	~
		1048	1	11	60	5825	22.1	962	.6	2.0		<u> </u>	3.0	10+	2.9	8	180	180	1.]	1
		1050		(1	60	S3.5	21.7	991	1.4	3.1		3.3	3.05	10+	7.9	8	190	290	23	•
H	-	1056	11	- 1 -	40	38.5	14.5	419	EN	3.5	<u> </u>		3.12	10+	305	8]-8	NO*
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7	-	1124	j.	 H	42	40.5	13,0	431	.9	3.1	23	5.0	3,4	6	3,35	8		_	1.9	نسا
TNO	_	1/32		11	41.	39.5	12.2	398	.9	28	3.4	4.8	3.5	6	3.4	5		_	1.9	
	_	1136	ָרָן בּוֹרַ בּ	- W	64	62	22.2	1019	1.1	2.5	33	4,0	3.0	13+	2.9	10		=	2.2	<u> </u>
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BLENDED BRAKING

SOAC # Z

3**8**

COUNTERCLOCKWISE

RUN GAZ

SPEED	DEAD TIME (SEC)	TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD OR NUMBER TIME OF DAY	JERK RATE MPH/ SEZ
20 21		8.5	116	1108	
X 21		9.1	118	1105	
JE 41	•	15.0	449	1102	
40		14.5	419	1056	
- 60		21.7	971	1052	
60		22.1	962	1048	
ad 19.5		29.2	1719	1042	
. 80		28.7	1670	1033	

3307

338 538 36 18 320 1700 1690

NUMBER THE BOEING COMPANY REV LTR SOAC SPEEDOMETER CALIBRATION HIGH-DENSITY CAR · TEST RUN 038 3/10/13 · DATA USED FOR OS CILLOGRAPH CALIBRATTON ALSO 50 20 20 30 40 50 60 TRUE SPEED ~MPH P. BROWN

3/10/22

- 945	_, _,	INDICATOR .	OHECK		RECORD
	715T 2000	417	34	TRUE 32.7	946
	2000'	. 28.6	49.5	47.7	951
	3500	31.1	78.5	76.7	957

-	SOME TEST FUN	039				
	MATE: 3/10/13	TIME		TART STOP 1:30pm		
	DYNAMIC	BRAKING G	cu w ww	ды долук () , чед (п. ша ш . че		
_	WEATHER CONDITION:	*				
	WIND SPEED 157 DIRECTION	BAROMETRIC PRESSURE		AMBIENT AIR TEMPERATURE	STOP	
	CREW: TEST CONTROL	LER & PAR	KER			
	OPERATIONS DIRECTOR DATA CONTROLLER P. C. INSTRUMENTATIONADDITIONAL PERSONNEL	By OREM BROWN	MOTO GROU REAR	RMAN BILL NO CONTROLLER MONITOR	CURRAM DICK HASKELL EY DINIS	1
	e de la companya del la companya de	and and a superior of the supe	Mangangha - was sha	and the real and analysis and the supposed and		
	VEHICLE CONFIGURATION) A.			· .	
	CAR 1 CAR 2		10500	20 48 ±.5°	7,	

THE FOLLOWING PAGES CONTAIN THE METHOD, 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

FRICTION BRAKING

SOAC #2

CLOCKWISE

Run DE

AM.

INITAL SPEED (ASMS)	DEAD T-MEN (SEC)	TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD OR NUMBER TIME OF DAY	JERK RATE MPH/ SEC
X€ 79		29.5	1851	159	
× 79		. 303	1878	206	:
× 60		22	1015	214	
× 60		21,5	1028	219	
× 42		14.4	478	219 228 223	
× 41		14.2	455	234	
42		13.5	N46	238	
\$ 41		14.5 7.5	417 431 119	242-246-249-252	
22	1	71	125	254	

STACT 318

298

2.8

II-13

DYNAMIC BRAKING

SOAL #2

COUNTERCLOLK WISE

RUN# 21

INITAL SPEED (ASMS)	DE AD I'ME (SEC)	TIME TO CTOP (SEC)	DISTANCE TO STOP (FT)	RECORD OR NUMBER TIME OF DAY	JERK RATE MANY SEC ²
20 -st		8.3	//9"	435	
28.21		. 9.1	107	433	
\$8 42		17.5	522	430	
40 42		17.8	528	426	·
.60. 6 <i>t</i>	÷	15.8	1197	422	
.60 62		25.0	1/36	417	
80 79.5		3/.6	1819	408	
. 80		3 1.1	1826	400	

DYNAMIC BRAKING

Sonl #2

Run #21

CLOCKWISE

INITAL SPEED (ASMS)	SEC	TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD OR NUMBER TIME OF DAY	JERK RATE MPHYECE
X21		9.2 cor	120	3:55	
1 23		10.3 10.5 MAR ANG 10.0	156	3:52	
W 41	,	17.5	5 39	345	
40 41.5		17.5	545	338	
XX 61		25.4	1/21	332	
66 60		24.7	1085	324326	
× 78		32.7	1877	317	
80 💢		33.2	1915	208	

CARAL: Z ACCEPTANCE TEST DATA EST. CAR WEIGHT = 105000 LB

TYPE: APOEN ————————————————————————————————————										
TEST	REC. DIRE	N SP	eed d	PAUS DEAD HTA TIME	RATE B		CEL.	AT ARMA	TURE D.T. + ENT 1/24t;	ACCEF
	CAR	BYCK IND.	TRUE TIME	DET 3	INIT-		COUNT, THE	Ate TRK	TRK TE	NOT
		mph	noh SEC	F SEC	Toph with	1°77 77	SEC SEC		amp ESEC	TIME
039	159 FWD	CW 79	77 29.5	1851 1.5	1.0 3.0	3.4 2.5	10+ 2.6	10 -	- 2.7	~
	206 "	11 79	77 30.3	1878 1.7	1.9 2.6	3.32.5	10+26	10 -	= 2.9	1
	214	17 60	58 22.0	10151.2	2.0 2,8	30728	10+ 2.9	10 =	- 25	√ S,
-	219 11	11 60	58 21.5	1028 1.3	2.8 2.9	3.8 7.8	10+ 2.8	10 -	- 2,2	<u>~</u>
7-1-	228 II	" 42	40.54.4	478 1.0	2.2 3.0	3.8 3.2	6+3.	5 -	- Z _* /	₩0 *
8	234 "	11.41	40 A.Z	455.9	7.632	4.1 3.2	2+ 3.3	5 -	- 2.8	P* 5,
3	238 II	11. 42	40.5 13.5	446.8	2.4 3.3	4.3 3.4	6+ 3.3	5_=	- 22	5/
-5	242 11	" 41	40 14.0	41710	2.53.4	4534	6 3.4	5 =	- 23	5/5
8-	246 11	11 41	40 13.7	431.9	253,3	4.3 3.4	6+3.4	5 =	- 20/	V5/S
	252 "	11 21	20 25	119 .6	24 3,2	4.7 4.0	- 4.1	3 -	- 7.7	5/:
- Y	254 "	" 22	20.5 0.1	125 4	293.	3 4,9 3,9	- 4,2	2 -	- 1.5	5/
039	308 FWD	CW 80	78 33	1951.4	1.6.2.	2.6.7.5	10+26	15 195	145 3.0	
	317 "	" 78	26 32.	1877 1.5	1.52.3	2625	10+ 2.6	15 295	240 26	
>	326 11	11 60	58 24.	10851.4	2.126	2.62.6	10+ 265	10 800	24528	
276	33Z <u>11</u>	" 61	59 25	1121 164	1.9 2.6	262 25	10+ 7.6	10 795	750 2.8	
2	338 11	11 4.5	40 12.5	545 1.4	1.9 2.6	2.6 255	104 2.55	10" 795	0502.6	
\$-	345 11	11_41	40 12.5	5391.2	V.8 26	2.6 255	10+26	10 795	245.206	· · · · ·
五一	325	11 23	21.5 10.3	150.5	2.5.2.6	2626	7 26	5 295	2401.5	
	355 0	11 21	20 9.4	120.6	24 25	5 255 255	6 2.65	5 190	245 106	-
039	400 REV	can bo	128 31.1	18261.5	2.02.6	2.92.9	10+ 2.8	10 290	280 2.6	1
رک	408 11	11 79.5	7253.6	1819 1.4	1.7 25	12.9 29	10+2.8	10 295	75 Z.5	مرا
₹ -	417:1	11 62	60. 25.0	11367.4	202,9	Z.9 2.9	10+ 208	10 190	800 2.7	1
(422 1	11 64	62.258	3 1197 1.5	2.128	2.9 2.9	D+ 2.8	10 785	185 2.8	~
٤	426 II 430 "	11 42	40.5 12.9			2.92.9			200 3.5	1
á .	433	1 11 21	119.5 9.1	107 .6	2228	2929	5 2.8			
- L	. 	1 1 61	119.5 8.	2417 . C	197.40	129 2.9	12 6.8	3 790	120 1.4	سيا

TIME AND DISTANCE TO STOP DYNAMIC BRAKING ONLY [CAR WEIGHT CW1 105,000 LBS]

NOTES:

1) LEVEL TANGENT TRACK

2) TRAIN RESISTANCE INCLUDED

(ZERO WIND)
3) GEAR RATIO 4.78

4) WHEEL DIAMETER 30 IN

5) JERK LIMITS AND DEAD TIME NOT INCLUDED

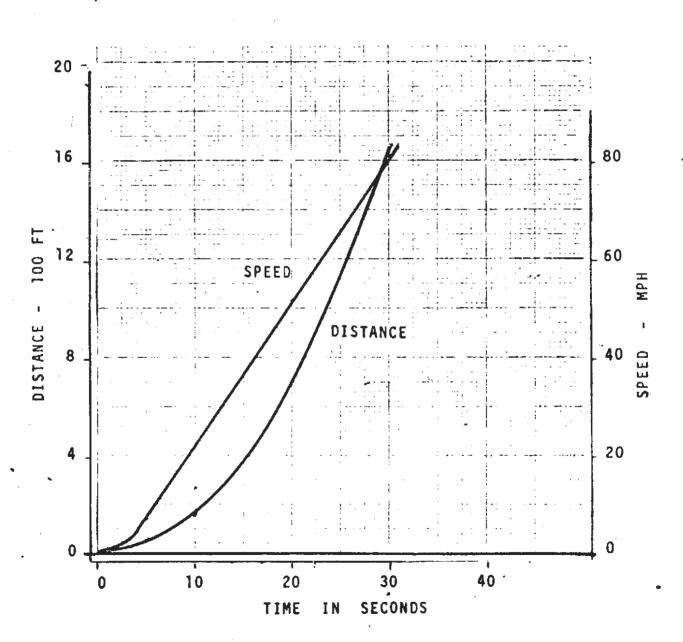
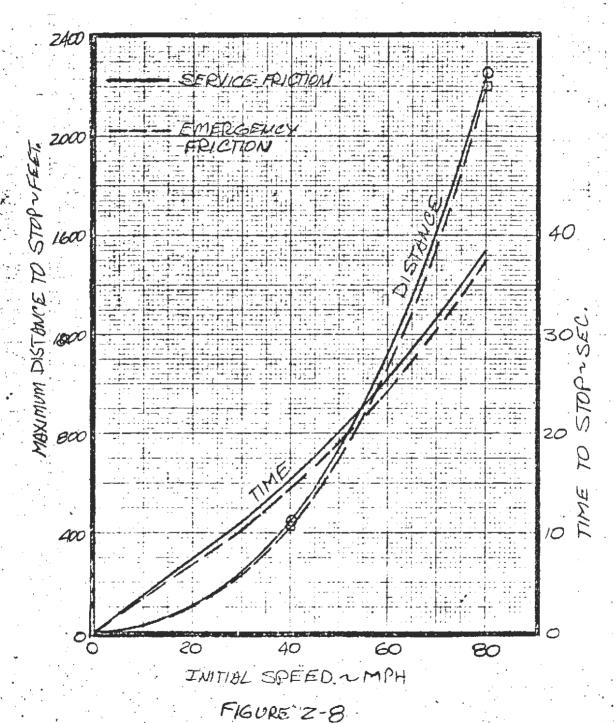


FIG. 2-7 SOAC SPEC.

TIME AND DISTANCE TO STOP SERVICE AND EMERGENCY FRICTION BRAKING

NOTES:
1) LEVEL TONGENT TRACK
2) INCLUDES SERK LIMITS
AND DEAD TIME

CAR WEIGHT: AWI ~ 10500048



II-18

SOAS TEST RUN	049	- 10 July 10 J		
DATE: 3/19/23	TIME:		53. p.m.	
	ON BROKING ~ FWO-CC		3CP'S (Fw)) 1 BEV)
WEATHER CONDITION:	5			
WIND SPEED	BAROMETRIC PRESSURE	AMBIENT AT TEMPERATUR		
CREW: TEST CONTROL	LER R. BPOS	<i>H</i>		
OPERATIONS DIRECTOR DATA CONTROLLER P-CINSTRUMENTATION	5 ROWN	NOTORMAN WO GROUND CONTROLS REAR MONITOR	. CURRAN ER P. HASKEL	· · · ·
ADDITIONAL PERSONNEL	J. FOGEL		, .	
VEHICLE CONFIGURATION	•	nen erre - englette ret der de understen der gesche e		· ·
CAR 1 CAR 2	10500	043		
THE FOLLOWING PAGE	S CONTAIN THE ME	THOD, 'QUICK-L		= TO MOPSE
RECORDED DATA, BCP'S 60.5/60	OF SERVICE	10 20 82		Emerc.
033 (ADJ. TO 66/	166 —	SERVICE EMERGENCY) }	

II-19

FRICTION BRAKING SOAC#11D CONTERCLOCKWISE-FWD 049

	de Village de Landing	Annual Supplement Supplement	entransportation and from the entertained and accompany fields.	SPECIAL SECTION OF THE PARTY AND THE PARTY A		:
Carecompt Carecom Carecompt.	1917. SPS)	=	TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD	BCP
***************************************	40	41	15.6	475	1/22	ZS11
	20		- Farmenhagen i da Malana den - en - perenante autolon desgrane antidagogum e			
45 E	7.	91	200	108	1_1125	
	ne,	905	12.5	414	1118	63
-	44	41.5	13.5	453	1115	
an . Language of the	- 60	58	19.2	907	1/17	69/67 4515
	30	61	21.0	1032	1106	69
	۵Ü	80	29,0	1293	1130	69
-	හිට	80	30.2	1901	1059	69
•	3/	300 999	33800 31893	33 <i>300</i> 33 <i>347</i>	33920 333 86	a de la companya de l
		901	907	453	414	
-	33800	7				
	179	3				

FRICTION BRAKING SOAC# 12-0 CLOCKWISE-REV. 049

INITA SPEE		TIME TO STOP (SEC)	DINJANCE TO STOP (FT)	RECORD NUMBER	всР
	IMO.		And in the contract of the con		
20	21	2.8	139	1134	
40	40	13./	416	1140	
иŌ	41	14.0	420	1136.	
4.0	42,	5 14.4	500	1138	
- 60	58	20,4	953	1144	
60	61	21,9	1066	1146	•
60	ଥ୍ଡ	30.6	1887	1153	
80	30	31.8	1970	1201	
,	72200 1800 470	32253 31800 953	32866 31800 1066	31800	-

PBROWN DUTTE 1VO. I LUCOR

TEST RUN: 049 3/10/03

FACTION BRAKING 105000 LB

PEC. Nb.	DIRE	GT-	INIT Sea	TAL I	STOP	PING TA	DEAD TIPIE	F	DEC	ا سب	DECEL.	DECEL.	Br Miran mov - 1	ACCEPT
	7					_		R.	INIT-		ACCELF2-	SPETY		5
-	TRACK	A	ארא. מבנה	E	1 6	3	SEC.		IBL	A3K.	mph/ SEC	TRACE	ان، مدنده،	laga a 🎤 e e e e e e e e e e e e e e e e e e
	۲	κ.	14 A	nph	SEC	+1	SEC.	secz			ISEC	"Thisec		·
1059	CCW	FWO	80	18.5	30-Z	1901	1.0	1-7	3.0	3.9	2,25	2.7		
7130	h	II.	<i>8</i> 0	18.5	29.0	1793	1.0	2-1	310	3.9	3.0.	2.9	_	/
1106	j. n	u	61	60	21.0	1032	.9	2.0	3.1	4.5	311	3.0	general control of the second	
1112	ч	11	58	525	<i>17.</i> 2	907	.7	2,0	3.1	4,6	3.1	3.0	i a i i i dan i i i i i i i i i i i i i i i i i i i	
1115	"	- 11	41.5	40.5	13.5	453	.6	2.1	3,/	4,5	3.4	3.5	al words	J.
1118	и.	11	40.5	40	12.5	414	-7	20/	3.3	4.7	3.5	3.4	la militar de la composición dela composición de la composición de la composición de la composición de la composición dela composición de la composición dela composición dela composición de la composición de la composición dela composic	V
1125)! !!	11	21	20	2.0	108	.3	2.5	3.5	4.7	3.6	3.4	a rain rain de	
											•			
1134	CM	REV	21	20.5	2.8	139	.6	2.2	3,0	4.3	3.5	3.4		
7136	u	ti i	41	40.5	14,0	470	.7	22	3.0	4.3	3.3	3.4	an a de la companione d	po estados en estados de la contra del la contra
38	4		125	41	14.4	500	.7	2.2	2,8	4.6	3,3	3.4	elegione de la company de la c	and with the second
1140_	it	11	40	39	13.1	416	-6	2.5	3.1	4.5	3.4	3A5	alang day in see Marie (1994) (1997) (1997) and an included determined	المنتسبة المالية
1144	it.	i.	58	525	204	953	.8	1.9	2.8	3.8	3.0	305	and the second s	
1146	ıt.	11	61	60	21.9	1066	10	1.9	2.8	3,6	29	7.85	**** **** **** ***********************	
1153	11	ų,	80	79	30.6	1887	1.1	1.8	2.6	3.1	2.7	2.6		مسا
1201	u u u	15	80	28.5	318	1970	40	1.9	25	3.0	2.5	2.5	.,	
	*								!				241 - 41	
							-				6 - 100 (100 mm 1 mm)		ļ	
			-					1.7		2 200				1 - praise dip - real for - An
apering a community of the community														
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				1	1			[
				!	-			II-	22		1			
and an element of the con-				-				T Tale		a				
- +			1		-		-			1				
		∮ 150	4	1	↓	\$ - · ·	1		1	ŀ			Į.	<u> </u>

4.3 Automatic Speed Maintaining System

4.3.1. Accelerate car to each of the following pre-selected speeds with Controller Handle in <u>Full Power</u> position. Monitor parameters as in paragraph 4.1. Evaluate capability of the speed maintaining system over a 15-30 second time period.

RUN	No. 049 3	3/17/73	
RECORD	SPEED	INDICATED	FWD- CCW
NO.	SETTING	SPEED	CCA
1215	3		
1217	15]
1218	25	25]
1219	35	36	
1220	50	51	
1221	70	70	
1222	80	80	

4.3.2. From an initial pre-selected speed of 80 mph perform the following speed reductions using speed select inputs with Controller Handle in <u>Full Power</u> position.

Monitor parameters as in paragraph 4.1. Hold reduced speeds for at least 15 seconds. Evaluate speed maintaining capability at each reduced speed. Record data per performance test instrumentation configuration given in

Table II. KUNNO. 049 RECORD NO. FINAL INDICATED SPEED SPEED 1223 70 80-70 50 1224 70-50 1225 50-35 1226 35-25 1227 25-15 228 15-3

SOAC TEST NUM	050	
UATE: 3/17/73	TIME:	2:20 4:00 P.m. P.m.
- CH5CK	ENCY BRAKING BLENDFO BRAKIN OUT NEW "PRO CEL. & BRAKE	6 WITH LOWERTD BCP'S OUCTION "PDR
WEATHER CONDITION:	\$	
WIND SPEED DIRECTION	BAROMETRIC PRESSURE	AMBIENT AIR START STOP
CREW:	LER R. BRUSH	**
OPERATIONS DIRECTOR	SROWN ERU	CRMAN W. CURRENT UND CONTROLLER R MONITOR R HASKEU (Z GUESTS)-BRUSH
VEHICLE CONFIGURATION	and the second s	

THE FOLLOWING PAGES CONTAIN THE NETHOD, 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR

105000 LB

CAR 2

CAR I

CHONGES: REPLACED "OLD STYLE" PDR WITH "PRODUCTION" PDR
-SWITCHED 2 CARDS DURING RUN @ 3:50 p.m.;

TARM OSCILL. IN REV-DREBRY
WITH BOTH CARDSES: LESS WITH

SECOND SET. TT-94

L-D COR

BLENDED SOAC #/ L-D COUNTERCLOPKWISE-FULD OSO

	INITA SPEE	ì	TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD HUMBER
	2 0				
	20				
T	ก์บิ	90,5	15.7	451	355
L.	1+.7	40	16.3	514	352
	60				
	60	r			
!	ටි				
	80	80	30.5	1805	346
	3/	995	33800 31995 1805	33800	

PAGE DOUGH IN ZOOH SEC -> STOPWORCH

ZIO SEC -> OSCILLOGRAPH

CCW-FWD DIRECTION.

EMERGENCY BRAKING SORC#1
105 KIB
L-D
CLOCKWISE - REV RUN + 050

Programme and the second secon	INITA SPEE		TIME TO STOP (SEC)	DISTANCE TO STOP (FI)	RECORD NUMBER	BCP
	20	22	20	115	320	Agra, and assume several section of the first of the section of th
	20					
programme of the second	40	41	12,0	359	322	Ayenaniya "Jamas" .
Marie and a	40	A1.5	11,4	359	324	
A Land Contract of	. 60	59,5	17,4	785	327	
A TANK CONTRA	60	60	18.0	8Z6	330	*
THE PLANT	80	80	25.8	1533	336.	
Contraction of	80	80	27,0	1614	341	
••	31	800	32159 31800	37639	37595	•
	3262 3180	36 16	31800 339 33353 31800 7333	359 53414 31800 1614	785	

EMERGENCY BRAKING SOAC #1 L-0

INITAL SPEED		TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD NUMBER	BCP
20					
20	23	6.8	109	315	
110	12	*1/07	376	312	
- 40 K	11.5	12.1	376	311	
- 60	62	18,4	875	308	
60	61	18.3	847	304	,
80 <u>8</u>	30	25.3	1534	257	
80	80	25.8	1595	235	28/
33.8	300	33800 32266 /\$34	33,500 33,953 847	33900 38925 895	•
339 334	00	33800 33691			

11-27

P. BROWN DUHE NO. I L DIME

TEST RUN: EMERGENCY BRAKING
050 3/11/13 105000 LB

EC.Nb.	DIR	N	SPE	ED	STOP	PENG TA	DELO	"JE	DEC	-6-	DECEL. AVG.	DECEL.	1	ACCEPT.
	TRACK	C _A R	Ψ _N D,	Rue	TIME	DIST		K.,	JAIT-	PESK	ACCELEZ-	SPETO		3
	K	_	mby	mph	SEC	ft	SEC	35C 2			mph/sec	mphsec		
235	CCW	FWD	80	78.5	25.8	1595	-	2,0	3,4	4.3	3.0	2.90		-
259	()	1)	80	B. 5	25.3	1534	-	3./	3.4	4.4	3.2	3.0	·	
304	Л	11	61	60	18,3	847	_	2.8	3.4	4.7	3.5	3.4	3/5	
308	Ð	0	62	61	18,4	875	_	207	3.3	4.8	3.4	3.3		-
311	u	1)	41.5	40.5	12.1	376	-	2.8	3 .5	5.0	3.6	3.7	5/5	-
3/3	11	"	42	40.5	11.7	376	_	3.1	3.6	5,0	3.8	3.8		
3/5	1'	",	23	22	6.8	109		3.5	36	50	4.4	3.9	5/5	<i></i>
320	CW	REV	22	22	2.0	115	_	4.0	3,3	4.5	3.8	3.6	3/5	
- 322	11	,,	41	40	12.0	359	-	3.6	3.5	4.7	3.7	3.8	3/8	-
*24	N .	ч	41.5	40.5	11.4	359	_	3.6	3.7	5.0	3.9	3.9		1-
327	1,	'1	59.5	59	12.4	185	-	3.4	3,2	4.3	3.4	3.35		·
330	11	11	60	59	180	826	-	3.7	3.1	4.4	3.3	3.25		
336	[*] R	13	80	29	25.8	1233	_	2.7	3.5	3.7	3./	3.05		<i></i>
- 34/	11	1 1 1	80	28	27.0	1614	-	2.5	3.2	3.5	3.0	3.1		
	-			BLI	EN	DE	Q	B	24	Z1/	16 C1	HECK		
346	CCW	FWD					1				2.95	1		
352	"	11	40	39.5	16.3	514	.6	28	3.0	3.1	3.0	28	1.65FC	
355	11	13	10.5		5. 7	451	-6	2,8	3.0	3.1	3.0	2.8	.65EC	
			-			- -					•		time @ ZEZO ROTE	
											4 - 4 - 4 - 4 - 4 - 4 - 4 - 4 - 4 - 4 -		1-41 4	
· · · · · · · · · · · · · · · · · · ·					- 1						w w	, . ,		** * * * * * * **
									II-	28				
														•

٠	SCAC TEST RUN 052
	TATE: 3/19/23 TIME: START 5:17
	PURPOSE: - CHOPPER BOSE SREED: LOW I CHECK - BLENDED BRAKING 40480m14 - EINERGENCY BRAKING - INITIAL ACCELERATIONS: 0-100 ft
-	WEATHER CONDITION:
	DIRECTION BAROMETRIC AMBIENT AIR START PRESSURE TEMPERATURE SYOP
	CREW: TEST CONTROLLER P. PARKER
·	DATA CONTROLLER W. BALLOUEZ GROUND CONTROLLER P. BROWN INSTRUMENTATION REAR MONITOR R HASKELL
	ADDITIONAL PERSONNEL
	VEHICLE CONFIGURATION:
	CAR 1 (CAR 2) 105000 LB H-DEAR

THE FOLLOWING PAGES CONTAIN THE METHOD. 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

DIR TIME 50 700 DECEL VMAY

253 FWD-CW 20.0 18 Mph

305 FWD-CW 21.1 200

500 FWD-CW 20.50R21.5 200

EMERGENCY

PAR #ZH-D

REY-COW

052

• • • • • • • • • • • • • • • • • • •	INITA SPEE		TIME TO STOP (SEC)	DILTANCE TO STOP (FT)	RECORD NUMBER
· _		Ima			Mile Shak (Mile) (Mile Shakkinin) (Ja (Mile) (Mile) (Mile) (Ja (Mile) (Mile) (Ja (Mile) (Mile) (M
_	20				-
· ·	20		7.25 / 8.4?	95	340
	40	41	74.6: / 11.5 .	335	338
	40	42	12/12	3'61	335
·	. 60	62	17.9/181	812	33/
_	6 0	60	18/18.6	798	328
- ™	دن ا	79	23, 4/24.4	1439	323
<u>.</u>	1 0U	79	24.15/ 24.6	.1433	318
Breno		79	Z 8.5	1780	5/0
• ***	35800 .32120 17 6 0		33500 32367 1433	32361 33	500)3500 002 38CSB 798 812
-	33800			-38F	
	33439			3705	
(-)	. 36	1	335	95	

3300

32460

EMERGEVEY

CDR N+ Z H-D

FWD - CW

	INITAL SPECI	- (TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD NUMBER
	20				
ALTERNATION ACTION	20		7/ 7/3	105	407
	άÛ		10.8/-	315	405
1115	40	39	11.1 / 10.5	312_	402
	- 60	59	17.4/17.2	769	359
Section 1	60	59	17./13.55	766	355
An openior and	່ອິບ	79	25,5/25,6	1508	350
Control Statement	δÛ	79	24,75/24.8	1,47	346

33.277

 BLEVOLD

CAR ME Z HD.

Per - ccw

052

INITAL SPEEL	- 1	TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD NULSER
20		and the second s	onageng assentially populations a single of a distribution deplaced subject to the control of th	
20				
ທົ່ນ	4)	15.5 15.5	455 519	426
40	41	14.9/14.5	436	423
- 60		•		
6 0				
60			,	4 418 Scrotcij
80	75	252/29.0	1718	41)

32100

BLOWDED COIL Nº 2 H-D
PUD-CW
052

Inital Speet	i	TIME TO STOP (SEC)	DISTANCE TO STUP (FT)	RECORD		
20						
28						
40	41	7.41/ 1.41	448	453		
40	41	14.6.715.3	477	445		
- 60	·					
60				*		
& Ú	79	29/29	1742	439		
80	79	25 /29.3	1.736	435		

SPEED COLIB

PECCRED Nº SPLED T9ME 28.5/26.6
500 \$9.51mp 28.5/26.6
504 34 91.7/91.7
510 59 17.17/35.8
511 CHECK TUN ON

TRUE

47.8

32.7

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-2.1

II-35

SOAC Nº 2 CARZ (H-D) ACCOLDIATION TEST ZU- 052 3/20/73

T							
75 2°	Time sec	ACCUL MOE/SEC	200	APT	VOLTOGE (CAP (BANK)	CA 12 57 EEG	community.
253	0 35 2.35 14.35 6.35 10.55 12.35 17.35 14.35 18.55 20.35 20.99	1.05 1.72 2.53 2.44 2.32 2.32 2.32 1.39 1.17 1.56 1.39	854 873 873 874 834 787 783 173 783	811 822 807 800 790 770 770 770 777 7755	00000000000000000000000000000000000000	1 7.2 5 10.5 10.5 23.5 23.5 33.5 43.8 43.8	FUD - CW VMAX * 77MPH TTO 700 = ? TO = FIRST MOTION PL
Smar Jee	2.5 .54	2.40			\$75°	30.Y	Her-can
305 L max V min T you	24.6	2.52			550	43.8	Pw-Cw
G MAY STORE	74.47	2.56			575 II-36	73.2	Pu0 - cw
	1.00		-	ŀ	,		

TEST END!

BRAKING TESTS

057 3/20/73

105,000 13

_	• •	DIRE	আগ	11-17 57L		STOFF		Cas		DEC.		DECES	DECEZ AV/At		ACCEPT.
	حادث ا	Faxcy	نہو	エレり	Teve	TIME	DIST	TIME	E 7	م(7،∼ھ	PEAK	Accuration	Stello		?
		ેંદ્	K.	мон	E NG	ثخد	PT	Sಆ೩	MPH SEC2		Aζ	MPHY.	MPD, SUE		
					Er	16	26	ادلا			₹ 26 £	126			
•			ſ	-					.~						
	318	ငယ	REV	کار	רר	24.प	1433		3.22	3.36	421	2.9	3.14	· • · ·	- V
•	323	"	ų	79	77	24,4	1439		3.49	3.29	4,00	3.07	3-14	5/5	V
	318		11	62	60	18.3	798		2.99	3,41	4.13	3.37	3.29	5/5.	V 23
	331	u ,		62	60	18.0	812	_	3.26	3.36	4.42	3.41	3.27	5/5	V
	335	и		42	40.5	12,0	361	-	341	3.5 <i>&</i>	4.46	3.66	3.66	5/5 (2)	V
**	338	H	"й 	41	39.5	11.5	335	-	3.32	3.62	4.47	3.83	3.80	S/S Long	V
_	340	Й	11.	20	18.75	7.25	95	-	438	4.12	4.34		3.28	2/12	
	16	ديب	FWD	79	77	24.8	ירו	_	3,24	3.24	3.83	3.08	2.9x		v - 3.
	350	и :		79	לר	24.5	१२०८	_	2.36		346	3.03	2.88	. <u>-</u> .	34
	7.55	н.	W	59	57.25	D.3	مامات	_	l	3.15		3.36	3-28		Var
	359	16	H.	59	ภวร	17.3	769	~	3.12	3.45	4.21	3.70	3.20	PAPUE SPAZO CHANGED	V 9:1
	402	ig.	ч	39	37.5	10.5	312	-	4,63	342	4.72	3.75	3.47	,	<u>V</u>
	405	п.	ρ'	40	38.5	10.8	315	-	4,00	366	4.67	3.75	3.80	S/5	
	407	•	n.	20	18.75	7.2	105	-	† Z8	3.75	4.28	-	4.57	5/5	
						LE	יפטו	20	75	2.4	1611	ıg			
	310	ست	eev	79	77	₹8.5	שארו	1.36	2.32	2.65	3.16	2.95	2.8/		
	411		и,	79	77	18,6	צורו	1.40	210	257	3.4/	2.82	2.95		<u></u>
	425	5		97	37.5	14.7	436	1.0	233	307	3.16	3.03.	2.84		
	426	-		યપુ	35.5	15.5	313	1.24	2.69	2.78	2.93	2,39	288		?
<u> </u>	429	;	Ÿ	41	35.5	15.5	455	.48	127	278	291	2,74	268		?
_							- 				3.7				
										1	3./	100 miles 2 2 2 2			
-	1 F 1 F 2		(A)	./∀+./ ./∀+./		h			<i>A</i>		l	• ··· ·	£ .		

SOAC ACCEPTANCE TESTS

2 of 2

- PUN Nº:052 CONFIG: Nº 7 CAR (H-D)

ורמסביי	E	, -,		4.7	√	•	105	K L	D C	3 /2				
رديوه سم	DIR		ساماا		SICE	PING	D	h	DEC		DECEL	DECEL	c ^o	1
REC	3,12	-C1,	SPE		DA	TA	DE AD	1	RA	re	AVG	AV/at	M	ACCEPT.
	T_	_	١., ١	T.	ME	D _{IS} T	T, D	ETHRK"	ST IN	PEK	ACCELOMETER	SPEED)	WE ST. 2	
10-	K	C _A R	20	V _	"E	-1	TIME	K	· In	~K	MPH	TRACE	N _T	-
	TRACK	K.		T _{RUE}	SEC	FT	SEC	MELY SEC ²			MPH/ SEC	MPHY		
						!		1	l			i		
				١.	0	LE	NT.	ا سے	<u> </u>	> 1CA	2KILDG			
435	ديب	FWD	79	דר	79.15	1736	149	2.48	219	2.94	2.94	2.75		1
					ļ			١.						
439	U	W	79	רר	رور	1742	1.60	2.73	265	2.95	2.95	2.75		ئة برياس
445			41	90	14,35	477	116	287	295	295	7.95	7.82		
. 443							-			(,,,,		2.06		• 1,
450	4	•	41	39.5	14.65	456	.6	2,44	2.95	295	2.95	2.88		
453			40	3 3. S	14 4	448	.6	1.86	र. <i>७।</i>	रग	2.21	7.8 8		
1			1,0	30.3	11,5	1 10		1.00	0.73	(7)	517.4	. (.00		
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	i													
1														

Nº 7 CAR (H-D) SPEED CALIB 3/29/73 RUN 052

REC NO	SPERO	TIME POR	SPEED THE	SPEED-TRUE
•	11-9	Husos	colc	Trace
500	4 ዓ, ና	28.5/28.6	47.8/47.7 (47.75)	47.75
५०५	34	41,7/41,7	32.7/32.7 (327)	32.7
310	79	17.7/35.5 (2000 pt)	(אפטר) ף.טרן רד	76.5

SOAC TEST RUN	054	The state of the s	•
DATE: 3/20/73	TIME:	START STOP 2:00 SBO	
PURPOSE: CONTINUE	ENERGINE	9	ann
WEATHER CONDITION:	***************************************		
	BAROMETRIC PRESSURE	AMBIENT AIR TEMPERATURE	START.
CREW: TEST CONTROL	LER BEE PRUSH	(EVERT PARTES)	
DATA CONTROLLER WAS INSTRUMENTATION GOLD	a liptley M	OTORMAN DILL CUIT ROUND CONTROLLER EAR MONITOR DICK	-
VEHICLE CONFIGURATION:	en e		
CAR 1 CAR 2	105K LB.	kkendink i diskuputanian diffrati haringa kata dala sungsuarkan suntangkat d	

THE FOLLOWING PAGES CONTAIN THE METHOD, 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

NEZ COR I+D OVER CIERRY SLT UP TO 300% OF

PUN 054

2 CAR TRAIN

CCW - Nº 1 PWO

217	, Pla	LL CIOLOX	£ 1~17) D L "3L	DECEN
INITA SPEE	_	TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD NUMBER
	e de la constitución de la const	-	100	2
20	21.5	8.8 / 8.6	141	324
20	21,5	9.0/9.5	141	321
40	43	16.7/16.3	500	317
, 40	41	15.3/14.9	483	307
. 50	61	22.3/23.2	1032	300
60	60	22. /22.2	1000	250
30	70	25.6/-	1374	238
80	ור	26.5/26.6	[44]	224
	_	72 (Are)	334- 5	

33,800 32,926

 33855. PEICHN- BENKING No 1 CANL FUD

CEW NºL FWD

IMITA SPEE		TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD NUMBER	32800
20	23	8/7.7	135	330	33000
20	20	7.5/7.0	127	334	32965
40	41	13/13.2	440	339	
40	42	13/13.1	449	344	33700 35005
- 50	56	18.2 / 18.1	831	350	33700
60	60	15.2/15.2	921	406	73673
80	74	26.8/26.9	।५४७	416	33400
80	73	25.5/25.6	1508	430	33360
3366		33500 33673 127	33800 356 33360 329		3346c
3340	13 87	33500 32292 1508	· II-42		•

RUN 054 3/20/33

2 COIR TROIM 105K LB EMERGENCY NET CAL THO

					ACTOR WAS THE CONTRACT OF THE PARTY OF THE P
Particular and the Control of the Co	INITAL SPEEL	- 1	TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD NUMBER
A STREET, STREET, STREET, ST.	20				
Py C. SPORTSALPA	20				
TO SECURE AND ADDRESS OF THE SECURE AND ADDR	40			·	
Total Control	40				·
	- 60				
7.7	50	62	19.3/19.8	e59	440
	30	,		-	
	30				*
- 1		THE RESERVE AND ADDRESS OF THE OWNER, THE PERSON NAMED IN			

W 054 3/20/73

BLEMDED BINIKING
2 - COIL TRAIN
CW NEZ FWD

conflict The Net ons

)	TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD NUMBER
که	8.2/7.9	121	527
ಶ	8.4/	117	573
4155	159/15-8	492	517
41	15.8/15.6	480	511/
49	18.26/ 18.0	666	504
53	19.2/19.3	778	453
			•
	20 20 29 41.55 41 49	STOP (SEC) 20 8.2/7.9 20 8.4/ 41:5 159115.8 41 15.8/15.6 49 18.26/18.0	STOP (SEC) TO STOP (FT). 20 8.2/7.9 121 20 8.4/ 117 41.59/15.8 492 41 15.8/15.6 480 49 18.26/18.0 666

325)8

32466

SOAC ACCEPTANCE TESTS

MAJERNA

___of___

- PUN Nº: 054 CONFIG : Z-CAR TRAIN

, DATE: 3/20/73 . WT . 105K LB

REC	DIR	ECT.	SPEE	AL.	STEPP DA"	TA	DE AD	2 E RY	DEC	re i	DECEL	DECEL AV/At	CON	ACCEPT.
	T 24 G K	CAR	20	1-R7 E	¹ Me Sec	15 T	E ME SEC	R K	-Zerest		PH/SEC	SPEED (TRACE)	OK KE JAN	
					B	LEì	JD1			LAK	ING			
724 238 250 300 307 312 317 321	CC (1)	FLAD III III II	71 70 60 61 41 43 41.5 71.5 21.5	(5.75 69 55 60 40.25 47.75 40.75 74	76.5 77.7 77.7 16.5 16.8 17.5 18.7 18.7	1441 1374 1080 1032 483 543 500 141	.60 .64 .68	_	286 303 315 298 286 280 371 3.36	3.62 3.20 3.03 3.15 8.20 2.86 2.86 2.80 3.71	3.11 2.99 2.99 3.07 2.94 2.86 7.86 7.86 3.07	2.94 2.94 2.82 3.95 2.94 2.82 2.94 3.08		1 .92 3 .2)
					F	210	701	- ر	3R	PKI	NG			72:31
430 4(' 470 350 344 339 334 320	CCU !! !! !! !! !! !! !! !! !! !! !! !! !!	FU-D 11 11 11 11 11 11 11 11 11 11 11 11 11	73 74 60 56 42 41 20 21	7:05 72:05 55 55 40:25 40:25 40:25	25.5 26.8 19.7 18.7 18.7 13.1 13.1	1509 1587 97.1 83.1 49 40 127 135			2.95 3.24 3.32 3.32 3.45		7.94 1.82 3.49 3.32 3.37 3.74 4.21	2.81 2.55 3.37 3.60 3.60 3.92 3.92	CATE SHOP IN	20m/h
gammaharanan (to a gama) a saa s					B	LE	DD(D_	BK	AK	106	20 January 19 190	5 1 200 A 111 200 1	age of the same of
453 504 511 517 513 517	E(w)	REV II	53 49 41 44 70 70	18.78 18.78 19.75	13.7 15.8 15.8 15.8 15.8 15.8 15.8 15.8 15.8	778 (656) 460 492 117		II					ALL CH DIGERAPH (IL 1.2 COMPLETE	

SOAC TEST RUM	055		•	
DATE: 3/21/73	TIME:	START STOP 19:40 1/2:35		
HIGH SPEED	Z-COR TR (BOMPH) BLOWD ICTION, EMERICAN	•	TEST -)IEEEUV-
WEATHER CONDITION:				
	ROHETRIC	AMBIENT AIR TEMPERATURE	START	
CREW: TEST CONTROLLE	R BOB BRUSH	, compatible		
DATA CONTROLLS WAS BEEN INSTRUMENTATION PROPERTY.	<u>ucovor</u>	ROUND CONTROLLER EAR MONITOR GARY		to Maria
ADDITIONAL VERSONNEL 60	s kennse (GSI),	Descuis	(Geomo c	مالات)
VEHICLE CONFIGURATION:	,		•	
CAR 1 CAR 2	105 K	POSPORE THE REPRESENTATION OF THE PROPERTY OF		
	1		and the summary of the constitution of the second	

THE FOLLOWING PAGES CONTAIN THE METHOD, 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

NO CHAMGES

FOUND ONE BRAKE GRID CONNECTION ON Nº I CAR LOOSE - REPLACED BOLD & PIXED.

TRACK COMOITIONS VERY 6000 TO DAY

TT-46

PUN 055

BLENDED BROKING

2 - CAR TRAIN

CW DIRECTION - KEN

Mary and the contract of the	INITAL SPEED		TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD NUMBER
- Standard	militeratura de dividizador d	1MD	aczybulku,g.wcząpo-no towierzowak rądnił lacuminiania, żyggryliniania.	programmer design specimies and a supply small manifold with the SM committee of the	A AMAGEMENTAÇÃO (, populações provincios provincios partes por establishes provincios a compressiva partes por establishes provincios partes partes por establishes partes
THE REPORT OF THE PERSON ASSESSED.	20	22	9.3/ -	133	1640
THE PROPERTY OF	20	21	8.518.3	119	1036
A STATE OF STATE OF	40	43	154/15.3	484	1031
	40	42	15.5/15.5	459	ાળ્ય
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	- 60	ြ	27.6/224	1008	1024
Property of the	60	GI	23.0/22.7	1055	1018
THE PART CALL SAME	30	79	29.6/29.5	1757	1010.
ļ	i	I	1		

33565

33557 31800 1757

29.2/ 28.6

287/285?

32764

31800

1765

II-47

319
3230

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329 55

328

1001

BLLVOLD BAS **るこれところ**

Continua

2 - CAPL TILAIN

שו - היינות

IN) TAL SPEED		TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD NUMBER
20	22	9.3/ -	133	1040
20	ય	8.618.3	119	1036
40	43	158/15.3	484	1031
40	42	15.5/15.5	459	1028
- 60	ဖြင့်	27.6/27.4	1008	1024
60	GI	23.0/22.7	1055	1018
30	79	29.6/29.5	1757	1010
80	75.5	29.24 28.6	1765	1001
	75	287/295?		9057

319 328

33365

33557 71800

RUW 055

515

PERCHAN BLAKING

CW - PLEV MEZ COS

SPE		TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD NUMBER
20	w	6.8/6.9	103	1043
20	22	7.317.3	173	1047
μŋ	42	13.0/12.9	400	1050
40	41	13.3/13.0	399	1054
÷£0	61	20.1/20.	938	1057
60	61	195/20.	915	1102
30	79	28.6/28.6	1763	////
(() ()	79	29.2/29.2	1784	1118

33563 31500 31500 1763

II-49

RUN 055 BLENDED BLOKING COU FUD 2-COR TROIN NOI COB

	INITAL SPEED	3	TIME TO STOP (SEC)	TO STOP (FT)	RECORD NUMBER	CTA consideration on that appearing the CTA and appearing the CTA
-	20		Control of the Contro			
	20					3331
-	40	42	15.1/15.3	477	1129	3331
	40	43	16.2/16.0	508	1134	3200
	- 60					3199
	60					3200
	80	80	29.5/29.9	1709	1143	}' '
-	80	ક્હ	29.4/30.2	1704	1201	
	335° 33 <u>)</u> 4		N N N N N N N N N N	33800 3380 31991 3199 1709 17	56 04	-

PUN 055 PURDOM BILDKING ECW - PWD 12-COR TROIL Nº1 COB

	INITAL SPESI		TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	RECORD
hanner or the second	20				
The state of the s	20				
4	49		-		
******	اذِنَ				
	. 60	o and the second of the second		emple product deserve . A delication range a destruighting deservant part of the	
K. K.	6 0	~			•
Tight with sufficients	60	80	25,2/28.8	1791	1220
Branch Company	ଥିତ	જી	31,/31,2	1923	1210

33800 31817 1923 179

WRALLSUAL

___Or __

- PUN Nº: OSS CONFIG: 2-CAR TRAIN

. DOTE: 3/21/27 . WT : 105 K LB

REC	DIR	ECT.	SPE	ED	DA.	TA	DEAD	15 15 OK	DEC RA	TΕ	DECEL	DECEL AV/AL	C _O M	ACCEPT.
, N _o	FRACK	C _A R	120	TRUE	t Me Sec	PST FT	T _M E Sec	Re'		EAL	MPH/	SPEED TRACE)	ME MAZ	
1090 1018 1024 1031 1036	Class by a a b	2 W	125 A3 51 55 A3 16 16 16 16 16 16 16 16 16 16 16 16 16		শুন্ধ গুৰু	1757 1757 1055 1055 1757 1757 1757 1757		2.86 2.82 2.35	278 252 252 259 266 266 286 286 286	7.86 7.86 7.94 2.94 2.16 7.86 7.86 7.86	2.86 2.86 2.97 2.97 2.86 2.86 2.86 2.86	2.82 2.82 2.88 2.75 2.90 3.01	₩ &, Tino Cerr Tou bers Ly,	
					FE	IC.	101	٠ ر	BRA	KIN	G			2
1118 1119 1057 1054 1050 1047	1) 11 4 4	11 11 11 11 11 11 11 11 11 11 11 11 11	79 61 82 22 22	7) 55.15 55.15 38.5 42.5 72.75	15.7 15.7 15.7 15. 15. 15. 15. 15. 15. 15. 15. 15. 15.	1767 1763 914 936 189 980 123	108	152 1.77 2.35 2.52 2.78 2.52 2.65 2.31	282 295 315 324 347 372 373	3.14 3.74 4.62 4.63 4.46 1.88 7.59	282 2.55 3.36 3.24 3.74 3.53 9.21 3.83	288 7.68 3.27 3.50 3.60 4.44 3.32		20 mgh.
					BL	(C)	DEI	_	SRA	Kik	G			
1134 1134 1139	(CD)	rup	- 45 20 20		79.8 79.7 16.1 15.2	104 106 106 106	1.04	2.18 2.68 2.32 2.23	7.93 7.56 7.9	7.22 7.53 7.29 7.29	2.56 2.99 2.9	3.01 3.01 3.88 3.08		
					FR	10	JOK)	372	7K11	بهر			
1210 1210	سي	Fw0	<u>හ</u> දින	76.75 78.75	31.1 79.0_	1913 1791	.92 .96	1.77	3.03 7.55	366	5.85	7.62 2.82		
,											1 44 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4			
									II-	52				

SOAC	IEST	
26244.42	بمحال التحداسات	حاساسة ليدول

058

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ijΑ	12	3

3/22/73

TIME:

PURPOSE: . EMENGENCY BLOOKE TESTS

ZCOR TROIN BOTH DIRECTIONS

on ROUGE SECTION SPEED SWEEPS TRACK (V: 40-50 \$ 80)

WEATHER CONDITION:

WIND SPEED 13-25

DIRECTION

BAROMETRIC **PRESSURE**

START

3707

CREW:

TEST COUTROLLER BOD BINGS 13

OPERATIONS DIRECTOR J WATLLY " HOTORMAN GARY PAUL

DATA CONTROLLS WALT TELLOUGE

INSTRUMENTATION TONG DOSCIDEN

CROUND CONTROLLER DICK HASSEL

REAR MONITOR

ADDITIONAL VERSONNEL GORY WELLY, GUS KROUSE (CETA TOCKSIN

VEHICLE CONFIGURATION:

CAR 1 CAR 2

LOSK LB

THE FOLLOWING PAGES CONTAIN THE METHOD. 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECURDED DATA.

RUN 056

EMERGENCY BEALING 2-CAR TRAIN CW-PRV NO CAG

			nanchartes for East 1930, and to Alich Bridge	PARTING AND THE STREET, BY LANGUA THE YEST THE SAME BOUNDED IN
INITAL	1	TIME TO STOP (SEC)	TO STOP (FT)	RECORD NUMBER
20	- A paragraphy in the State of			
20	21	8.4/7,5	86	302
úΟ	41	11.3	325	256
40	41	12,5	337	248
60	61	18.0/17.6	806	242
60	63	18.8/18.9	881	235
80,	79	25.7/25.5	1520	230
\$0	79	27/265	1541	723
	50			219
ر بار	3341 1800 1597	37606	32681 321 31800 318	37 32126
. 2.	19			

EMERGENCY BRAKING CLW-FUD ZCAR-TRAIN Nº1 CAB

gar san igi hiri germensin	en krapitski kenkular	POWER CONTROL HOLD IN THE WATER WATER	ingle and one. There yell, reconstruction are necessarily appearance and the contract of the c	THE PARTY OF STREET AND ADDRESS OF THE PARTY	
INITA		TIME TO STOP (SEC)	DISTANCE TO STOP (FT)	record Number	
20	l				
20	22	7.47.5	100	350	
40	42	11.2/11.5			
Y		111.2	347	346	
40	41	123/-	350	342	
60	61	18.4/1865	860	335	
60	62	18.7/18.7	428	328	
80	ક્છ	25.5/25.0	1527	320	
80	80	25.8/25.9	1555	312	

MISSON CAPET SECONDS. PLECOID 357

ACCEL IN CEW . (FWD)

THIE JO 700 = 20./20.4 SEC

417 TIME @ 700 # = 10.4 / 20.4 SPEED @ 4000 # = 72

SPEED @ GOOD # = 72 MPH

SOAC ACCEPTANCE TESTS

_L_of__

- PUN Nº: 058 CONFIG: 2.CAR TRAIL

TREC.	518	ECT,	SPE	AL.	STOPE DA	TÀ	DE AD	7	DEC TV:	م ح	DECEL	DECEL	CO X	ACCEPT.
Nº	TRACK	1		TRUE.		24	TM E SEC	RKII MEH SECZ	Z.P.Se.	EAK	MCELOMETER	STEED) TRACE)	0 & 8 M 8 8 0	
					EI	クE	l .	<u>=</u> γ.5(1372	1642G			
223 236 242 242 248 366 302	11 H	2 4 4 4	79 79 63 61 41 41 21		7.77 3.25 18.8	1541 1570 581 337 325 86	111111	273 769 286 341 3.94 357 357	3.49 3.36	3.91 4.21 4.79, 5.00 454 5.00 4.0)	7.99 7.94 3.41 3.36 3.89 4.03 4.33	2.85 3.20 3.40 3.99 3.99 3.99		£3.5
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312 170 103 335 342 346 350	CELL 11 11 11 11 11 11 11	PivO H	80 80 67 61 47 77		25.25 15.7 15.7 15.7 15.7 17.7 17.7	1565			341 3.10 3.03 3.30 3.32 3.57	4.08 4.08 4.08 4.05 4.84 4.67 531 4.83	2.74 2.64 3.15 3.24 3.82 3.78 4.06	2.86 3.01 3.27 3.34 3.86 4.14 4.32		63
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417	20.4	756	496	oranis services and a programme and a	granis and a secondaria.	1.85	garina i se agranda de la composición del composición de la compos	The section when the section is	
	20,4			ר	**** ***** * **** * * * * * * * * * *	·		<u> </u>	
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	- 20	AC LEST RUIT			WIND SPEED	
	DATE:	4-9-23	TIME:	START STOP		
		KH-1	FOUD TRUCK		AMBIENT TEMPERAT	AI
 		INITIAL HEC	PS INVESTIGES BREKIND FL TO DOOF	Tr @ < 600 Voi	TS (DOT-001 ONLY)	UK.
•		VEHICLE CONFI CURRENT SH MOVED TO	GURATION: CAR ONT ON SET FOUO TRUE	1 (CAR 2) 10 TRUCK INITI K C 10:20 AFTER TUUT.	5000 68.	•
-		CREW:	ST CONTROLLER <u>/</u>	- THOMPSON		
		OPERATIONS D DATA CONTROL INSTRUMENTAT	IRECTOR <u>R.O25</u> LER <u>P.Broinn</u> ION	MOTORMAI GROUND REAR MO	CONTROLLER	
		ADDITIONAL P	ersonnel <u>Gewi</u>	- BROWN BIL	1 SEARLY	
	\bigcirc	NOTES - REDUCED I	A ≈11% F726	om FRIDAY 4	1/6 (NOW = 1-2/6 FROM 019-16	5T
PROF	8.→③	DIFF IX	FORM GIVES DUNECTED FROM THIS DINITOR & REPL		EVENT MURK)	
	5 6	LOOSE TO	TUT LITE O. COSD. FIX #2 70	N WISHOUT)	TOF PROP.	
		ON THE		LIGHT OURIN	16 RUN 023	

11220 4/2/23 - WO: 500 Monday (PEAR TRUCK) ZNO - Kum to 1 1157 300 AM 755-WD-13.5 MU 275, 4 AMTS 2.2777 388 AMOS 420 MATES 19,5 MU BOYINE 500 ANPS 211.5 MJ 520 AMPS BEAKE 11 683 23.3 10 700 AMPS TIP 20 750 AMPS 714 34.5 U 775 11 38.0 500 AMPS DR 367 " 380 AMPS 15.0 D16 (FRONT TRUCK) 1/19/23 10:30 A-17 PIN #2 500 AMPS 24.5 499 JURS END D TR 5/0 /10 50 25.0 OR 37.5 DR 750 " 765 255 " 755 " 37.0 DA 800 806 39.5 BRAKE 11 825 11 836 111.0

BLENDED #2 H-D BRAKING FND-CW RUN 023

INITA SPEE		TIME TO STOP (SEC)		TANCE OP (FT) DECELS	RECORD NUMBER
·	IMD			APPROX.	A STATE OF THE PARTY OF THE PAR
20				·	
40%	40	14.3	457	-13.2	1145
40	40	-14.2	459	-3-25	1140
40	38	13.8	407	-3.2	1137
- 60			, , , , , , , , , , , , , , , , , , , ,		
60					· ·
80	29	27,3	1620	-3./	1125
80	28	22,3	1660	-3.0	1116

29800 <u>29800</u> NO WEST/SOUTH DIESEL 200'- CW - 1153 - 19.2 SEC (ZWOTCHES) BLENDED #2 H-D BRAKING REV-1(W RUM 073

INITA SPEE		TIME TO STOP (SEC)		rance 'P (FT) Rote	RECORD NUMBER
	END			APPROX,	
20					
20	·				
ń0	40	-13.6	428	3.25	1211
43	40	14.0	428	-3,25	1207
- 60					
60					
80	80	25.7	1516	3,25	1202
80	79	25.4	1508	3,25	1156

33800

20	ACTEST TON	- 077			WIND SPEED
DATE:	4/9/13	204 TIN	12.0	5 4:45	DIRECTION
PURPOSE:	DYNAMIC DUTY CY	ATTONS-07004 BRUKING ONL CLE —	t \$ 0-80m		AMBIENT AIR TEMPERATURE
Co	VEHICLE CO	NFIGURATION:	CAR 1 CAR	2) 1050	0013
	CREW:	TEST CONTROLLE	R F. Thom	1052N	
	OPERATIONS DATA CONTI	ROLLER P. BRA	OREM DION	MOTORMAN GROUND CONT REAR MONITO	
•	ADDITIONAL	_ PERSONNEL		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
Notes:	ACCELA	ERATIONS	•	:	
DIR.	TIME TO	MAX SPEFD 4000 ft	No.	RATE	POSCILLOGRAPH DOTA.
Fwo-cw	19.05EC.	INDICATED.	146	2.80 ACCE	19.250c
REV-CCW	19000	79niph	154	260 ACCEL.	2.76 AV/st
FWD-CW	18.9 -	300 only	200	2.75/2	25 AV/st
PEV-COW	18.9	· sad' only	202	200/2	25 AV/st
			11-63		

SOAC HI-DENSITY (AR (#2) TEST RUN 074 (4/9/13) ACCELERATION DUTT.

									•	
No.	DIR- ECT- ION	INITIAL RATE (mphkac)	TAUL TAU	DYAt mph/sec (5 sec)	VOLTS PENK ACCEL	VOLTS BASE SPEEO	TIME 200ft SEC WATCH	TIME TO 2006+ OSCILL. (SEC)	SPED 2009L mph	VOLTS 100G
46	FWD-CW	2.80	~7.	2.89	615	584	19.0 18.9	19.2	40.2	584
154	REV-CCW	2.60	~7	2076	628	604	19.0 19.4	19.5	47.2	604
<i>20</i> 0	FWDCW	2.75	~6	2.95	615	592	18.9 19.1	19 . Z	46.0	584
30 2	REV-CCW	2,70		2.75	628.	615	18.9 19.4	19.5	46.6	603
-		REC. No.	SEPE JERK PATE (mph/sec) .5sec	JERK RATE (mph/sec) 1.0 SEC						
-		146 154 200 202	4.5 3.1 3.9 3.3	2.4 2.3 2.5 2.2						
-						II-64				,

DYNAMIC BRAKING ONLY #2 SOAC H-DCAR FWD-CW RUN 094

INITA SPEET	1	TIME TO STOP (SEC)		TANCE PP (FT) ROTE	RECORD NUMBER
	IND.				
20				·	
20			4.		
40	40	-15.7	484	3,0	Z28
- 40	40	15.8	48A	3.0	224
· 60	P-8-1-0 - 1-0-1-4 - 1-0-1-4 - 1-0-1-4				
60					
80	18	29,7	1722	3.0	218
80	79	29.5	1734	3,0	213

29800

DYNAMIC BRAKING ONLY #2 SOAC

REV-CCW

REV-CCW

PUN 004

INITAL SPEET	Į.	TIME TO STOP (SEC)	1	TANCE OP (FT) ROGE	RECORD NUMBER
	IND				
20				Additional control of the second of the seco	
20			-		
40	40	-1406	449	3.1-	246 242
40	40	15.0	450	3./	242
. 60					·
60					
80	29	26.6	1585	3./+	239
80	80	.26,5	1577	3./	232

33800

. 4		CAI	-DE/					CE TES		10500	OLB	
TEST PUN	REC		MAL	STEPP	N6	DEAD	JEN.)3 40% Decel. rate	DECEL	EDT.		
-		$\overline{\lambda}_{D}$	TRUE	TIME	DIST			arceir- omeiel	DY/st	JE ST		
		1 .	mph	(320)	(ft)	;						
				Z		DE	D	BRA.	KING:	FW	D-CW	
_ 073	1116	18	22	22.3	1660	_	-	3.0	3.2/	N.A.		
	i	Ì	1	21.3	1620	.8	2.4	3./	3.06			
-	1137	38	38.5	13.8	407	06	2./	32	328			
	140	40	40	14.Z	459	.7	2.4	3.2	3.28			
-	1145	40	40	14.3	457	-7	23	3.1	3.30	Y		
. —				BLEN	DED,	BRA	KI	NG: K	ZEV-	ccw.		
003	1156	29	28	25.4	1508	-9	29	3.2	3,28	N.A.	•	
-	1202	80	29	25.7	1516	09	2.4	3,3	3.28			* · · · · · · ·
	1207	40	40	14.0	428	8	27	3,2	3,36			***
	1211	40	40	13.6	428	.8	3.2	3.3	-	V		~··
	,			DYNA	MIC	B	RA	KING	CHL	y: Fn	10 - Cu	1
074	ZIB	29	78	29.5	1734	8	Res.	2.95	3.01	2.1	F	
! -	218	18	77	29.7	1222	8.	1.7	2.95	3.01	2.4		
_	224	40	40	15.8	484	.75	2,2	3.00	3.01	1.9		
Y	228	40	40	15.7	484	-8	2.0	3.00	3.08	1.9		
-				DYNE	mic	B	15H	KING	ONL	Y: RE	V-CCU	1
014	232	80	19	26.5	1507	-9	2.3	3.25	315	2.0		
	239	29	78	26.6	1585	.8	2.5	3.25	3.18	2.1		
	242	40	40	15.0	450	.s	2.4	2.20	3.14	1.7		
V	246	40	40	14.6	449	. 8	2.3	3.10	3.08	1.8		
												
-/~~												
m.,							II	-67				

CYCLE SERVICE DUTY FRICTION COR No. Z FLANGE RIM -HIGH DENSITY -BLENDED FWO-CW DIRECTION WHEEL TUREAD Herrore TIME CIA # TEMPERATURE CYCLE CHULE 514 298 2:52 35.3202m21. 3:46 ۷ 2 3 3 M.6 4 N. G.V 10000 5 7 250°(RFD) 4:00 8 8 9 L 9 4:05 10 L 10 4.96.5 憂 H. 11 1501/65 12 6 3/3 12 /200° 7100 13 400 13 1370 (RED) 14 L 14 F.B.F. 15 L 15 SCH 02017 16 1 16 370 RED 200° END, cut - Π / 17 LTT r 18 L 18 3:26 19 19 20 L 20 PAD RESIDER EN FIRE 21 = SLIP/\$LIDES 5218 22 51. 23 4 23 3:36:55 264 437 24 2 LARS & 33500-26400 3 LAPS +30000 52796 6+-> D=200FT, 192961 LAP = 9.12 MILES 9.12 26400 9.12 4625 9.12 11775 9.12 9,12 19296 27.40 MILES 7.19

II-68

1000

26.03 MILES

14 42,92 min

 $V = 36.4 \, \text{mph}$

_

51.0 MINDIES

V= 32.2mph

. SC	DAC TEST RUN	076		WIN	SPEED
DATE:	4/10/23	TIME:	STANT STORY	DIR	ECTION
	TROUBLE S	EDO-CALD 122	men LURCH S/S		AMBIENT AIR
3	PUT CURRENT SI ACCELS TO SA BLENDED E	RAKING	(6) STEEDOI	METER COLI	B,
. :	- LOGIC CARD	GURATION: CAR	D LOCATE +	per. 11410	, s, 22mpl
_	SK LURCHING - PUT CURREN	OF SHOWFON	FWD TRUCK	.6 / 2 4 ' 7	•••
	CREW:	ST CONTROLLER _	F. THOMPSON	,	•
	OPERATIONS D DATA CONTROL INSTRUMENTAT	IRECTOR <u>P. D.</u> LER <u>P. B. ROW</u> ION	GROU	RMAN G. Brown ND CONTROLLER MONITOR	
	ADDITIONAL F	ERSONNEL	T. HIX.	•	· · · · · · · · · · · · · · · · · · ·
RUN ME	TESS		•		
	DEPLACED J	34 with #2	H-D CAR J	34; REPL	KEO
	TOP SPEEDO	-CALD 46 W	ITH ORIGINISZ	THAT WAS	IM
	APPI. VOLTAGA	LY 19 IS SWAPP E FEEDBACK CI VE VBASE? (1)	RCUIT IN BOTH	- CARS: FIEL	D 700
2	BAD CORD	WAS CARD 4	16 TOP STEEL	DO CARD: AXL	E#1
_	DIDNOT GI	FT TRIPS-CR	ARD J34 is A	PROB. BAD.	(1:47)
3	REPLACE SEFT J	ORIGINAL NO. 34 FROM No. 2	1 POR CORDS	: 525, 53 46 FROM	2:535
•••	OTHER CAR	BACK-IN.	***		•

WEATHER CONDITION.

RUN NOTES:

A SHUNT ON FUND TRUCK-MODS. FROM # 3 BOVE & 2:03: NO S/S LURCHING @ 20 Mph ... PORD 46 CUAS BAD. "(H-D46)" NO TRIPS IN TRANSITION;

MODE I I DIR Y A/B REC

DR 650 32,5 663 FWD

SPEEDOMETER CALIBRATIONS

VIND COURSE TIME THE PEC.

80 4000' 34.25 19.6 21/
200 AMPS/TRUCK FOR BOMPH ON LEV. LOW.

50 2000' 27,25 50.0 219

35 2000' 38,55 35,4 ZZ3

STOP TO FIX CARD J34@ 2:39 \$ DLSO CHECK ARMOTURE YOUTS FEED BACK -> FLOD.

FINDINGS: FEEDBACK WIRE FOR DEM. VOLTS CONNECTED WRONG-MONITOR IS RESDING THE GENERATED VOLTAGE OF A DIODE COOLING FOR WATCH WAS

LOW-DENSITY CAR 0 PUN 076 4/10/23 . DATA USFO FOR OSCILLOGRAPH CALIB. ALSO. NOTES: USES H-D CAR SPEEDOMETER CARDS 60 50 40 30 P. B ROWN 4/10/23 SHEET II-71

CALIBRATION

NOT EVEN CONNECTED. (DIDDES BOOKD TO BELLINE
THE TWO TRUCK DEMOTURE CUPRENTS.) THIS IS
THE SIME IS ON #2 H-D COR DISO & WE
RIN THE FULL DUTY CYCLE ON UNCOOLED
DIDDES. GOOD DESIGN MAZGINION OR TITE
TWO DIDDES IN PORTLEL STILL FUNCTION WITH
ONE BLOWN -- TO BE DETERMINED ON #2. COR?
#1 LOOKS OK.

BACK ON LINE @ 3:35 -SMOUL FIX ON CARD \$34 REPLACED TRANSISTOR (DAMAGE FROM GOOVOLT) - FON CONNECTED ON DIDDIES - DRM. VOLT FREOBACK INSTALLED - NO TRIPS

MONITUR SHUNT ON FOUD TRUCK DR 200 IF, 35.0 mv -> 214 B 11 200 IF 11 -> 11 A BR 260 IF 39.0 > 275 CHOP ON,

ACCELERATION RUNS ACCEL. ROSE REC. NO. Vniox, T200' 4000 ~2,05 3:45 29mph 19.0 FWD. 19.7 <2,50 ? 29 mph 350 REV, 200 ONLY 19,2 ~2,75 353 FWO 19.3 19.5 ~2.50 200 any 356 ", REY 19:7

TEST RUN 076

ACCELERATION DATA (3) DIESELS ON-LINE S.+W. + DOT-COI

			<u></u>	S.+W	. + .007					
REC.	DIR- ECT- ION	INITIAL RATE (wan/sec)	TIME @ INITIME RATE (SEC)	AV/St nph/kec (SSEC)	VOLTS PFWK NCCEL	BASE	TIME TO 200ft (SEC) WATCH	TIME 70 200(t (SEE)	SIEED 2007 (mph)	VOLTS 2 2004
345	FWD	R.75	~8	2.80	640	600	19.0 19.0	19.1	47.4	600
350	REV.	2.5	~ 6 :	2.66	650	600	19.7 19.9	20,	45.4	595
₹ 3	FwD	2.75	~6	2.78	645	605	19.2	19.2	46	610
356	REV	2.50	-6	2.66	650	610	19.5	19.7	45.3	615
721	FWD	2.70	~6	2.67	645	600				_
_ 22	REV	2,55	~6	2.66	645	_		-		
MA	DE O	VE LA	P IN	PEV (رسے	AT 8	D MPH			
437	REV	2.65	~5	2.66	650	600	19.4	19.5	45.3	600
- 443 	RÉV	2.6	\$ 5	2,73	650	600	19.4	19.5	44.7	600
	AVG ROTES SMELT AVIST	FWO 2.74	<u>REV</u> 2,62	TOTAL 146. 268	II-	3	:			

TEST RUN 076 ACCELERATION DATA

JER	CK RATES	(MAHISECZ)
REC NO.	PEAK SLOPE	10 Sec.
345	3./	2./
350	2.5	1.5
353	3./	2.0
356	2.7	1.8
421	3.1	2.0
422	2.5	2.0
437	2.6	1.8
443	2.6	2.0

-TIME 502: LOST FWO TRUCK CURRENT! AFT TRUCK WORKS BUTNO PROPULSION

BLENDED BRJKING #1 L-D
FWO-CCW & REV-CCW RUN016

	INITAL SPEED		TIME TO STOP (SEC)	DISTANCE TO STOP (FT) PATE		RECORD NUMBER
		IND				
- ·	20					
_	20			~		
-FWD	40	41	-14.1	443	~3./	458
Fwo	۲.0	10,5	14.9	461	~3,0	404
JEV	40	40	14.3	453	13.2	415
REX	40 &0	41	14.6	446	23.25	453
	80					
w_	80					

33800

-	REC 421	PWD	ACCEC	-2.75
ا - ريس <u>ز آ</u> "	.922	REY	ACCEL	~2.50
1 N N	437	REY	19.4/19.4/50	ic→200/ ·
-LAP	443	REV	19.4/19.2	200/

*	CAR	IFL	PU PU	LEPTAN NOV	TOP IE		10500		
REC- JED 2.	INIT SPE IND. (mph)	TRUE (mph)	STOP DA TIME (SEC)	PING DIST (ft)	(SEC)	mph/sec ²	ACCELER- ONIETER (MPH/SEC)	DECEL RATE AVAT (mph/sec)	RATE ANG FOR DIRECTION (MPH/SEC)
		F	BLF. ORW	S D E	DIE DIE	ECT	OM		
404	40.5	41	14.9	461	.7	2.6	3.05	3.20	3.19
458	4/	41.4	14.1	443	•7	3.0	3,20	3.32	
		_ 2.	EVER	SE	DIRE	CTIC	N	·	·
415	40	40.5	<i> 4.</i> 3	453	.7	3,0	3.25	3.32	3.30
453	41	41.4	14.6	446	.7	3.5	3.3	3.33	
	·							•	
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		•							
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<u> </u>	AC TEST RUN 077		WIND SPEED
DATE:	4/11/23 - TIME: STA	58 10:00	DIRECTION
PURPOSE:	@ BLENDED BRYKING @ CHECK OUT MOTER CONNECTION	PM	AMBIENT AIR TEMPERATURE
	्र राष्ट्री		20.
	VEHICLE CONFIGURATION: CAR 1 CAR REPAIRED MOTOR CONNECTION	on two IR	NCK
	SAME CAROS AS LAST REC CAROS J34 & 46 ARE FROM "	24-0 MR.	
•	CREW: TEST CONTROLLER F. TH	MISOM	•
	OPERATIONS DIRECTOR R. OREN	PIOTORPIAN	. H/X
	INSTRUMENTATION	GROUND CONTRO REAR MONITOR	LLER
	ADDITIONAL PERSONNEL		
	•	5	
· NOTES			
	DOT-DOI NOT ON LINE (ON PO	RPOSE) WEST	\$
	SOUTH DIESELS ONLY ~	650 VOLTS	•
2	GOT SOME CURRENT SPIKES	DURING TRAN	ISITION

MEALINER LU

IM SPEED LIMITING - RECORDS AVOILABLE

BLENDED BRAKING #1 L-DOBR FUND & RUN 099

-amis	INITAL SPEEL	3		ME TO P (SEC)	1	PATE	REC NUM		DIR.
_		IND							
· 	20			· · · · · · · · · · · · · · · · · · ·					
-	20								
	40		7						
, m.	40				•				
750/160	ED: 558	20	26.	3	1614	~3.3	946		REY
-750/160	80	80	26.	5	1606	~3,3	940		REV
010/20	03	81	27.	,0	1648	-305	928	·	FWD
150/	ຮົບ	80	26.	.5	1636	-30	920	<i></i>	FWD

	CAR "	1 4		CEPTAI ON ON	UPE TE	ESTS	10500	OLB.	<u>-</u>
REC- - ORD -,vo.	INIT SPE IND. (mph)	FÛ	DA TIME (SEC)	DIST (ft)	(320)	MAJE MAJSEC2	PLACE EX- ONIETER (MPH/SEC)	DECEL PATE AVAT (GPH/SEC)	RATE AVG FOR DIRECTION (mph/sec)
	_	F	BLE	_	D BR. DIR	PECT			
404	40.5	41	14.9	461	.7	2.6	3.05	3.20	3.19
458	4/	41.4	14.1	443	-7	3.0	3,20	3.32	
_		_2	EVER	SE	DIRE	CTIC	N		
415	40	4P,5	14.3	453	•7	3,0	3.25	2.32	3.30
-453	41	4:4	14.6	446	.7	3.5	3.3	3,33	
					N C		u;	<u>.</u>	
920	80	29.5	26.5	1636		3.0	3.0	3.2	3.14
928	81	30.4	22,0	164B			3,15	25	
- :			REV	ERSE	DIRE	CTION		-	
940	80	19.5	26.5	1606		2.9	3,25	3,26	3,22
946	80	79.5	26.3	1614		2,9."	3,20	3.16	
					4	2.9 AV6			FSR AVG 32/ min/sec
_ :		ļ		4	II-79 ·		ı		

SOAC TEST RUN 01/8 WIND SPEED
DATE: 4/11/23 TIME: START STOP DIRECTION
PURPOSE: 1) CHECK OUT 2-CAR CONSIST (2) ACCELER NOTION (3) BLENDED BRAKING (4) DYNAMIC BRAKING ONLY
VEHICLE CONFIGURATION: CAR 1 CAR 2 105000 LB #1 (HR SIME NS RUM 097) #2 CAR BLOUGHT UP TO #1 (ARP) BUT SAME PERF. AS I AST #2 (AR RUN, 074?
CREW: VORIOUS TEST CONTROLLER F. THOMSON OPERATIONS DIRECTOR R. OREM MOTORMAN J. HIX DATA CONTROLLER P. BROWN GROUND CONTROLLER TOWEST
INSTRUMENTATION REAR MONITOR
G. DAVIS, W. COBB + FRIENDS & R.BRUSH
NOTES! O 1048 DRIVE FROM No. 1 N.6 ATRLEAKS. 1106 START AGAIN. Gloringh #1 = GZmph #2 BEC DIR CONTR. MME TO 300 VEROCO' 1123 FUD #1 20.0/20.0 05 mp4 NO PRELOWN 1128 " " 20.3/20.4 100' ONLY PRELOWD 1131 " 19.4/19.9 200' PRELOWD - LESS THAN GOO VELTS PRIOR TO 500'—
(5) 1702 SWITCH CONTROL TO #2 H-D CAR DATE STILL IN #/ CAR > BLEND BRK: ACTEL \$ DYNOM, ONLY
(3) CONTROL BACK IN #/ L-D@ 1:101m

L-D FWD

BIENDED BRAKING

#14 = SONC

FWD DIR ON 1-0 can

RUN 078

TRACKS CCW INITAL .TIME TO DISTANCE RECORD STOP (SEC) **SPEED** TO STOP (FT) NUMBER RATE Iwo, 20 20 14,3 40 454 ~3.0 14,0 453 ~3,0 45141 - 60 60 1659 -3.0 27.0 80 1664 27./ ~3.0 80

BLENDED BRAKING #14#2 CARS #2 H-D FWD DIR. (TPACKEW) RUN 098

INITAL SPECI		TIME TO STOP (SEC)		ANCE P (FT) RATE	RECORD NUMBER
20	INO CAB Z			ACCEL EST- ONIENES	
20			<u>.</u>		
49	40	-14,3	417	~3,3	1246
40	40	1402	423	-13.25	1293
- 60					
60					- M
08	79	26.3	1557	~3,3	1236
80	79	26.5	1529	3.3	1229

DYNAMIC BRAKING ONLY #/4. PZ SONC #Z H-D FWD DIR & (CW) RUN 0118

INITAL SPEED	H·⊅	TIME TO STOP (SEC)		TANCE P (FT) RATE	RECORD NUMBER
20	TV O			,	
20			Martin di		
40	40	* 15.0	447	~3,15	108
40	40	14.5	453	-3.15	105 pm
- 60		41			
50					
80	79	28.3	1644	-3.15	100 pm
80	19	28.6	1646	232	1254m

CONTROL TO #/ L-D CAB @ 1:10 pm.

DYNOMIC BRAKING ONLY. #15 #2 SONC #1 L-D FWD (CCW) RUN 098

INITAI SPEEI	L-0 #1	TIME TO STOP (SEC)	DISTA TO STO		RECORD NUMBER
20	IND		·		
20					
40	4/	*15.2	463	~2,95	132
40	40	14.4	467	~2.95	128
- 60					
60					
80	80	28,2	1000	22.95	124-
80	29.5	28,4	1706	-295	115

•	SOAC TEST RUN	080		WIND SPEED
• ,	DATE: 4/12/23	TIME:	START 3702/5	DIRECTION
•	2 DYNAMIC	Y CLESS BLENC	124	AMBIENT AIR TEMPERATURE
	VEHICLE CONFI (1) PUT ALL (4) S (2) PUT POSES FRO, (3) CHANGED OF, AM	n =2 (H-D) CAR	W CHOPPER INTO L-D CAP. B.	
	OPERATIONS DI DATA CONTROLL INSTRUMENTATI		MOTORMAN S GROUND CONTE	
	POSSIBLE 2 MO TRIPS & D.B.		GEN, Spikes: 2:37	
``	TO HOLD BREAKER CYCLE TO CUIC	CATE CLOSE ELEASE MEANS DOWN. CYC 29 & PROBLEM WITH LITTLE H-UP, DATA PIN S.E. R	PROPULSION II	CONTINUED TONTINUED TO ONE
	BV 175	ELF. TT-	85	

DYNAMIC BRAICING ONLY #12-DION FUD & REV DIRFOTTON RUN 080

INITA SPEE	D	TIME TO STOP (SEC)	DISTANCE TO STOP (FT) PATE		RECORD NUMBER	PIR.
	IND	12 4	1/16	/	200	REV
4020	41	13.4	700	~3,/	307	
4032	41	15.4	4.57	~301	304	REX
40	41	-16.3	494	沙茶	247	FWD
ri0	41	15.8	49/	22015	243	FWO
80 ₅₅	79	28,4	1679	~3,/	258	REV
80	80	28.0	1200	~3./	233	REX
80	80	28.7	1759	2015	239	FWD
80	80	28.9	1774	2	231	FWD

250 1 " FWD

* ACCECTIONETER
IS INFORMET IN
BRIK-FLOW DOTA;
INFORMITTIONS
PROPLEM.
—SEE FINAL TOBULATED
DOTA FOR PATES.

	TES	TR	20M	080		YNAMI	CON	<u> </u>	CAR	No. 1	40
(KCC.			STOPP. DATA TIME		DEAD	KATE	DECEL	RAIRE	SAT. Hater	•
		李子	Tie Impli	SEC	4	SEC	mph/ SEC ²	ACCELEZ: ONIESEZ MIHISEC	11/sec	+ 0°C	
				FORV	VARC) —	CCW	ON TR	UCK.	<u>-</u>	
4	23/	80	79.5	Z8.9	1994	-7	25	N.6.	2.90	45	AVG,
•	23 9	80	09,5	28.9,	1759	- 5	2.1	N.6.	293	10	2.96
,	243	41	41.4	15.8	491	.8	2.3	N.6.	3,03	1.8	mph/sec
_	247	4/	41.4	16.3	494	.7	22	N.6.	2.97	1.7	
_				-							
_			- 	REV	ERS	区 ~	CW	ON T	RACA	-	AVG.
_		80	79.5	28.0	1700	.8	2.2	3.05	3,00	109	3.04
_	258	19	78A	28.4	1619	.8	2.3	3,00	3.07	2.3	mph/sæc
_	304	41	41.4	15.4	457	.7	25	3.05	3.07	48	Z-WAY
	307	41	41.4	15.4	466	.7.	2.5	3.05	3,00	1.3	<u>a</u> v6. 3.00
				D)	ECOR	02	53 7	TME A	US TO	21/	mph/sec_
	PEF. TIME			PATE	SPERO	- Z	27	1116	HISTO		en e e e e e e e e e e e e e e e e e e
.	0	·		0	29.5		TIME	RATE	SPEED		e seeman and the seem
	2			2.25	32		26,5	1.50	1.5		ST ASS Proper age to
`	941	100		2,90	69			# 1 1 1 m a 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		- 14 - 18 miles - 1 - 1 - 1	paramatan per
r	- 8		1	3.00	93		- · · · · · · · · · · · · · · · · · · ·				L
٠	- 261			3037	317	-		4 14 44 4 1		***************************************	´ .
wage.	28 28			1.20	6						•

SOUC L-D CAK SERVICE DUTY CYCLE 1/ 173 RON FWO ~ CCW DIRECTION FRICTION CNLY

BLENDED

	- Nore	R		•		WHEEL	TUREAD	
	CHCLE	TEMPE	RATURE			CYCLE	TEMPERATURE	
	, ~	3:11	323		,	IV	4311 127	
ļ	21			w ·		2		
- '	3 1	s 3:18				3 1		
	5 /	7,10				5 V	477	
Ĩ.	6 /					61		
	8 4	·		-	JLAP	8 1	130500	
1022	9 1/		296?		7-91-	9 1-	1/33	
-	10 /				168	. 10 1	4:40000 PIZE	34
	11 /				· (E)	11 1	35 STC 55	Li
	13 1	'			Dec S	13 /		
	14 1/			7	APIN S	2L17954 L		
	15 1				SEGAP.	15		
2 Lines	16 17	2.45				16		
	18	3:43			V	18 4	333EC 5	TP11
	19	-		LOST OSC.	PWR	19 1	30 5 = 1 - 04 151	
	20	~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~		CONTINU	~_/	201	320 200	_
	21 1	3:52	1		095 281	21 1	FIRE "SEC. CLA	<i>ک</i>
3 LARS	L				SAC	23 2	68PSI	
***	241			V -		24 /	- OpenALINA)
		op: 3:5		200		FROM	31.6 SEC 2010 FT	
	3raps+ 3:	2300 to 2	24200			5:09	STA: 3/8	
						3LAPS+	127 10 319	
) }	TIME: 4	7 min	ë		3180	2	320/280°	
		min. ST	OP.		19100	<i>?</i>	18510/8101	
9. 9.	12	7=36.9	mel		220	TIME	58 min.	
9.	12 ×	7 3 3 7			9,12	2.42	min STOP	
	.59mL 0157	·.	II-88		33,86,		32,9mph	

SOAC #1 L-O CAR TEST RUN 080

- INSTRUMENTATION CHECK-ACCELE RATION & BRAKING RATES

REC.	MODE	DIZ- EcT.	ACCEL. ACCELER- OMETER	SPESSO- MINTER	DUTY CYCLE NUMBER
239 240 -	BPOKE ACCEL	FWD REY	-2.05 2.45	-2.93 2.67	
2.53 250	BRAICE ACCEL.	REV FWD	-3.05 2.80	-3,00 2,18	
STOPPING 2010	BRAKE	FWD	AVERA -2,30 -2,50 -2,15	-2,22 -2,47 -2,13	#5 #11 #24
DIST,	, .	h			LEV. TANG, TRY

NOTE: BASED ON ABOVE DATA THE
ACCELEROMETER APPEDRS TO BE
IN ERROR FOR FUND-BRAKE &
REV-ACCEL ON COR NO. 1. DATA
VALIDATED BY SPEEDOMETER TRACE.
THIS IS ON INSERMITTONT PROBLEM
& SOME DATA IS OK.

MAX. RÉCORDED BRAKE TEMPS: 320° TREBO
FRITOU CYCLE #24. 380° RIM

— COR MEETS BRAKE SPEC. RATE & DIST. ON
FINISL STOP. 11-89

SECTION 2. RIDE QUALITY TESTS

SOAC TEST RUN OII

11/30/72

TIME

1:00 PM

CONFIGURATION

MotoRMAN:

CREW ;

CAR I CAR 2

105 KIb

REASON

CONTINUED RIDE QUALITY & NOISE DATA

METHOD:

- (a) Coperate Car around loop at contravent speed
- (C) Repeat 50 MAH RUN
- (d) when sotiefied with settings (3 or 4 runs)
 take ride data at other speeds 25,35,80

Noise Dara Interior at 80 MPH

Check or Walkthow Expansion joint at Low 339+30

DATA:

* SPEED LIMIT; TEST CANCELLED

057		
TIME:	START (STO) 11:20 12:	30
· - · · · · ·	,	ain Twck
Section of the sectio		
AROMETRIC RESSURE	AMBIENT A TEMPERATU	START
ER B BWS	CARL SH (REEGIE PA	(4314
BALLAUEY (ROUND CONTROL REAR MONITOR	ER DEK HASKE
	TIME: SIN TESTS SINS TEST DOTA FOR RESSIRE RESSIRE RALLOUX POSCIOUS	TIME: START STORY OIN TESTS - OMS TEST AND OBT DOTA FOR GSI ROMETRIC AMBIENT A TEMPERATURE RESSURE MUTORMAN GONA BALLAUX CROKED CONTROL DESCRIBE CONTROL

VEHICLE CONFIGURATION.

CAR I CAR 2 105 L LB

THE FOLLOWING PAGES CONTAIN THE METHOD. 'QUICK-LCOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

- · INSTALLED TRUCK INGTON INSTRUMENTATION
- . NO CHANGES TO CORS FROM YESTOLONY

A. married		7200 056	**************************************	ASMS TESTS.
Chatter, a.	Direct	= 2 (HIDEN)	rev)	カルション : CAB Nº
Section 1	~	-		
Charles and the Party	_ * 72EC 2º	SPERS	SPELD IND	No commune imp
Section 1				
The second second	1135/113)	3	3	1200
Eg treespect		15	15	15 15/16
A Company		75	15	25 26/25
A Section Section	1140	35	35	35 35/36
The second second	1143	5 <i>0</i>	150	. 50 51
and the State of the same	1145	סר	70	70 70
A Complete C	1147	80	පිට	50 79
Townson I'V Lange	1150	10	70	70 76
A STANDARD	1153	९ ०	50	50 50
Sand Mind Street	1154	35	35	35 35
		25	٧<	25
2		15	14	15 13
	\	73	_	3
A Commence of the Commence of				1215 70 70
				1216 70750 50
A Marie Carlo Marie Marie	- 🐠		II -9 3	
Par Alleria				
de	ļ			

TRACK SECTION	TEST STATION	Re F
/	1	205
II	2	230
II.	3 9	250
	36	315
世	49	365
	46	428
I	5	467
叮	L	490
	<u> </u>	

SOAC TEST RUN	062		
DATE: 3た8/73	TIME:	START STOP 3:50 5:30	
NEZ (I+D)		CURRENTS o	7~11 W1
	ROMETRIC SSURE	AMBIENT AIR TEMPERATURE	START
TEST CONTROLLER OPERATIONS DIRECTOR TROY DATA CONTROLLER INSTRUMENTATION ADDITIONAL PERSONNEL SUS	GRO REA	ORMAN GARY DAY UND CONTROLLER _ R MONITOR DICK 14	
 VEHICLE CONFIGURATION: (CAR 1 (CAR 2)	2 112	

THE FOLLOWING PAGES CONTAIN THE METHOD, 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

· PRIMOVED 3" SPACER BLOCKS FROM EDCH
TRUCK ON Nº 2 CAR,
· DOJUSTED SPEED SENSOR CARS TO SPEED TO TRY & ELIMINATE

105K LB

Nº Z CAR FUO TRUCK

		4. ,				•
	MODE	MOMITON	V	·I	1/1 BASIC SPORT	
		1440		_1	↑	
	ר ר	4650	1,67	268	1	
		600	1,65	660	T	
		300	1,74	296		
	·	150	125	100	7	
		125	,14	56	1	
	B	טרר	2.20	850		
		S*0	5172	900		
-		800	7.25	900		
	D	350	185	340	1	
		410	1.04	416		
		510	1.40	560	1	
		500	1,33	532	1	
	·	650	נהו	692	1	
		600	1,65	660	1	
	÷	750	2.12	848	1	
		200	.43	172	1	
		.100	610	40	1	
	3	200	. እክ	120	^	
		3,000	172	288		
		400	1,01	404	,	
		90mg	1.28	5/2		
		७५०	186	744		
	7	San	1111	888	1	
	,	750	عبت	808	1	
		725	7.01	804	114	
		Seri	221	884		
		500	1.33	532		
		400	57	<u> 3</u> 88	114	
			•			•
			11-96			

N°Z H-D FUD TRICK REN (CCW) 3128/73

0	Mary	Man-Ton	V	J	1/1 BASE STEED	
·	1937	11000	(214)	35		
T	,	જ્જન	2.19	876	1	
		500	1.31	534	↓	
		600	1.45	660	1	
		700	1,54	792	1	
		200	₹.37	148	1	
		300	กน	28 8	4	
		400	1,05	480	+	
		110	115	60	1	
		€ 50 m	٠٢٧,	168	1 1	
		3000	กร	300	1	
		400	Post	416	9	
	į	500	1,35	540	4	
		740	2.09	836	1.	
- 1	B	760	2.10	840		
0		100	. જા દ	32	- Landaneseye	
	İ	<u> </u>	139	156		
		300	רר	302		
		400	ماه ۱۰	424		
		500	1.37	548		
		1,000	1,64	656		
		750	しいり	840		
					1	
•			,		·	
			II-97			

MODE	MEMITER	V	I	4/4 Bost 58 (20)
	Antonia and antiques control to the second and antiques of the second and the sec	A Charles and a second s		and the same and t
D	100	•07	28	4
	150	-10	40	₹.
	0न्द्र	.16	64	
	300	ر در.	148	4
	400	15°C	232	1
	500	.81.1.78	324/3,12	1
	60-0	1.03	412	↓
	500	1.42	565	+
	750	1,35	55'L	↓
	125	1,3%	352	
	735	1,40	560	↑
	600	1.14	456	^
<u> </u>	100	102	8	1
•	200	126	104	1
	30-0	146	184	1
	400	.५४	272	8 A
	510	,52	368	1
	625	1.10	440	^
3	150	٢٥٠,	16	
	೭೮೮			
	300	.42	168	
	400	,66	264	
	500	-४७	344	
	760	1,35/37	५५०	
	740	141	564	
D	800	1,40	566	1
المعاملة الماداء المعاملة المع	740	1.33	534	l
B	car	.27	108	
	600	1,08	432	
•				
-		II-98		
	i i		1	

Nº Z CAR (A-D) AFT TRUCK DEN (CCU)

2/24/13

MODE	MONITOR	Y	I	1/1	BASE	SPEED
				1		
D .	140	,06	24	1		
	200	,27	108			
	300	.53	217	1		
	400	יש/אַרי	300	L		
	500	19 5/.53	350	1		
	600	1/14	456	1		
	ン やつ	1,42	568	1		
	800	1,60	७५०	1		
	750	1,43	572	114		
	विचे	103	12	1		
	w	.22	' '১'	1		
	300	.42	168	1		
A	५००	.63	252	} ^		
	500	184	336	1		
	600	1,06	424	§ A		
	740	1.36	544	A		
B	840	192	568			
	10-0	.03	12	Í		
	े	118	15	. ∳ •		
	300	.40	160			
	450	162	268			
√` -	500	.50	320			
	600	1.03	412			
	70-0	1.38	452			
	<i>7</i> 0~		325			
						,
						,
						;
•						ı
W.						
		II-99		1		

SOAC TEST RUN	063	
DATE: 3/29/73	TIME:	START STOP
• OBTAIN	DOD! WONAL S	LURCH FIX NOE QUALITY DATA LE TEST TECHNQUE
WEATHER CONDITION:		
WIND SPEED DIRECTION	BAROMETRIC PRESSURE	AMBIENT AIR START TEMPERATURE STOP
CREW: TEST CONTROL	LER BOB BRUSH	4
OPERATIONS DIRECTOR TO DATA CONTROLLER WALT INSTRUMENTATION	PALLMEN G	OTORMAN GARY PAVIS ROUND CONTROLLER EAR MONITOR DICK HASKEL SSI), TED PETTEAM, 1057
VEHICLE CONFIGURATION	: CAR 1 CAR 2	
105 K	LB.	

THE FOLLOWING PAGES CONTAIN THE METHOD, 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

OPEDMETER READING 3100 MINES,

938 - DELLE FILM STOP - SI'IN - SLIDE

NO SPIH-SLIDE LITE INDICATION

942 - LURCH CHECK 7

NO LURCH

944 - 11 11

- ME CALIBRATION OF SPECIAl SENSOR CARDS (NEZ COR)
- · SLIP-STIME FILIGHT IN COP ! INT WORKING.
- " HOILM IS AWALL NEEDS TO BE LOOKED

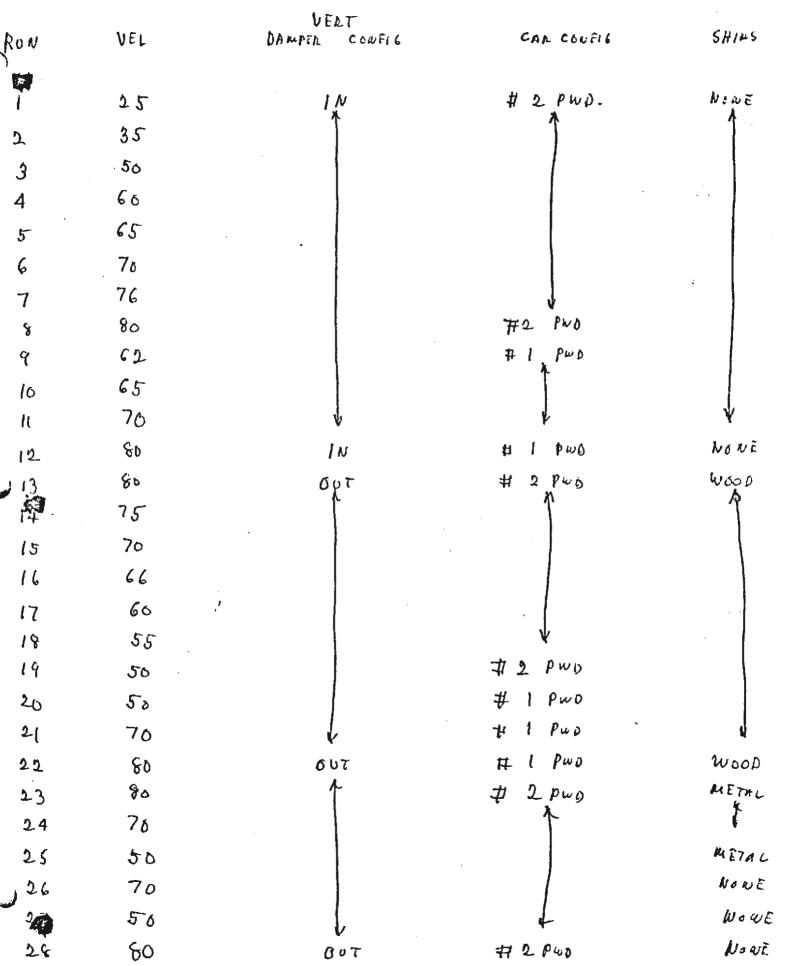
SOAC TEST RUN	064	
DATE: 3/29/73	TIME:	START STOP 3:50 4:35
<u> </u>	QUALITY DATA 3" SIAIM REMI	
WEATHER CONDITION:	Snowing -	
WIND SPEED DIRECTION	BAROMETRIC PRESSURE	AMBIENT AIR TEMPERATURE STOP
CREW: TEST CONTROL	LER BOB TSUSJA	_
OPERATIONS DIRECTOR		ORMAN GARY DAVIS
DATA CONTROLLER INSTRUMENTATION		UND CONTROLLERR MONITOR DICK HASKEL
ADDITIONAL PERSONNEL	GUS KRAUSE	
VEHICLE CONFIGURATION	: CAR 1 CAR 2	
105 K	_73.	
		- · · · · · · · · · · · · · · · · · · ·

THE FOLLOWING PAGES CONTAIN THE METHOD, 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

RATE DATE HE REQUIRED.

	•	3 T.M. A.W. LESSING CO. (1997)	eranueranani, .	<u>Vic</u>	ATHER CONTINUE
SOAC	TEST RUN	090			WIND SPEED
DATE: 4	26-13	TIME	START 14-1 (11500 1840	DIRECTION
r e e e e e e e e e e e e e e e e e e e	VIBRAT V LUAY 51		22 1115		AMBIENT AIS TEMPERATUR
HYDEN-INST	LARI	BODY	AR 1 CAR	Signalar West Adventisis and sery-	LLA FUD AX
	DEM.	T CONTROLLER			
	PPERATIONS DI DATA CONTROLL INSTRUMENTATI	RECTOR HE ER SPENSON ON KRAL	ZCEY CED MIMCIC 15 E	MOTORMAN E GROUND CONTRO REAR MONITOR	
	ADDITIONAL PE	(1) NE ST	N/E	NO NOISE	n Moi se
•	and the second second	6			75,80-SECTI
2 5	PEED SU (SEC)	UEEP-D	LDEAD C	AR - 50	, 60, 70,80 (0, 70,80
	PANTO C		PEEDSU	150 75	,60,65,70
4 5	PEED SI	NEEP- 2	5ste	SECT 19	

SOAC 092,091,090



II-104

	SOAC TEST RUN 091	WIND SPEED
	DATE: 4-27-73 TIME: START STOP 11:00 12:35	DIRECTION
	PURPOSE: 1. VIBORATION INVESTIGATION	AMBIENT AIR
,	2 WAYSIDE MOISE.	TEMPERATUR
	VEHICLE CONFIGURATION: CAR 1 CAR 2 VERT DAMPER-DISCONNECTED- MA SHOCKS - LOCKED OUT - HY I P WITE Problem notresolud	BOTH CARS
_	CDEM.	•
	DATA CONTROLLER VIAMINGIX GROUND CONTINSTRUMENTATION KRAUSE REAR MONITO	
	ADDITIONAL PERSONNEL CURE, YOUGAS	
•	1 STEED SLUTEP- 75,755,50, 60/65/-	70, 75, 80
	2 SPEED SWEEP- MA .UNLOCKED-5	
V	4 UNCOUPLE - RUN HY DEN	80,
6	5 SPeed sweep - 1/2 Powered -	
_ 	. II-105	•

		†OSMANOHOLIPPIN	AND DESCRIPTION OF THE PERSON	onemany .	111	Alita Garage	
:	SOAC TEST RUN	0	12			WIND SPEED	**************************************
DATE:	4-27-73		TIME:	5TART 15:30	10:45	DIRECTION	
PURPOSI		PATION			1011.	AMBIENT	ATR
	2 WA	YSIDE	Mois			TEMPERAT	
11 s	VEHICLE CO	IT I CUDATION	CAR 1	CAR 2		<u> </u>	
•	/ DTIE		MYFD-	DISCO	MYDE HYDE	ED-BOTH	CARS
	"Pwi	re Pro	CLER	7 -	*		
•	OPERATIONS DATA CONTR	TEST CONTRO	HAZLE LAMINO	✓ MC			<u>L</u> <u>C</u>
	ADDITIONAL	PERSONNEL			•		· ·
7	SPEED SE	UECP.	- VIB	- 50	55, 60,	65,7075	80
20	WAY 51-DE	Equipo	ENT	HOISE	- PLAT.	FORM TES.	<i>7</i>
3	SECT I -	50 Power	a, 2.5	COMST	, 50 104	UCK , 35 Co.	15T
4	SPEED 50	WEER M	7 50	scy z	7 777	TO E W	_
	70 MP	4,30	7, 8	OMPI			
•	Souplin C 3 /3	Rrobler					
	C S /3/	lake (14 / C	or-	•	•	

11-106

					· .	<u>n=min</u>		<u> </u>
	<u> </u>	C TEST RUN	129				ND SPEED	;
ل	DATE:	7/5/73	TII	ME:	START STOP	. 30 DI	RECTION	
	PURPOSE:	CAR NO		ECK	RUN	90+	AMBIENT TEMPERA	
		· · · · · · · · · · · · · · · · · · ·			·			
1 .		VEHICLE CONF					•	
y		90	000 #	G. W	J.			•
•			-			andre grant control and an artist and a		• • •
	-	CREW:	ST CONTROLLE	R <u>A</u> .	Vocimera			<u> </u>
		·					au Day	
(•	OPERATIONS D DATA CONTROL INSTRUMENTAT	LER <u>G</u> E	WE F		CONTROLLE	R <u>Filtrage</u>	وعوز العراق محراء
		ADDITIONAL P	ERSONNEL					
		•	-					
		HAW	D BRAK	E A	CEKENSE	OK		•
		VIBRAT	100.	CHEC	K W	acre The	2006 Fr	•
		40			CHT@ CAB	END.		
		45 50			CIGNIZ © CI		-	
•		55 ₹60	OK	•	. •		· :	
		65						
		70 75					1	
			O VIBR	HTION	, CAME	IN 01	U SECT	- I
			WAS	400	AL TO	574	670	
	KTE CA	•		~ " N	R MOTOR	COCON	14	•
	ACTION	116145	,	II-	107			

- (1) MA TRIP THROUGH GAP NO INDICATOR
 LIGHT- RECYCLED NOK AFTER

 RESET.
- D FWD TRUCK ANALOG BRAKE VALVE LEAKING - REPLACE WITH SPARE
- (3) INSPECT REAR END UNDERCAR
 FOR NOISE (IMPACT OR LOOSE PART)

	SOAC TEST RUN	WIND SPEED
DATE:	7/5/73 TIME: START STOP 15:30 17:00	DIRECTION
į	RIDE QUAL CHECK AFTER 10 BEEF UP	AMBIENT AIR TEMPERATURE
	VEHICLE CONFIGURATION: CAR 1 CAR 2 ENDOSO START METER 5954 METER 5996	
	TEST CONTROLLER F. Thompson OPERATIONS DIRECTOR A Doilwacke MOTORMAN DATA CONTROLLER Gue Kause/S Shapiro GROUND CONTR INSTRUMENTATION PACCAMANN REAR MONITOR ADDITIONAL PERSONNEL 20RED W. Cobb Dave B	P. HASKILL
	Engineering Strumentation Check	out.

SECTION 3. NOISE MEASUREMENT TESTS

SOAC TEST RUN 0005

DATE | 11-16-72

TIME

CONFIGURATION

CAR 2 RUM SINGLE @ 105,000LB

LOW DENSITY HIGH DENSITY

REASON

ACCEL, DECEL, MOTOR FLASH OVER OBTAIN NOISE

METHOD: SET -UP DISTANCE COURSE STA 298 TO STA 338

I RUN CAR FWO DIRECTION TO VMAX EVALUATE MOTOR FLASH OVER

2 RUN CAR AFT DIRECTION TO VMAX EVALUATE MOTOR FLASH OVER

3 ACCEL CAR 20, 40, 60 MPH RECORD TIME TO SPEED AND DISTANCE

4 DECEL CAR TROM 20, 40, GO MPH RECORD TIME AND DISTANCE BLENDED BRAKE, DYNAMIC ONLY

DATA: FRICTION ONLY

5 Moise DATA:

Three Interior locations @ accel, 0, 20, 40, 60 MPH Two Exterior Positions @ 0, 20, 40, 60 MPH passing All Equipment operating

INTERIOR NOISE LEVELS - SOAC#1; LOW DENSITY CAN
'A' WEIGHTED SOUND LEVEL - dbA

CAR @ 105 K/b; empty

	All	SOUITMENT.	OPERATIN	<i>5</i> -	1
		FRONT OVER THITEK	CENTER	REAR Over #2 Tax	
	Acceleration	૯૩	62.5	6 5	*
SENTE D	0	62	61	64.5	
(EAR	25	63	61	64	
LEVEL)	35	63	61	65	
	50	65	63	67	
	70	72	65	70	
	Acceleration	L 3	62.5	66	*
STANDING (EAR	0	62	62	65	
TEAET)	25	63	61.5	64	
	35	63	62.	65	
. <i>.</i>	50	65	3ما	67	
	70	72	65	70	

11/16/72; Run 005

Only two exterior
Nonco level data

points obtained

this data:

5 themen; 3 above

rail car at

OMFH 84dbA

80 MFH 114 ab A

· Effect of track locatu

* Acceleration Noise levels are a function of speed

RONG 'S

INTERIOR MOISE LEVELS - 50AC TR

14' Weighted Sound Level - dbA

Car of 105 Kib

. HEHTS OFF

O KIGHTS ON

		FRONT (TRK#1)	CENTER	REAR (TRK#2)
	ACCLERATION	(3) (3)	(23) Lat 62.5	(p) (p)
SEATED	2625	·	(C)	64)
(EAR LEYEL)	4030	(S)	(63)	(1)
	70	(1) 26 J	(S) (2)	70 To
	0	29 CD	(a) 42 (b)	(4.5) (0.4)
	ACCELERATION	. દેમ (લ	625) 50162.5	50 G
STANDING	202	(B)	(5:19)	(t)
(EAR LEVEL)	35 20 1	(S)	(2) (3)	(52)
•	06	(E) 28	(P) (P)	16 (0)
	0	20 (2)	(2) 62 (4)	65 65

EXTERNAL NOISE LEVELS - SOAC # /

'A' Weighted Sound LEVEL - dbA

Car at 105 KIb

RUN 88 5

	SPEED (MPH)	MAX. Sound LEVEL
	0	
50' from	20	•
5' Above Rail	4c	
	60.	
,	0	84
5' from Car;	230	904
35' Above	40	>.00
Rail	6160	Ç/O
	80	1/4

SOAC TEST RUN 1010

DATE 11/29/72

TIME

Motorman

CONFIGURATION

Grew

(a) Car 2 Drusing Grain CAR 1 CAR 2 105Klb (b) Car i slove

REASON

(a) VIP Tour (b) Spech Remitting, Rude Quality

9:30 to 10:30: Check aperation & walkthan

VIP RUN

Un couple, remove #/CAR To Born

(b) Run loop at Steady speeds with ASMS. 25, 35, 50,70

Record: Ride Guality Noise Data

TRACK

UP. MAIN ARESOIRIUR VALVE FROZEN SLEAKING.

CLEARED WITH HEAT, VALVE NEAT NOT OR DURING LAYOVER DUETO LACK OF BATTERY CHARGING ROWER IN BARN.

& RUNS FOR CHELKOUT VIP RUN COMPLETED SHUTDOWN @ 12 NOON

(b) Runs in AFTERNOON II-115

/ CONT. COMMENTS OVER)

NOTE:

Roul Switch at man junction is losse & bent. Cause uncertain. Must not pass thru switch at more Tham 15 MPH and must De un ((w direction

P.M. Pide Quality & Noise Date started

25, 35, 50, MPH; Tripped on shutdown at 80 mPH. on return to start point new problems noted. Shutdown at 2:30 PM.

INTERIOR MOISE LEVELS - 50AC #2 'A' WEIGHTED Sound Level - dbA

Car at 105 KIB; EMPTY; RUN BACKWARDS (CCW) 11/29/72 RW#10

		4	01.00	
		FRONT (TRK"I)	CENIEK	KEAK (TKK Z)
	ACCELERATION			
SEATED	000	53	52	68
(EAR. LEVEL)	250th	63.5	(53 (63	&9 89
	80			۱۲
	0		79	60
	ACELERATION			
STANDING	20	63	27	65
(EAR LEVEL)	40.60	†9 79	63 63	67 106
	$\mathcal{B}_{\mathcal{O}}$			ال
,	0		25	49

EXTERNAL NOISE LEVELS - SOAC #2 'A' Weighted Sound Level ~ dbA Car at 105 KIb

	SPEED (MPH)	MAX. Sound LEVEL	
50' from Cor;			
5' Above RAIL			
	20	84	93 3
5' from Car;	40	90 91	
5' Above	60	93	92
Rail			, - -

SECTION 4. EMI TESTS

SOAC TEST RUN	066		
DATE: 4-2-3	TIME:	START STOP	
PURPOSE: RERORD SHUNTACURRENTS TAKE EMI DATA		FROM CURRENT	SENSOR
WEATHER CONDITION:			
WIND SPEED DIRECTION	BAROMETRIC PRESSURE	AMBIENT AIR TEMPERATURE	START
CREW: TEST CONTROL	LER R. PARICE	Z_	
OPERATIONS DIRECTOR	T. BOMAR	OTORMAN LARY	DAVIS
OPERATIONS DIRECTOR	IFF HALLAPS PEN	GROUND CONTROLLER _ CER REAR MONITOR <u>DICK</u>	HASKEL
ADDITIONAL PERSONNEL			
VEHICLE CONFIGURATION	: CAR 1 4 CAR 2		
105	K LB C	ARS AT ORIGIN	urc HT.

THE FOLLOWING PAGES CONTAIN THE METHOD, 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

COAC	TEST	DHM
SOAC	TEOT.	<u>nun</u>

06 7

DATE:

4-7-3

TIME:

STOP 3,30 START 2:00

PURPOSE: RECOLD CURRINTS FROM EVERENT SHUNT, HALL LURRENT SENSOR & ARM MURE CURRENT SEASON TAKE ETAI DASA

WEATHER CONDITION:

WIND SPEED

DIRECTION

BAROMETRIC PRESSURE

AMBIENT AIR

START STOP

CREW:

TEST CONTROLLER F. THOMPSON

OPERATIONS DIRECTOR T. BOMMA MOTORMAN G. DAVIS DATA CONTROLLER CHARLIM, BECKILL GROUND CONTROLLER INSTRUMENTATION CHARLES SPENCER REAR MONITOR D. HOSKEL

ADDITIONAL PERSONNEL

VEHICLE CONFIGURATION: CAR 1 4 CAR 2

105 K LB CARS AT OKIGIANE 145.

THE FOLLOWING PAGES CONTAIN THE METHOD, 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

SOAC TEST RUN	068		,
DATE: 4-3-2	TIME:	START STOP	
PURPOSE: TAKE	EMI DATA		
WEATHER CONDITION:			
WIND SPEED DIRECTION	BAROMETRIC PRESSURE	AMBIENT AIR TEMPERATURE	START
CREW: TEST CONTROL	LLER F. Tilly	1P5 NN	
OPERATIONS DIRECTOR	BICHIA	MOTORMAN 6 0A GROUND CONTROLLER REAR MONITOR 2 F	
VEHICLE CONFIGURATION	: CAR 1 ⊬CAR	2	
105	FLB		

THE FOLLOWING PAGES CONTAIN THE METHOD, 'QUICK-LOOK INDICATORS, TEST DATA AND RECORD NUMBERS FOR RECORDED DATA.

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APPENDIX III

RIDE QUALITY REPORT D174-10025-1

		-
		•

Engineering Division

THE BOEING COMPANY

VERTOL DIVISION . MORTON, PENNSYLVANIA

CODE IDENT. NO. 77272

	NUMBER	D174-1002	25-1			
TITLE	SOAC RIDE	QUALITY	IMPROVEMENT	ΓР	ROGRAM	
	FOR LIMITATIONS CONTAINED IN T OF THIS D	HIS DOCUMEN		DIST	RIBUTION	
MODE	L	C	ONTRACT			
ISSUE	NO	_ ISSUED TO	:			
PREPARED BY	R. Vlamino R. Vlamino S. Shapiro	k ∱-	PREPARED I		T. W. Harl T. Herbert Engineer of S	
APPROVED BY	D. Bevan	1	PREPARED I	BY	Engineering	Division
APPROVED BY	J. O'Leary	+			Asst.Engineer GSI Inc. Engineering I	Division
APPROVED BY	A. Vollmer	ke ke	APPROVED I		K. Jackson Director of F GSI Inc.	

ABSTRACT

A ride quality test program on the State-of-the-Art Car uncovered vertical vibrations near 80 MPH. Shake tests of the SOAC identified the major vertical modes of the primary car structure and significant secondary structure. The secondary structure supporting the motor alternator was analyzed and modified. Subsequent shake tests and ride quality tests verified that the structural changes produced the desired improvement in ride quality.

KEY WORDS

Rail Vehicle Dynamics Ride Quality Test Urban Rapid Rail Vehicle State-of-the-Art Car



LIM	TAT	IONS
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All revisions to this document shall be approved by the above noted organization prior to release.

FORM 46281 (3/67)



			-	ACTIVE	SHEI	T RECORD					
		ADD	ED	SHEETS				ADI	DED	SHEETS	
SHEET	REV LTR	SHEET	REV LTR	SHEET NUMBER	REV LTR	SHEET	REV LTR	SHEET	REV LTR	SHEET NUMBER	REV LTR
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(Longitudinal Stiffening)

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SUMMARY

This report presents the results of a vibration reduction program conducted on the State-of-the-Art Car (SOAC) to improve ride quality. The testing included two ride quality vibration surveys, two vehicle shake tests, and a wheel concentricity test. All tests were performed at the DOT High Speed Ground Test Center (HSGTC) during the period April through July 1973.

This program of testing and analysis indicated the structure supporting the motor alternator should be modified. This modification was designed by Boeing Vertol and installed on the vehicle at HSGTC. A shake test verified the predicted structural response and a follow-up ride quality survey substantiated that the objectionable vibrations had been eliminated.

1.0 INTRODUCTION

During acceptance testing of the SOAC on the Urban Mass Transit Authority's (UMTA) 80-mph test oval, passenger observations indicated a vertical ride quality vibration problem existed on the vehicle. The most noticeable vibration occurred near 80 mph, although car body vibrations were evident at other speeds. Vibration near 80 mph was characterized by motions of the floor, ceiling panels and seats. These observations and passenger comments precipitated a diagnostic and corrective program which included: a diagnostic ride quality vibration survey, vehicle shake test, analysis, subsequent structural modification, verification shake test, ride quality survey, and a wheel concentricity test. These tests were performed at the HSGTC, Pueblo, Colorado, in parallel with the acceptance testing.

The vibrations of interest were at frequencies higher than are normally treated by a truck builder; that is, higher than the rigid body suspension frequencies. However, the services and test equipment of the truck supplier (GSI) were used in the diagnostic testing. Since the frequency of vibration was associated with car body flexible modes, St. Louis Car Company requested the assistance of the Boeing Vertol Company to conduct the diagnostic testing, associated analysis, and detailed design of the necessary structural modifications.

2.0 INITIAL RIDE QUALITY TEST

2.1 PURPOSE OF TEST

The main purpose of this diagnostic test was to provide a quantitative evaluation of any vibration problems of the vehicle and investigate in detail the observed 80 mph problem.

2.2 TEST EQUIPMENT

Six Statham linear accelerometers of the unbonded strain gage type were used to record the ride quality characteristics of the vehicle. Three vertical car body accelerometers were used: one located over the bolster (Station 108); one located over the center of the car (Station 450); and one over a point in between (Station 225). An exploded view of the SOAC identifying the station numbers of the vehicle is presented in Figure 3.

One longitudinal accelerometer was used and placed in the car over the bolster. The other two vertical accelerometers were located on the truck bolster and on the No. 1 traction motor. Data were collected on a six-channel Honeywell Visicorder Model 906-C. All of this instrumentation was supplied by General Steel Industries.

2.3 TEST PROCEDURES

The facilities at the HSGTC were used for this ride quality test. Data were recorded on UMTA's 80-mph test oval, traveling at various planned speeds with the car moving in forward and reverse directions over track section 1, Station 160, a straight and level track with wooden ties and welded rail. Figure 5 identifies the track section and station number. Data were collected on the No. 2 SOAC, the high density car, at the 90,000 lbs. light car weight.

All data records were of at least 10 seconds duration and were reduced manually. Visual observations were made of the interior of the car throughout the duration of the test to detect any other vibration problems which may not have been recorded by the instrumentation available.

2.4 RESULTS OF TEST

The results of the ride quality test provided a quantitative substantiation of the severe vibration problem evident near 80 mph in the SOAC. Figures 1 and 2 show a summary of car body vertical vibration data at 25, 35, 50, 60, 65, 70, 76 and 80 mph. The data in both figures are presented for three different car body locations: at the car centerline over the forward bolster (Station 108); at the center of the car (Station 450); and at a point in between (Station 225).

THE BOEING COMPANY

Figure 3 shows an exploded view of the SOAC vehicle illustrating the car body locations under discussion. Figure 1 presents the vertical vibration data as g's versus frequency plotted against the SOAC goal. These data show there are two frequency ranges: 1.2 Hz to 1.7 Hz and 7 Hz to 15 Hz. These bands correspond to rigid body suspension modes and car body flexible modes respectively. The worst vibration levels occur in the center of the car at 14.5 Hz where there is a band extending from .10 g's to .26 g's. Figure 2 presents the same ride quality data as Figure 1, except the g levels are plotted against speed. This includes only data taken from the higher frequency range (7 Hz to 15 Hz).

Observers commented the ride was generally smooth but defined three speeds with particularly noticeable vibration. A mild vibration was reported between 35 mph and 45 mph and the data of Figure 2 show some evidence of this at the mid-car location. More noticeable to observers was the vibration near 64 mph which is seen in the data of Figure 2 at each of the three car body stations. A severe vibration involving amplitude modulation (beating) was evident near 79 mph.

Car body vertical accelerometer waveforms indicated a high amplitude vibration with a 9-second beat was present in the data measured over the center of the car (Station 450). This beat produced an amplitude modulation of the vertical acceleration between .10 g's and .26 g's at approximately 15 Hz at this location. A sample accelerometer trace showing the beating that occurred is shown in Figure 4A.

The data of Figures 1 and 2 indicate that, in the higher frequency ranges, the accelerations exceed the SOAC goal. In fact, observers were satisfied with the ride quality over the whole speed range with the exception of 64 and 80 mph. An explanation of this acceptance is that the manual reduction of response data may have resulted in incomplete separation of frequencies and consequent "lumping" or summing of acceleration values near selected frequencies. This resulted in the large test values shown at the higher frequencies.

Part of this vibration survey was devoted to determining the effect of the secondary suspension vertical hydraulic dampers on car body acceleration levels. A comparison of vibrations with dampers connected vs. dampers removed for car body longitudinal, mid-car vertical, motor alternator vertical, traction motor vertical, car cab vertical, and truck bolster vertical vibration levels, is shown in Figure 6. It can be concluded that except for car body longitudinal, the levels in the higher frequency range were reduced with dampers off.

The effect of car body-mounted equipment was considered in light of the findings of NASA TN D-6735 "Dynamic Responses of Railroad Car Models to Vertical and Lateral Rail Inputs" by Sewall, Parris, and Darling. The largest of these is a flexibly-mounted motor alternator supported on secondary structure at midcar. To determine the effect of the motor alternator suspension frequency on car body vibration levels, shims between the motor alternator mounting brackets and the motor alternator hard points were also evaluated. These shims were intended to lock out the motor alternator isolation mounts. Two shim materials were used: wood and steel.

The results of this testing are also shown on the lower section of Figure 6 and indicated that car body vibration levels were significantly lower with wood shims and significantly higher with steel shims. The predominant frequency content of the waveforms analyzed was approximately 15 Hz for this 80 mph test condition.

2.5 CONCLUSIONS

The results of the ride quality test provided a quantitative substantiation of the severe vibration evident near 80 mph in the SOAC. Mild vibration was reported between 35 mph and 45 mph and near 64 mph. Car body vertical accelerometer waveforms indicated a high amplitude vibration with a 9-second beat was present in the data measured over the center of the car near 80 mph.

Testing to this point did not provide an understanding of the measured ride quality results. In addition, the frequencies of vibration observed in the test data could not be correlated with any car body vibration modes since there were no analytical predictions of car body flexible modes and frequencies. To understand the dynamics of the vehicle in the frequency range above the rigid body suspension frequencies, it was concluded the best course of action would be to perform a shake test of the SOAC.

3.0 INITIAL VEHICLE SHAKE TEST

A clear definition of the dynamic characteristics of the vehicle was necessary to understand the results of the ride quality vibration survey discussed in Section 2.4. In addition, many of the physical parameters required for an analytical study of the SOAC were not readily available and could be expediently determined from measurements recorded during a shake test.

3.1 PURPOSE OF TEST

The purpose of the initial SOAC shake test was threefold:

- 1. Determine the car body vertical bending modes and frequencies.
- 2. Determine truck modes and frequencies.
- 3. Determine the effect of the motor alternator on car body vibration.

3.2 TEST EQUIPMENT

Six Statham linear accelerometers were used to record the dynamic response of the test car. These were mounted to rigid metal brackets which could be conveniently moved and attached to the structure with "C" clamps or secured to the car body floor with lead weights. Excitation forces were supplied by an electric-driven Lazan Model LAl Shaker. Accelerometer outputs were recorded on a six-channel Honeywell Visicorder Model 906C. This instrumentation was supplied by General Steel Industries.

3.3 TEST PROCEDURES

The test was conducted at HSGTC on the No. 1 SOAC (low density car) at the 90,000 lbs. light car weight.

Car No. 2 had been used in the initial ride quality test but was not available for these shake tests. The cars are identical structurally and the results are applicable to both.

During the test a shaker was used to apply a sinusoidal exciting force to either the car body or truck frame. When exciting the car body, the shaker was attached to the anticlimber at the R end of the car. Both a vertical and longitudinal shake of the car body were conducted. Figures 7a and 7b show the vertical and longitudinal shaker configurations. For truck excitations, the shaker was attached with clamps to the underside of the truck frame cross transom.

For each test configuration, frequency sweeps were obtained over the band extending from 6 Hz to 20 Hz in .5 Hz increments. When a natural mode was located the shaker frequency was finetuned to determine the frequency and amplitudes at resonance. In addition, detailed probes of the structure were carried out to determine the mode shapes. No attempt was made to shake the car body at the rigid body suspension frequencies because of the limited force output of the shaker at low frequencies.

The characteristics of the Lazan Model LAI shaker is shown in Figure 8. The force output of the shaker increased with the square of the exciting frequency. To obtain data which would be representative of a constant force input, all data were scaled to a 500-lb. input force. Dynamic time histories were obtained but no attempt was made to determine the phase angle between pickups except at the natural modes. After the frequency sweeps for a particular configuration were completed, these plots were studied for resonant amplitudes. The test program defining shaker alignment, pickup locations, and excitation frequencies used in the shaker diagnostic testing was suggested by Boeing Vertol and executed by General Steel Industries.

3.4 RESULTS OF CAR BODY SHAKE TEST

Frequency response curves for car body vertical excitation at the R end of the car are shown in Figures 9 through 12. Pickup locations are at the R end of the car, Station 450, Station 673, and on the motor alternator. All data are for a vehicle weight of 90,000 lbs. and a shaker force of 500 lbs. A diagram showing the car body locations identified on these figures is presented in Figure 3.

A review of these curves indicates there are four car body flexible modes in the frequency range of 6 Hz to 20 Hz and they occur at 8.1 Hz, 12.25 Hz and two between 15 Hz and 15.2 Hz. The fact that there are two modes in the 15 Hz to 15.2 Hz range is not readily evident from examination of the frequency response curves. However, during the test, attemps to fine-tune the shaker in this frequency range proved difficult and it was noted there were actually two peaks within approximately .2 Hz. The data of Figure 9 taken at the R end of the car exhibit a large vertical response near 8 Hz which was later found to be the first vertical bending mode as shown in Figure 13. There is also a suggestion of a mode near 12 Hz and a major response near 15 Hz.

Figure 10, data taken at the center of the car (Station 450), substantiates the presence of a resonance near 12 Hz. Figure 11 is dominated by the 15 Hz peak and, as can be seen in Figure 13, the pickup was near the antinode of the 15 Hz peak and close to the node of the 8 Hz primary vertical bending mode. Figure 12 shows the response of the motor alternator itself is similar to the response of the car body floor over this component for the entire frequency range explored.

The mode shapes were determined as shown in Figures 13, 14 and 15. Detailed probing of the car body at the major resonances revealed the 8.1 Hz mode is the first vertical bending of the car body. The two modes between 15 Hz and 15.2 Hz involved localized bending of the three motor alternator lateral support beams and a higher order car body bending mode. Continued probing disclosed there was substantial bending of the motor alternator lateral support beams at approximately 15 Hz, but no bending was detected of any other equipment support beams. The mode shapes of the motor alternator lateral support beam and traction motor cooling fan support beam are shown in Figures 14 and 15.

As a result of the ride quality testing described in Section 1.0 it was evident the mounting of the motor alternator had a large effect on the mid-car body vibration. Therefore frequency response curves were also determined with steel shims between the motor alternator support brackets and the motor alternator hard points to lock out the isolation. These results are presented in Figures 16 through 19. From these data several significant conclusions were evident:

- Vibration levels at the R end of the car were not affected by shims but the levels at mid-car (Station 450) were increased by a factor of 2:1 at the 15 Hz - 16 Hz range when shims were in place.
- Vibration levels over the R end traction motor cooling fan (Station 673) were higher by a factor of 2:1 at the 15 Hz - 16 Hz range without shims.
- 3. Vibration levels on the motor alternator were not significantly affected by shims.
- 4. There was no effect of shims on the 12.25 Hz mode.

Additional curves were obtained by orienting the shaker in the longitudinal direction on the R car end and these data are presented in Figures 20 through 23. Pickup locations are Station 673 (vertical), motor alternator, R car end, and mid-car seat back. From these curves it was noted:

1. Figure 20 shows there is coupling between the longitudinal and vertical directions in the 12.25 Hz and 15 - 15.2 Hz modes. A longitudinal excitation of the car body results in significant vertical response of the structure at Station 673. This coordinate coupling was noted during the ride quality vibration survey, during which the 15 Hz vertical vibration was accompanied by substantial car body longitudinal vibration. The response was tabulated in Figure 6.

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- 2. The 12.25 Hz mode was found to be the motor alternator oscillating on its support beams in the longitudinal direction, moving out of phase with the car body. The frequency response curves are shown in Figures 21 and 22.
- 3. The mid-car seatback exhibits a resonance in the longitudinal direction at 15.4 Hz. This response curve, shown in Figure 23 is for an unloaded test. This seat, when empty, had been noted to exhibit large longitudinal motion.

3.5 RESULTS OF TRUCK SHAKE TEST

Shaking the truck frame vertically, the response curves shown in Figures 24 through 27 were determined. These data indicate the truck frame vertical frequency is at 9.8 Hz with the vertical hydraulic dampers off (Figure 24) and 10.4 Hz with dampers on (Figure 25). The validity of this shift is in question since it was observed that there was virtually no damper motion at the small shake test amplitudes and all relative motion between the truck frame and bolster was being taken up by the elastomer bushing at the upper end of the damper link. The effect on R car end vibration with and without dampers is shown by comparing Figure 26 (dampers off) with Figure 27 (dampers on). This data would indicate the car body levels are reduced by having the hydraulic dampers in place, but again this may be invalidated by the above-mentioned factors.

3.6 CONCLUSIONS

Four car body flexible modes were identified in the frequency range of 6 Hz to 20 Hz, and they occur at 8.1 Hz, 12.25 Hz and two between 15 Hz - 15.2 Hz. Detailed probing of the car body at the major resonances revealed the 8.1 Hz mode is the first vertical bending of the car body. The mode at 12.25 Hz was the motor alternator oscillating on its support beams in the longitudinal direction. The two modes between 15 Hz and 15.2 Hz involved localized bending of the three motor alternator lateral support beams and a higher order car body bending mode. The truck frame vertical frequency is approximately 9.8 Hz.

From the shake test data it was concluded that the two modes between 15 Hz and 15.2 Hz were the cause of the vibration problem identified in the ride quality surveys described in Section 2.4. The presence of these two modes in close proximity would cause beating of the car body vibration at a frequency equal to the difference of the two modal frequencies.

Since a major structural modification to the vehicle underframe would be required to shift the car body mode, the decision was made to stiffen the motor alternator support structure to separate the car body bending mode from the motor alternator support beam bending mode.

4.0 MOTOR ALTERNATOR SUPPORT STRUCTURE ANALYSIS

The results of the shake test described in Section 3.5 indicated the close proximity of two natural frequencies; the higher order car body bending mode, 15 Hz, and the motor alternator on its support structure, 15.2 Hz. It was decided to design a modification to the motor alternator support structure to introduce a sufficient degree of decoupling of the two modes.

4.1 DESCRIPTION OF ANALYSIS

To optimize the structural modification of the motor alternator support beams a finite element model was developed and is shown in Figure 28. Clock springs representing the side sill torsional stiffness were included to simulate the actual end conditions of the lateral beams. Additional node points were eventually added to the model to permit a detailed representation of the stiffening material. The final model of the proposed modification, with the values of beam bending inertia required to obtain the desired frequency shift, is also shown in Figure 28.

4.2 RESULTS OF ANALYSIS

Figure 29 shows a plot of the dynamic amplification factor of the motor alternator beam bending mode to the wheel rotational frequency for the baseline configuration and several frequencies up to 19.5 Hz, the objective for the modification. 19.5 Hz was selected by making a tradeoff between a practical structural modification of minimum weight and an acceptable dynamic amplification factor from the wheel rotational frequency. A frequency spread of approximately 4.5 Hz between the higher order car body bending mode and the motor alternator lateral beam bending mode would eliminate the possibility of beating.

In addition to separating the two vertical modes, an analysis was performed to optimize the structural modification required to shift the 12.25 Hz mode above 20 Hz. The necessary longitudinal stiffness was provided by four canted struts providing axial stiffness.

Photographs showing details of the lateral and longitudinal stiffening of the motor alternator support structure installed on the SOAC cars are presented in Figures 30 through 32. This installation was performed under Boeing Vertol supervision at the DOT HSGTC.

5.0 SECOND VEHICLE SHAKE TEST

Following the modification to the motor alternator support structure a second shake test was conducted.

5.1 PURPOSE OF TEST

The purpose of the second vehicle shake test was to determine the actual, as-built characteristics of the structural modification to the motor alternator support beams.

5.2 TEST EQUIPMENT

The test equipment was the same as described in Section 3.2.

5.3 TEST PROCEDURES

The test procedures were similar to those described in Section 3.3. The shaker was located at the R car end and only a vertical shake was performed.

5.4 RESULTS OF TEST

Frequency response curves for car body excitation are shown in Figures 33 and 34. All data presented are for a car weight of 90,000 lbs. and a shaker force of 500 lbs. A diagram showing the car body locations identified on these figures is presented in Figure 3.

From these curves several conclusions were determined:

- As expected, the structural modification did not change the frequency of the first vertical bending mode.
- The motor alternator longitudinal mode, previously at 12.25 Hz, has been shifted above 20 Hz as planned.
- 3. The higher order car body bending mode at approximately 15 Hz was unaffected.
- 4. Stiffening the motor alternator support beams shifted the beam bending mode to 19.4 Hz, close to the value predicted by the analysis of the modification. (See Figures 33 and 34.)

New mode shapes of the car body and motor alternator support beams are shown in Figures 35 and 36 respectively.

It should be noted that the coupler vibrated substantially at approximately 15 Hz and was shimmed throughout the test.

5.5 CONCLUSIONS

The structural modification to the motor alternator lateral support beams shifted the 15.2 Hz mode to 19.4 Hz. The motor alternator longitudinal mode, previously at 12.25 Hz, has been shifted above 20 Hz as planned. The 4.4 Hz frequency differential between the higher order car body bending mode (15 Hz) and the motor alternator lateral beam bending mode (19.4 Hz) insures there will not be beating between these two modes. This change in frequency should alleviate the vibration problem near 80 mph. Shifting the longitudinal mode above 20 Hz should eliminate the 12 Hz vibration previously noted near 64 mph.

6.0 SECOND RIDE QUALITY TEST

6.1 PURPOSE OF TEST

The purpose of the second SOAC ride quality test, also conducted at the HSGTC, was to determine the actual effectiveness of the motor alternator modification on ride quality.

6.2 TEST EQUIPMENT

The test car and instrumentation were the same as that described in Section 2.2. Resilient wheels had been installed on both SOAC cars in preparation for acoustic testing. The spring rates of the resilient wheels are several orders of magnitude higher than either the primary or secondary suspension system spring rates and would not be expected to influence vibration in the 0 Hz to 20 Hz frequency range.

6.3 TEST PROCEDURES

The procedures were the same as in Section 2.3.

6.4 RESULTS OF TEST

The ride quality summary of Figure 37 when compared with Figure 1 indicates the vibration at or near the rigid body suspension frequencies is virtually unchanged. At the higher frequencies there is little or no change over the bolster but significant improvement, from an average value of .07 g's to an average value of .05 g's, was measured at mid-car (Station 450) and at Station 225.

Comparison of Figure 38 with Figure 2 substantiates the improvement near 65 mph and 80 mph reported by observers. The mild vibration near 40 mph noticed in the initial ride quality test remains relatively unchanged. The frequency of vibration near 40 mph is associated with the first vertical bending mode and is unaffected by changes to secondary structure. At speeds between 40 mph and 70 mph, vibration at the center of the car and at Station 225 has been improved from .075 g's to .050 g's. No effect is noted over the bolster. The vibration previously observed near 65 mph is no longer evident. The beating of the vertical vibration observed near 80 mph has been eliminated.

Maximum acceleration levels are now about .10 g's near 15 Hz vs. .26 g's in the initial ride quality test. These levels are related to the higher mode of the primary structure which was unchanged. As predicted by the analysis, the response from the mode involving bending of the motor alternator support structure was eliminated.

Figures 4a and 4b show accelerometer waveforms of car body vertical accelerations at the center of the car before and after the change to the motor alternator support structure was made. These data indicated the beating phenomenon was eliminated by separating these two modes. Several circuits of the test track were made at 80 mph to insure the beat phenomenon did not occur on other track sections.

During the test a local vibration at 15 Hz was observed in the rear of the car. The data indicated the possibility of a car body-mounted component impacting the undercar structure. As noted in Section 5.4, the coupler vibrated considerably during the shake test at this frequency. This information led to the decision to temporarily install wooden shims near the coupler anchor. Data showing the improvement by shimming the coupler appears in Figure 39. The coupler centering mechanisms on Car 1 and Car 2 were not operative, thus permitting the couplers to vibrate. This condition will not exist with the coupler centering mechanism activated.

6.5 CONCLUSIONS

Ride quality characteristics of the vehicle were altered by modification of secondary support structure while characteristics influenced by primary structure were unchanged. Vibration levels decreased from .07 g's to .05 g's at mid-car (Station 450) and Station 225. The mild vibration near 40 mph noticed in the initial ride quality test remains relatively unchanged but the vibration previously observed near 65 mph is no longer evident. The beating of the vertical vibration observed near 80 mph has been eliminated. Maximum acceleration levels are now about .10 g's near 15 Hz vs .26 g's in the initial ride quality test.

7.0 WHEEL CONCENTRICITY TEST

7.1 PURPOSE OF TEST

The purpose of the wheel concentricity test was to obtain a quantitative measure of the wheel flats, concentricity, and degree of lateral wheel runout. These data could then be compared to AAR Standards and wheel specifications for various transit authorities.

7.2 TEST EQUIPMENT AND PROCEDURES

During the test a fixture was attached to the axle centerline and four dial gages were mounted to this fixture in such a way that they made contact with the wheel. Figures 40 and 41 show a picture of the test apparatus. Two gages were used to measure the concentricity and two to measure the lateral wheel runout. The measurement of concentricity was made at the tape line, the specified location for measurement of wheel diameter. This tape line is 2-13/32 inches from the outside rim.

After the fixture and gages were in position, a forklift was used to pull the car so that ten or more measurements could be taken for one wheel revolution. This process was repeated for all wheels on both SOAC cars. For data collection purposes each wheel was designated an identification number. Figure 42 presents this information.

7.3 RESULTS OF TEST

This test was performed after the initial ride quality vibration survey indicated high car body vibration levels. During that time it is believed wheel wear reduced the magnitude of the flats. This theory is substantiated by observation that the "wheel click" was reduced substantially over this time period. Journal box accelerometer data taken after the braking and performance tests showed a spike at the wheel rotational frequency. This spike was not evident in journal box data collected shortly before the concentricity test.

A summary of the wheel concentricity and lateral runout test results is presented in Figure 43. Total Indicator Reading (TIR) for these parameters is shown for all eight wheels of both SOAC 1 and SOAC 2. Tabulated data of all concentricity measurements made during the test are shown in Figures 44 through 47. Measurement of wheel flat and buildup data are shown in Figure 48. A maximum buildup of .007 inch on the SOAC 1 occurred on the No. 3 wheel. Wheel No. 7 on SOAC 2 had a maximum buildup of .011 inch. Wheel flat data indicated a maximum depth of .018 inch (No. 3 and No. 4 wheels) and .010 inch (No. 2, 6 and 7 wheels) on SOAC No. 1 and SOAC No. 2 respectively.

7.4 CONCLUSIONS

A comparison of TIR for all eight wheels of both SOAC 1 and 2 with AAR Standards and several transit authorities' standards (see Figure 43) indicates the eccentricity of the SOAC wheels is well within these specifications.

8.0 CONCLUSIONS

8.1 INITIAL RIDE QUALITY TEST

The results of the ride quality test provided a quantitative substantiation of the severe vibration evident near 80 mph in the SOAC. Mild vibration was reported between 35 mph and 45 mph and near 64 mph. Car body vertical accelerometer waveforms indicated that a high amplitude vibration with a ninesecond beat was present in the data measured at the center of the car near 80 mph.

8.2 INITIAL VEHICLE SHAKE TEST

Four car body flexible modes were identified in the 6 to 20 Hz range. From the test data it was concluded that the two modes between 15 Hz and 15.2 Hz were the cause of the vibration problem identified in the initial ride quality test. These two modes involved localized bending of the three motor alternator lateral support beams and a car body bending mode. The presence of these two modes in close proximity would cause beating of the car body vibration at a frequency equal to the difference between the two modal frequencies.

8.3 MOTOR ALTERNATOR SUPPORT STRUCTURE ANALYSIS

A finite element model was developed to optimize the structural modification of the motor alternator support beams. Structural members were sized to shift the 15.2 Hz mode to 19.5 Hz. This frequency was selected by making a tradeoff between a practical structural modification of minimum weight and an acceptable dynamic amplification factor from the wheel rotational frequency.

8.4 SECOND VEHICLE SHAKE TEST

The structural modification to the motor alternator lateral support beams shifted the 15.2 Hz mode to 19.4 Hz. The 4.4 Hz frequency differential between the higher order car body bending mode (15 Hz) and the motor alternator beam bending mode (19.4 Hz) insures against beating between these two modes. This change in frequency should alleviate the vibration problem near 80 mph. Shifting the longitudinal mode above 20 Hz will reduce the 12 Hz vibration levels near 64 mph.

8.5 SECOND RIDE QUALITY TEST

The modification to the motor alternator support structure eliminated the objectionable vibration near 64 mph and the beating phenomenon near 80 mph. Maximum vibration levels at the higher frequencies (15 Hz) have been reduced from .26 g's to .1 g. Although this exceeds the design goal of .055 g's at this frequency, this is probably the result of data reduction technique as explained in Section 1.4. The SOAC is considered satisfactory by passenger observers.

8.6 WHEEL CONCENTRICITY TEST

All eight wheels of both SOAC 1 and 2 were well within the AAR and several transit authority standards for wheel concentricity and lateral runout.

9.0 RECOMMENDATIONS

A review of the SOAC shake test and ride quality test procedures, equipment and data collection techniques have prompted the inclusion of this section of the report. Its purpose is to document pertinent facts learned during these tests and to make recommendations to improve future testing.

9.1 SHAKE TESTING

When performing a rail car shake test, the following should be considered:

- 9.1.1 Utilize a continuous sweep oscillator to control the shaker frequency. Simultaneously obtain accelerometer output, amplitude and phase vs. frequency and automatically record these data with an X-Y plotter. If this equipment is not available, frequency sweeps should be performed manually in sufficiently small increments to define accurately the system frequency response curves. If manual tuning of the shaker is required, a fine adjustment of the frequency should be made in the region of a resonant amplitude to precisely determine the modal frequency.
- 9.1.2 An accelerometer should be located on the structure adjacent to the shaker location to determine amplitude and phase at the input source. These data are helpful in providing a check on the recording instrumentation.
- 9.1.3 A sufficient number of accelerometers should be used to expediently determine the flexible mode shapes. If the number of available accelerometers is limited, probes of the structure must be undertaken to accurately determine details of the mode shapes.
- 9.1.4 Car body equipment mounts should be checked to insure that they are not bottoming at any frequency or amplitude.
- 9.1.5 Throughout the duration of the test, visual observations should be made to detect any panel or equipment resonances.
- 9.1.6 To determine the car body modes and frequencies, excitation should be applied in three directions: vertical, lateral and longitudinal. The shaker should be placed at two locations on the structure to insure that one of the locations is not a node point of a mode. It is recommended that one point lie off the car centerline to obtain ample excitation of the car body lateral/torsion modes.
- 9.1.7 Excitation should be applied to the truck frame to determine vertical/pitch/roll modes and frequencies.

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- 9.1.8 Frequency response curves should be generated for any massive car body-mounted equipment.
- 9.1.9 On-site data reduction should be performed so that modes and frequencies can be identified while the test is still in progress in the event further investigatory testing is required.

9.2 RIDE QUALITY TESTING

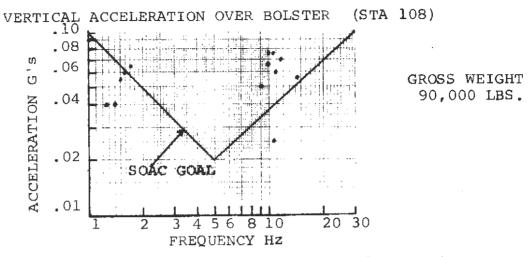
For ride quality testing:

- Any speed sweeps should be made over the same track section.
- Periodically walk through the vehicle to note any panel, seat, door or floor motion.
- 3. Relate frequencies observed in the ride quality testing to modes and frequencies determined in the shake test in order to establish which mode is the primary contributor to the vibration levels at each speed.
- 4. Monitor the "quick look" outputs to insure that paper speed and gains yield meaningful and easily readable data.

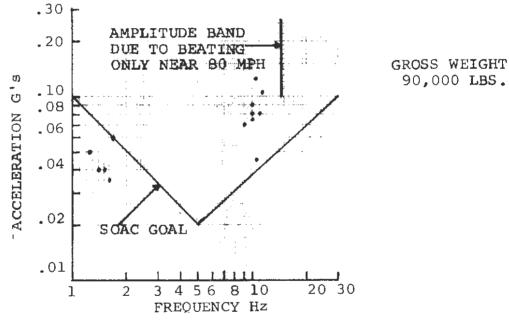
9.3 GENERAL

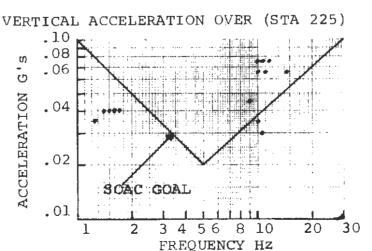
- 9.3.1 A relationship between car body modal frequencies and primary excitation frequencies throughout the speed range should be obtained to optimize the design of the vehicle to achieve superior ride quality characteristics.
- 9.3.2 A three-dimensional finite element analytical model of the car body should be developed and include primary and secondary structural elements to calculate the coupled natural modes and frequencies. These results should be compared to the relationships described in Item 9.3.1 to determine if any modification to the structure is required.
- 9.3.3 Analytical predictions of the car body and truck modes and frequencies should be correlated with shake test data to confirm the validity of the idealization techniques.
- 9.3.4 A ride quality test should be performed to confirm the relationships established in 9.1.1 above.





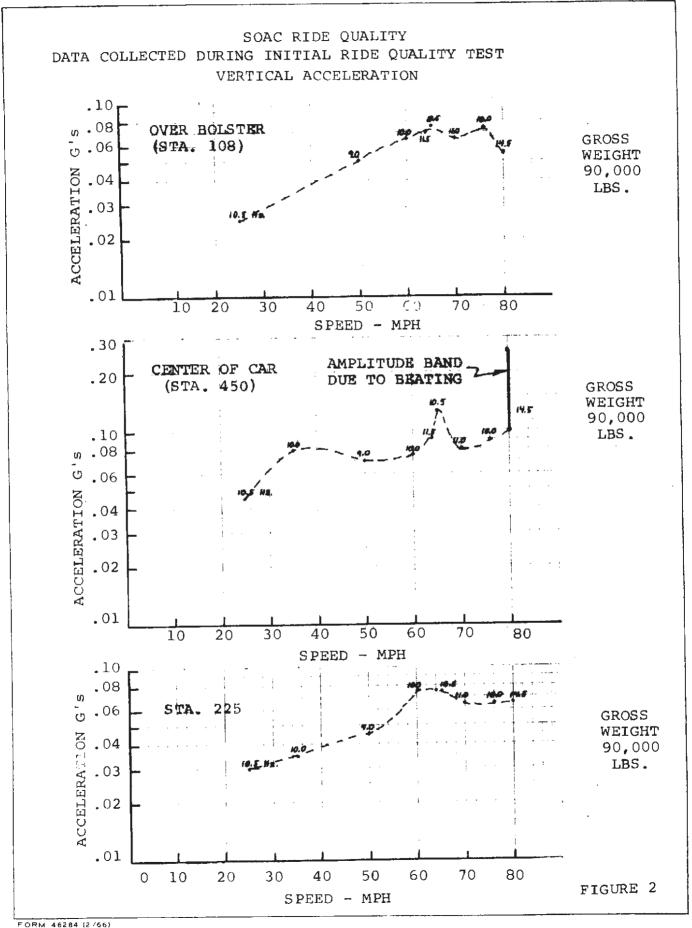
VERTICAL ACCELERATION OVER CENTER OF CAR (STA 450)





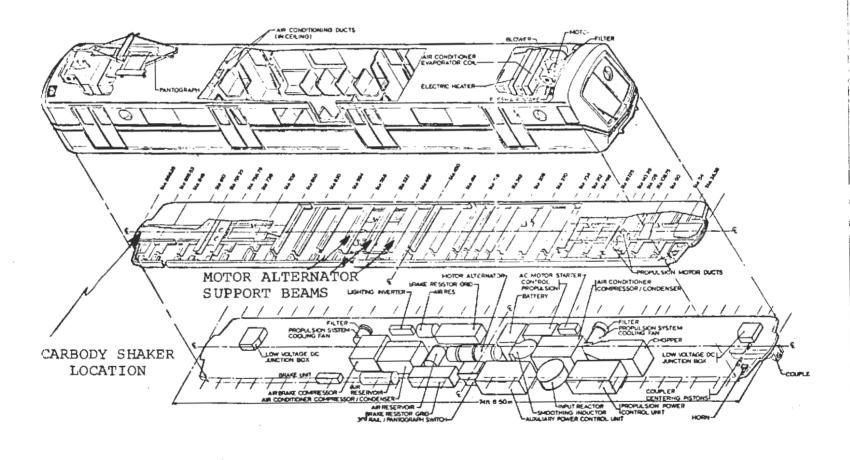
GROSS WEIGHT 90,000 LBS.





SHEET

27

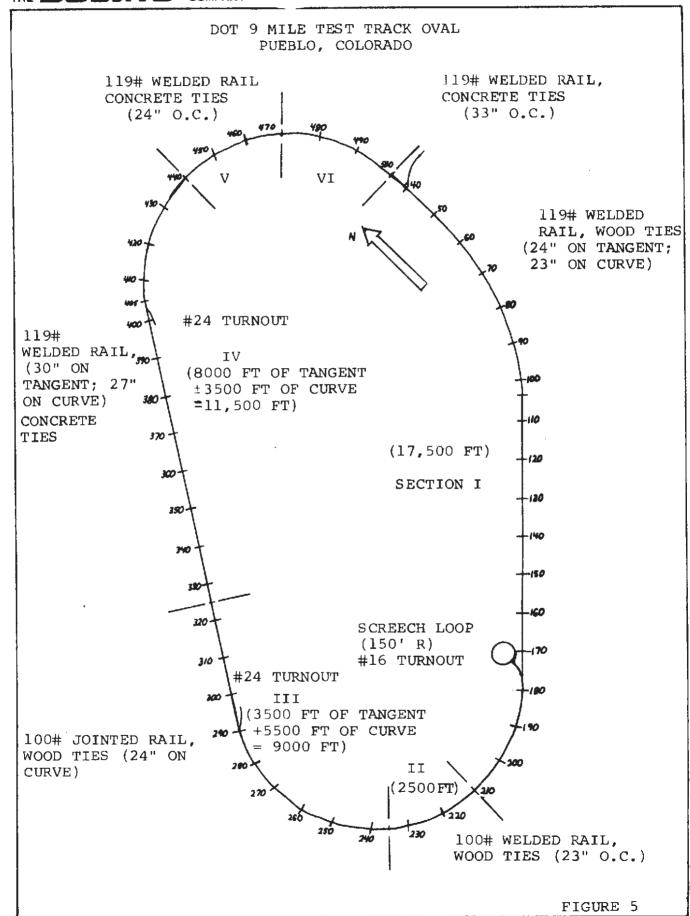


SOAC EXPLODED VIEW

CARBODY VERTICAL ACCELERATION GROSS WEIGHT = 90,000 LB. CENTER OF CAR (STA 450) 80 MPH SPEED SAMPLE ACCELEROMETER OUTPUT INITIAL RIDE QUALITY TEST .5 g's/In. PEAK ACCELERATION = .26 g's 8 5 6 2 3 1 0 TIME - SECONDS FIGURE 4a RIDE QUALITY TEST AFTER MOTOR STRUCTURAL MODIFICATION ALTERNATOR .5 g's/In. PEAK ACCELERATION = .10 g's 8 5 3 1 2 0 TIME - SECONDS

FIGURE 4b

FORM 11180 (6/67)





SOAC VIBRATION DATA

Gross Weight = 90,000 Lb. Welded Rail

Speed = 80 MPH

Effect of Secondary Suspension Houdaille Vertical Dampers

Pickup	Dampers On	Dampers Off
Car Longitudinal Mid Car Vertical Motor Alternator Vert. Traction Motor Vert. Car Cab Vertical Truck Bolster Motion Vertical	.037 g @ 14.5 cps .125 g @ 14.5 cps Not Available .75 g @ 11 cps .05 g @ 1.5 cps t .2 Inches	.05 g @ 14 cps .05 g @ 14 cps .10 g @ 14 cps .5 g @ 11 cps .037 @ 1.25 cps ± .2 Inches
Truck Bolster Vertical	.35 g @ 15.5 cps	Not Available

Effect of Motor Alternator Shims

Pickup	Wood Shims	Steel Shims	No Shims
Car Longitudinal Mid Car Vertical Motor Alternator Vertical	.015g @ 14 cps .037g @ Random .075g @ 14 cps	.062g @ 14.5cps .09g @ 14.5cps .15g @ 14.5cps	.05g @ 14cps
Traction Motor Vertical	.25g @ 14 cps	lg @ 11.5cps	.5g @ llcps
Car Cab Truck Bolster Motion Vertical	.075g @ 1.25 cps ± .2 Inches	.062g @ 1.25cps ±.25 Inches	.037g@1 .2 5cps ±.2 Inches

VERTICAL SHAKER CONFIGURATION

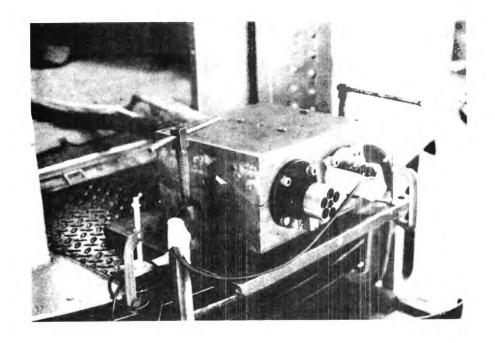


FIGURE 7a

LONGITUDINAL SHAKER CONFIGURATION

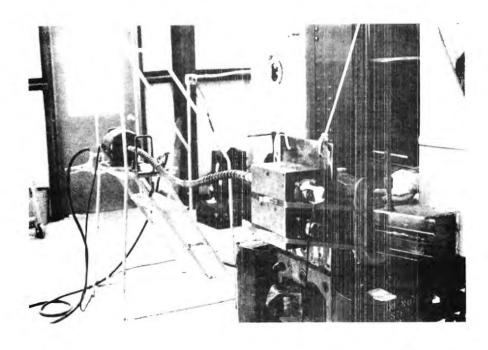
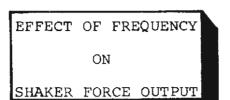
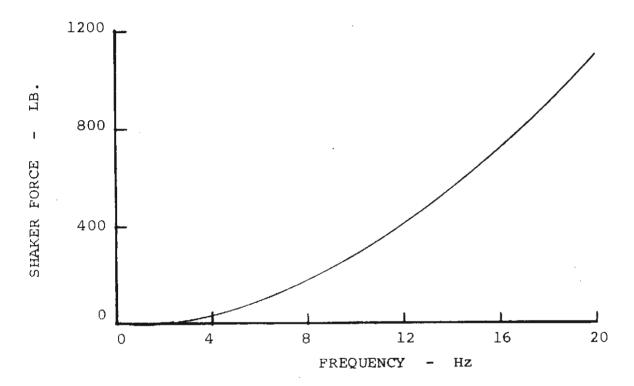


FIGURE 7b



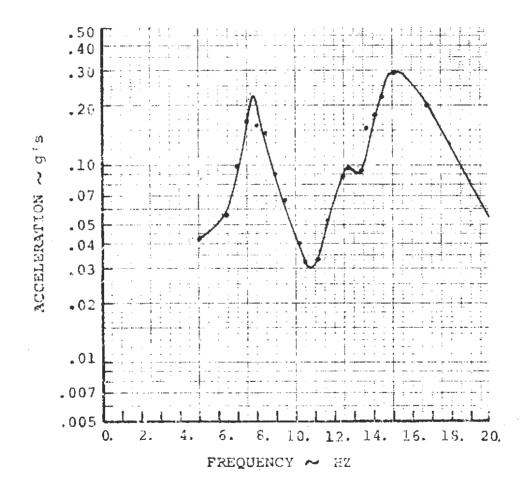
LAZAN MODEL LA1 SHAKER OUTPUT CHARACTERISTICS



SOAC SHAKE TEST?

Frequency Response Curves

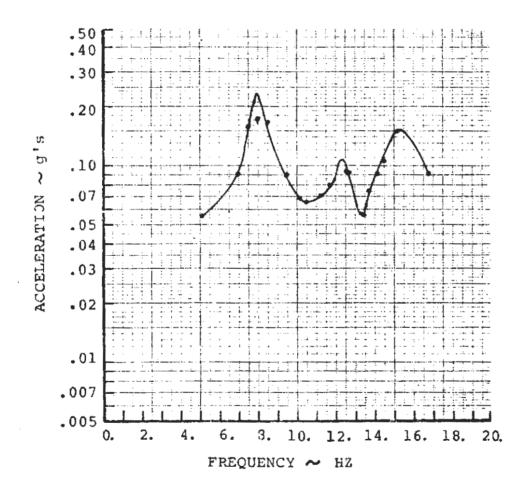
Shaker Location R CAR END
Shaker Force 500 LB
Shaker Direction VERT
Gross Weight 90000 LB
Vertical Damper Config. 0FF
Motor Alternator Config. No SHIMS
Pick-Up Location R CAR END VERT



SOAC SHAKE TEST

Frequency Response Curves

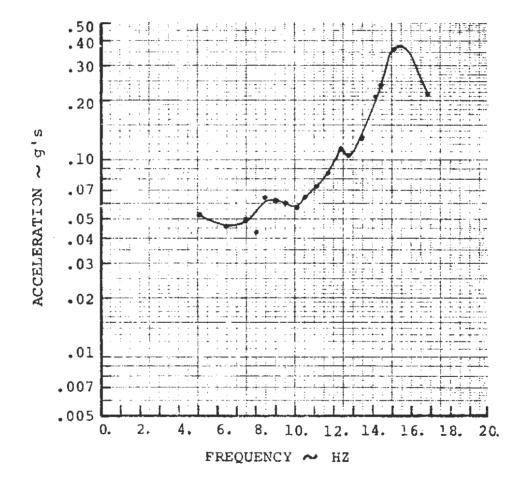
Shaker Location R CAR END
Shaker Force 500 LR
Shaker Direction VERT
Gross Weight 90000 LB
Vertical Damper Config. OFF
Motor Alternator Config. NO SHIMS
Pick-Up Location STA 450 CVERT



SOAC SHAKE TEST

Frequency Response Curves

Shaker Location R CAR END
Shaker Force 500 L8
Shaker Direction VERT
Gross Weight 9000 L8
Vertical Damper Config. 0FF
Motor Alternator Config. NO SHIMS
Pick-Up Location STA 673 ~ NERT



SOAC SHAKE TEST

Frequency Response Curves

Shaker Location R CAR FND

Shaker Force 500 LB

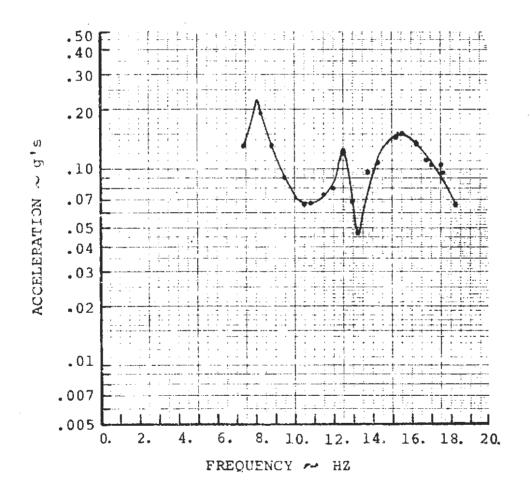
Shaker Direction VERT

Gross Weight 90000 LB

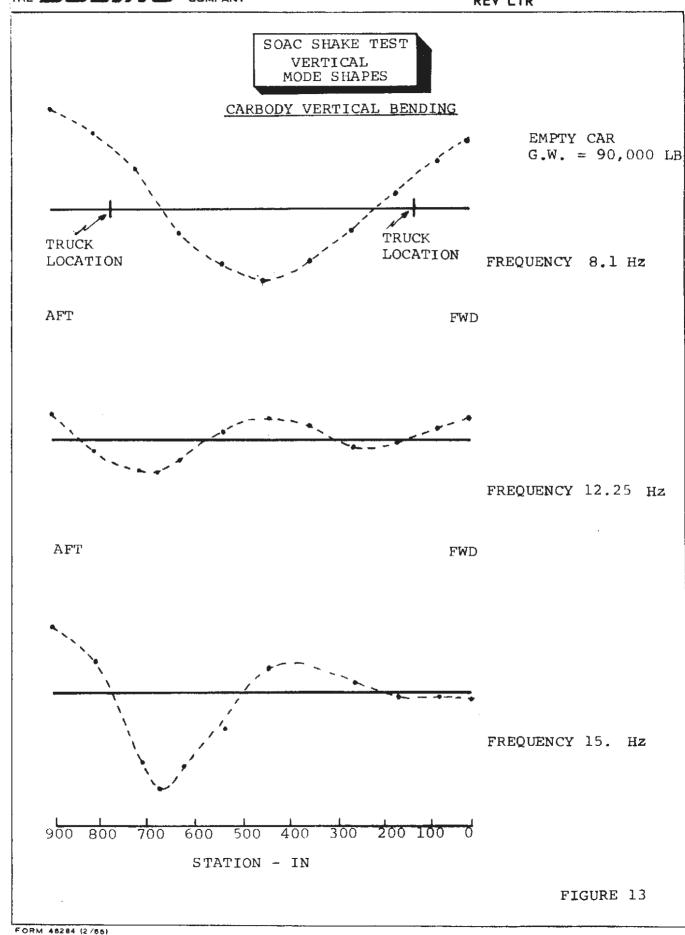
Vertical Damper Config. OFF

Motor Alternator Config. NO SHIMS

Pick-Up Location NOTOR ALTERNATOR ~ VERT



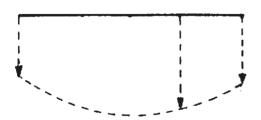






SOAC SHAKE TEST VERTICAL MODE SHAPES

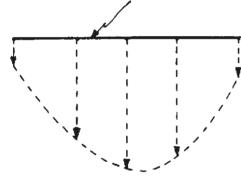
MOTOR ALTERNATOR LATERAL SUPPORT BEAM



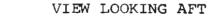
FREQUENCY = 8.10 Hz

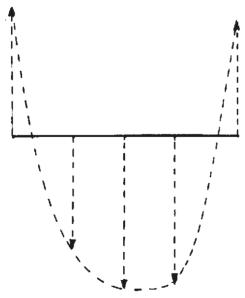
VIEW LOOKING AFT

MOTOR ALTERNATOR LATERAL SUPPORT BEAM

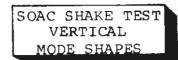


FREQUENCY = 12.25 Hz





FREQUENCY = 15.2 Hz



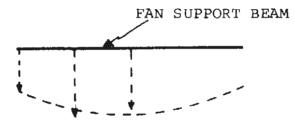
MOTOR FAN SUPPORT BEAM



EMPTY CAR G.W. = 90,000 LB.

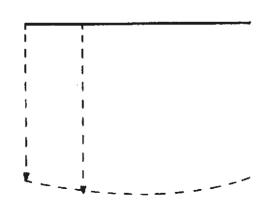
FREQUENCY = 8.10 Hz

VIEW LOOKING AFT



FREQUENCY = 12.25 Hz

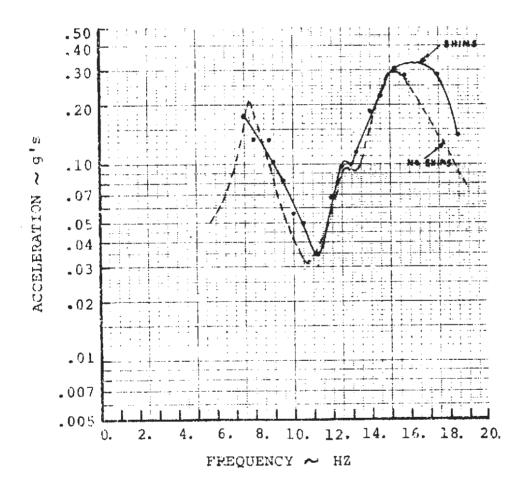
VIEW LOOKING AFT



FREQUENCY = 15.2 Hz

Frequency Response Curves

Shaker Location R CAR END
Shaker Force 500 LB
Shaker Direction VERT
Gross Weight 90000 LB
Vertical Damper Config. OFF
Motor Alternator Config. SHIMS
Pick-Up Location R CAR END ~ VERT



Frequency Response Curves

Shaker Location R CAR FHD

Shaker Force 500 LR

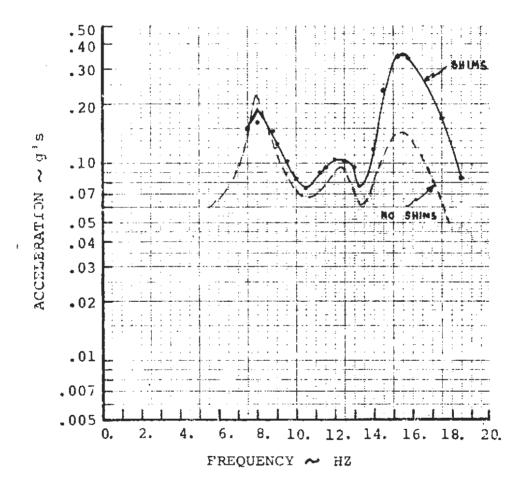
Shaker Direction VERT

Gross Weight 90000 LR

Vertical Damper Config. OFF

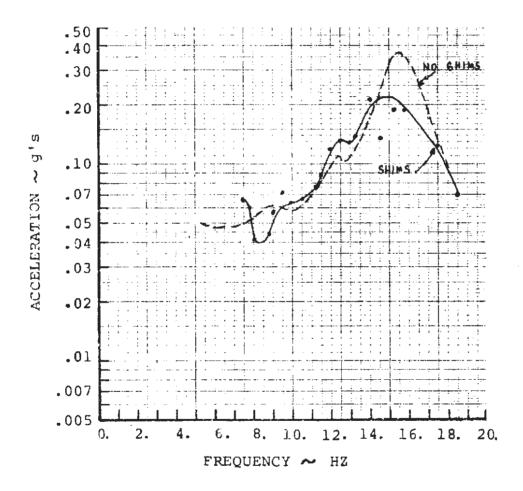
Motor Alternator Config. SHIMS

Pick-Up Location STA 450 ~ VERT



Frequency Response Curves

Shaker Location R CAR END
Shaker Force 500 LB
Shaker Direction VERT
Gross Weight 90000 LB
Vertical Damper Config. OFF
Motor Alternator Config. SHIMS
Pick-Up Location STA 673~VERT



Frequency Response Curves

Shaker Location R CAR END
Shaker Force 500 LB
Shaker Direction VERT
Gross Weight 9000 LB
Vertical Damper Config. OFF
Motor Alternator Config. SHIMS
Pick-Up Location MOTOR ALTERNATOR VERT

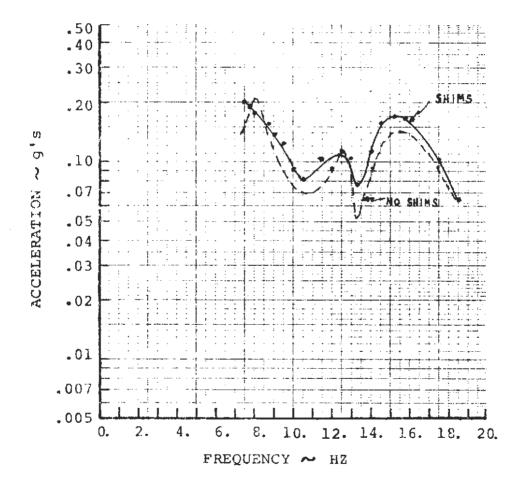
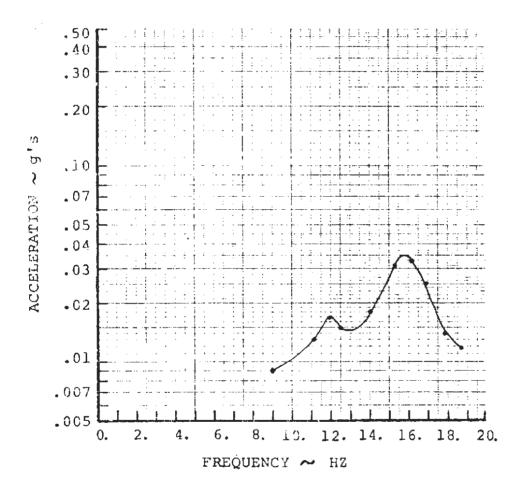


figure 19

Frequency Response Curves

Shaker Location R CAR END
Shaker Force 500 LB
Shaker Direction Long
Gross Weight 9000 LB
Vertical Damper Config. OFF
Motor Alternator Config. No SHIMS
Pick-Up Location STA 673~YERT



Frequency Response Curves

Shaker Location A CAR END

Shaker Force 500 LB

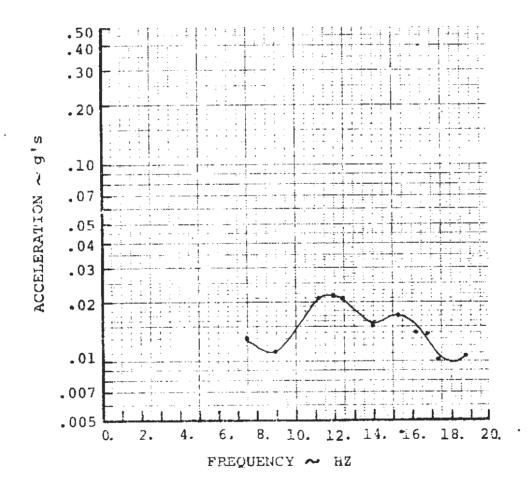
Shaker Direction LONG

Gross Weight 90000 LB

Vertical Damper Config. OFF

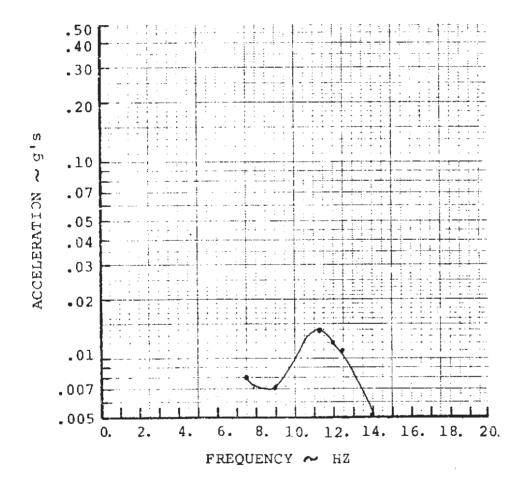
Motor Alternator Config. NO SHIMS

Pick-Up Location MCTOR ALTERNATOR ~ LONG



Frequency Response Curves

Shaker Location R CAR END
Shaker Force 500 LB
Shaker Direction Long
Gross Weight 90000 LB
Vertical Damper Config. OFF
Motor Alternator Config. No SHIMS
Pick-Up Location R CAR END ~ LONG



Frequency Response Curves

Shaker Location R CAR END

Shaker Force 500 LB

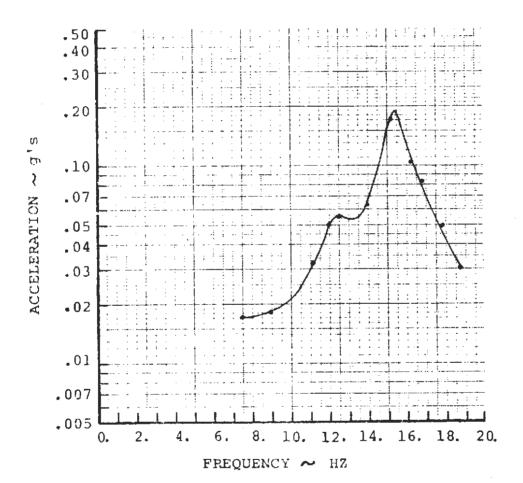
Shaker Direction LONG

Gross Weight 90000 LB

Vertical Damper Config. OFF

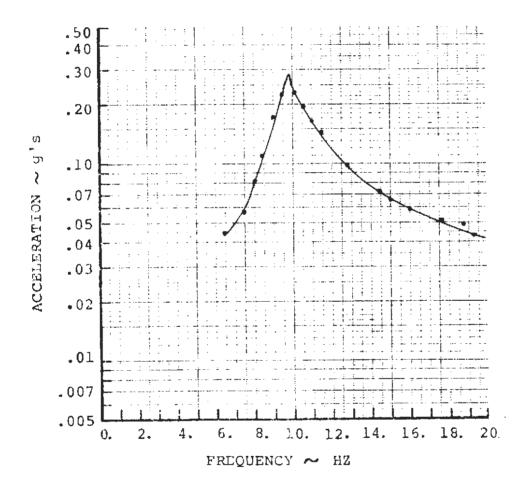
Motor Alternator Config. NO SHIMS

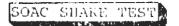
Pick-Up Location MID CAR SEAT BACK ~LONG



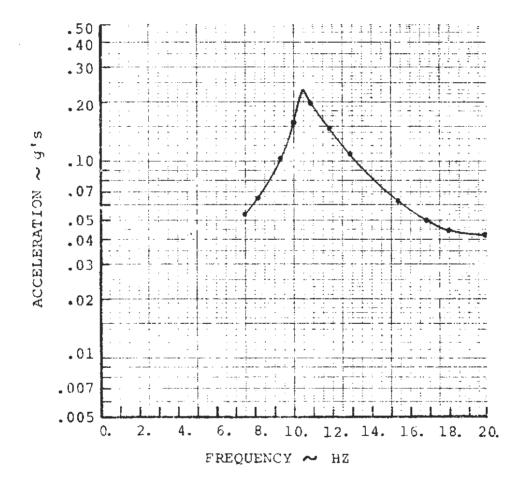
Frequency Response Curves

Shaker Location TRUCK FRAME
Shaker Force 500 LB
Shaker Direction VERT
Gross Weight 90000 LB
Vertical Damper Config. 0FF
Motor Alternator Config. NO SHIMS
Pick-Up Location TRUCK FRAME ~ VERT



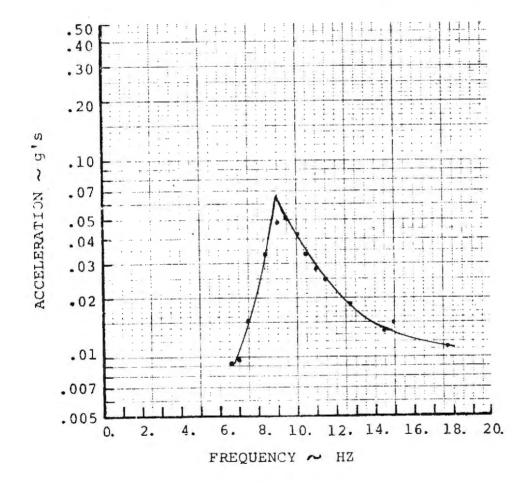


Frequency Response Curves



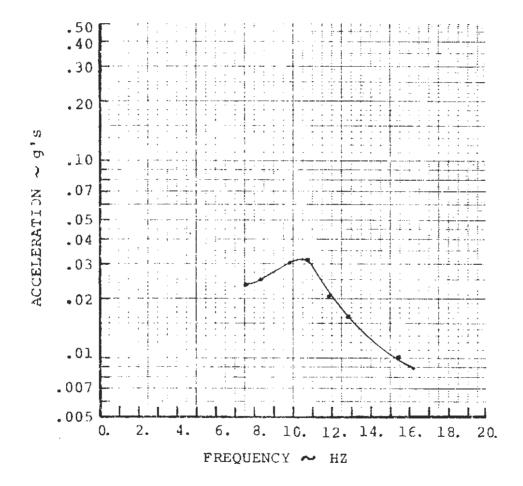
Frequency Response Curves

Shaker Location TRUCK FRAME
Shaker Force 500 LB
Shaker Direction VFRT
Gross Weight 90000 LB
Vertical Damper Config. OFF
Motor Alternator Config. No SHIMS
Pick-Up Location B CAR END ~ VERT



Frequency Response Curves

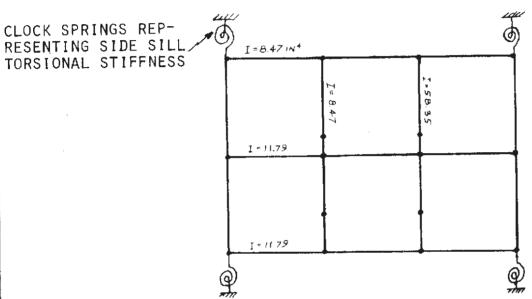
Shaker Location TRUCK FRAME
Shaker Force 500 LB
Shaker Direction VERT
Gross Weight 90000 LB
Vertical Damper Config. 0N
Motor Alternator Config. No SHIMS
Pick-Up Location G CAR END ~ VERT



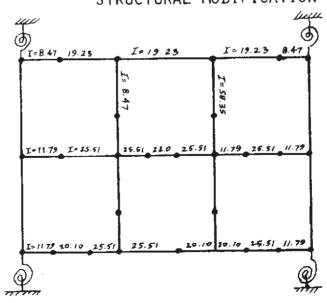


FINITE ELEMENT ANALYTICAL MODEL SOAC MA SUPPORT STRUCTURE

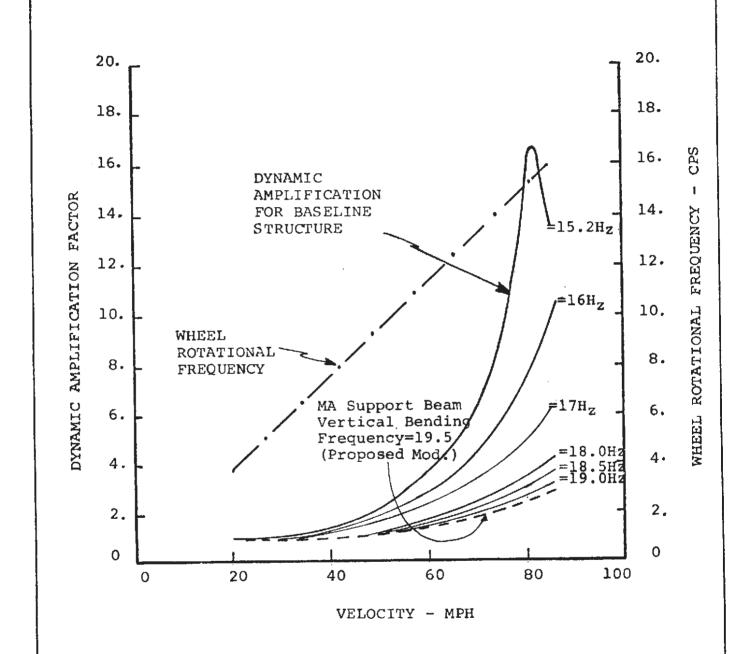
BASELINE CONFIGURATION



STRUCTURAL MODIFICATION

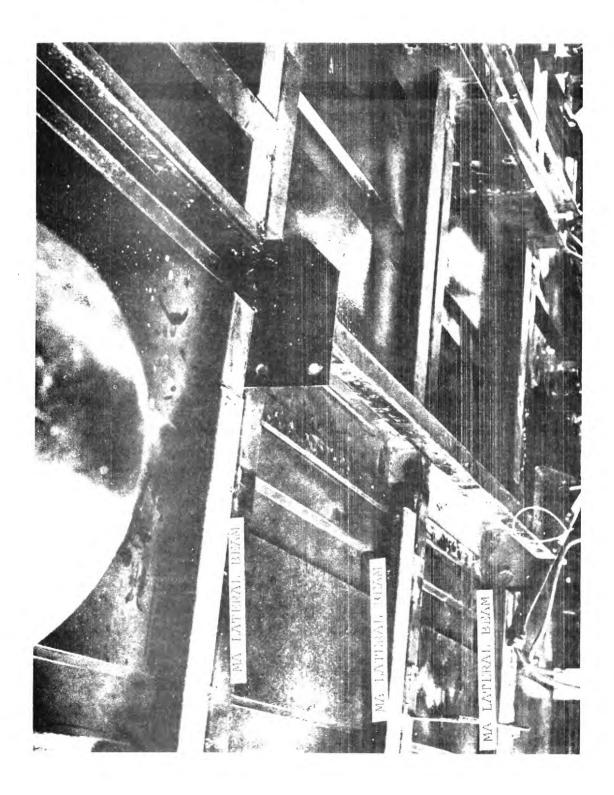


EFFECT OF CARBODY STRUCTURAL MODIFICATION ON DYNAMIC AMPLIFICATION



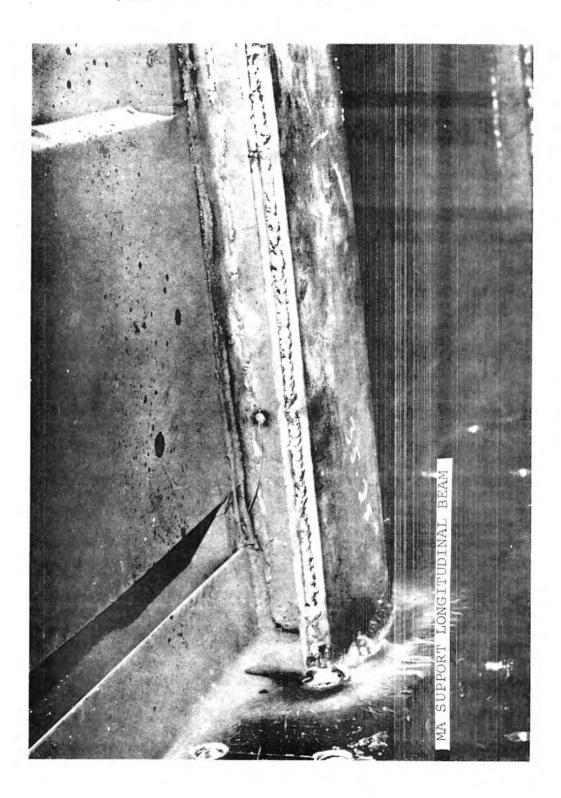


MOTOR ALTERNATOR STRUCTURAL MODIFICATION IN PROGRESS



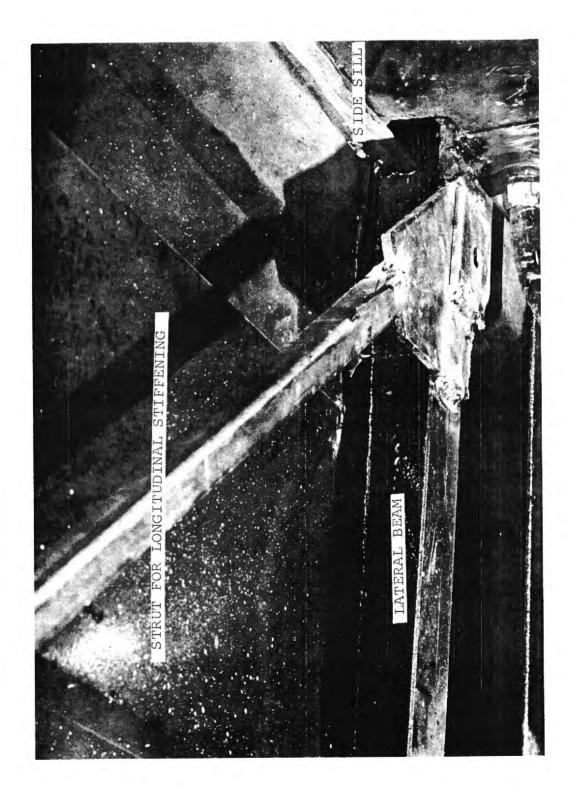


MOTOR ALTERNATOR STRUCTURAL MODIFICATION (DETAIL OF LATERAL STIFFENING)





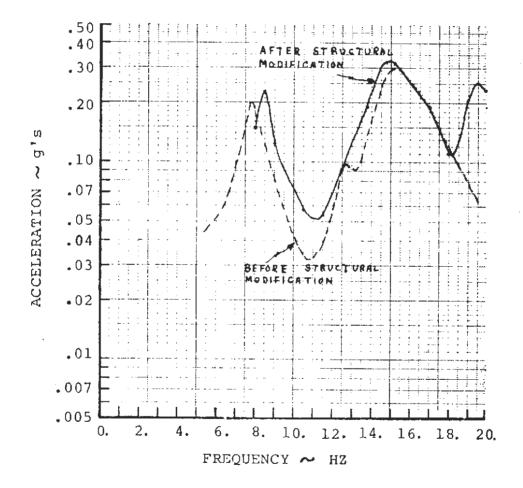
MOTOR ALTERNATOR STRUCTURAL MODIFICATION (LONGITUDINAL STIFFENING)



Frequency Response Curves

Data Collected After Motor Alternator Support Modification

Shaker Location R CAR END
Shaker Force 500 LB
Shaker Direction VERT
Gross Weight 90,000 LBS
Vertical Damper Config. OFF
Motor Alternator Config. NO SHIMS
Pick-Up Location R CAR END-VERT

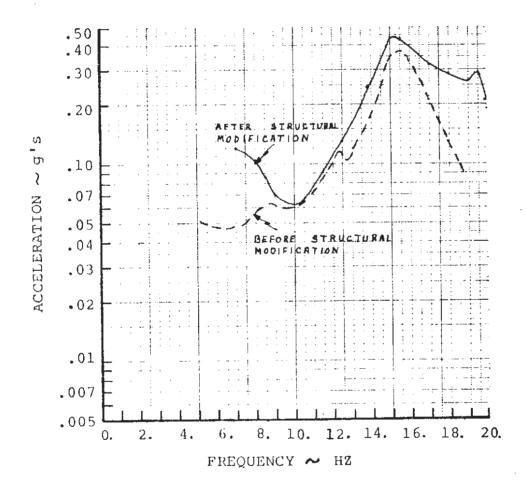




Frequency Response Curves

Data collected After Motor Alternator Support Modification

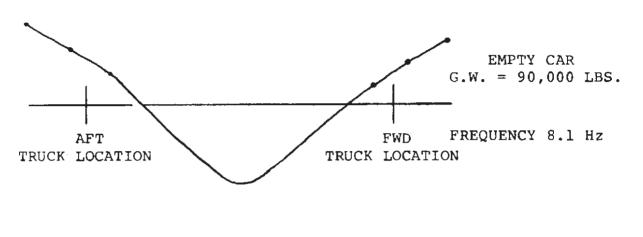
Shaker Location R CAR END
Shaker Force 500 LBS.
Shaker Direction VERT.
Gross Weight 90,000 LBS.
Vertical Damper Config. OFF
Motor Alternator Config. NO SHIMS
Pick-Up Location STA 673 VERT.

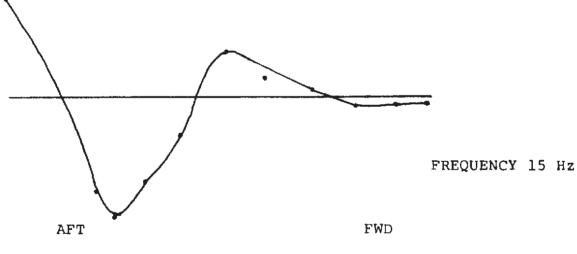


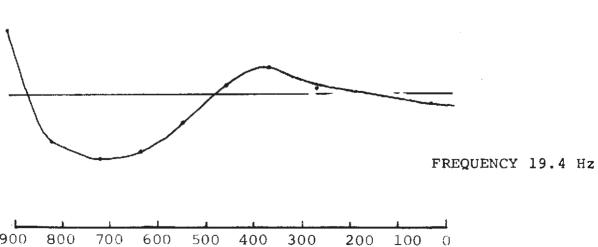
SOAC SHAKE TESTS VERTICAL MODE SHAPES

CARBODY VERTICAL BENDING

DATA COLLECTED AFTER MOTOR ALTERNATOR SUPPORT MODIFICATION







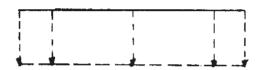
FORM 46284 (2/66)

STATION - IN

SOAC SHAKE TESTS VERTICAL MODE SHAPES

MOTOR ALTERNATOR LATERAL SUPPORT BEAM

DATA COLLECTED AFTER MOTOR ALTERNATOR SUPPORT MODIFICATION

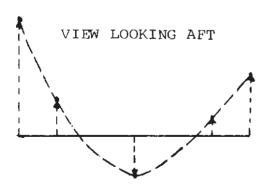


FREQUENCY = 8.1 Hz

VIEW LOOKING AFT

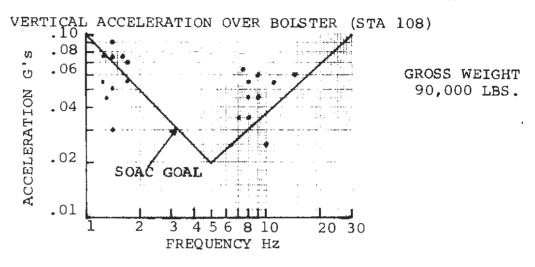


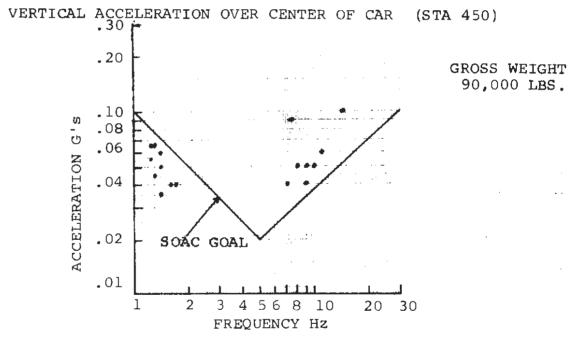
FREQUENCY = 15.2 Hz

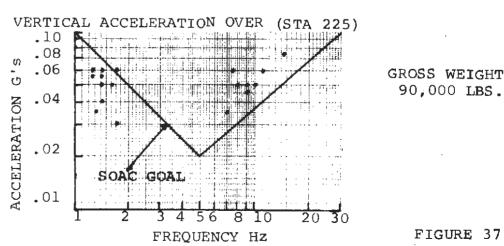


FREQUENCY = 19.4 Hz

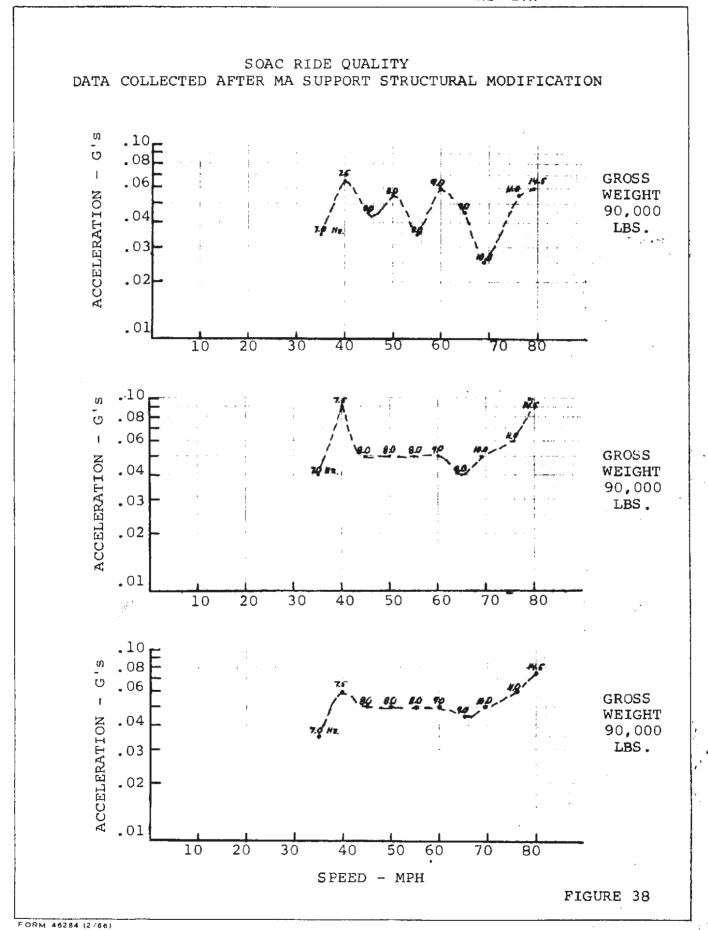
SOAC RIDE QUALITY DATA COLLECTED AFTER MA SUPPORT STRUCTURAL MODIFICATION

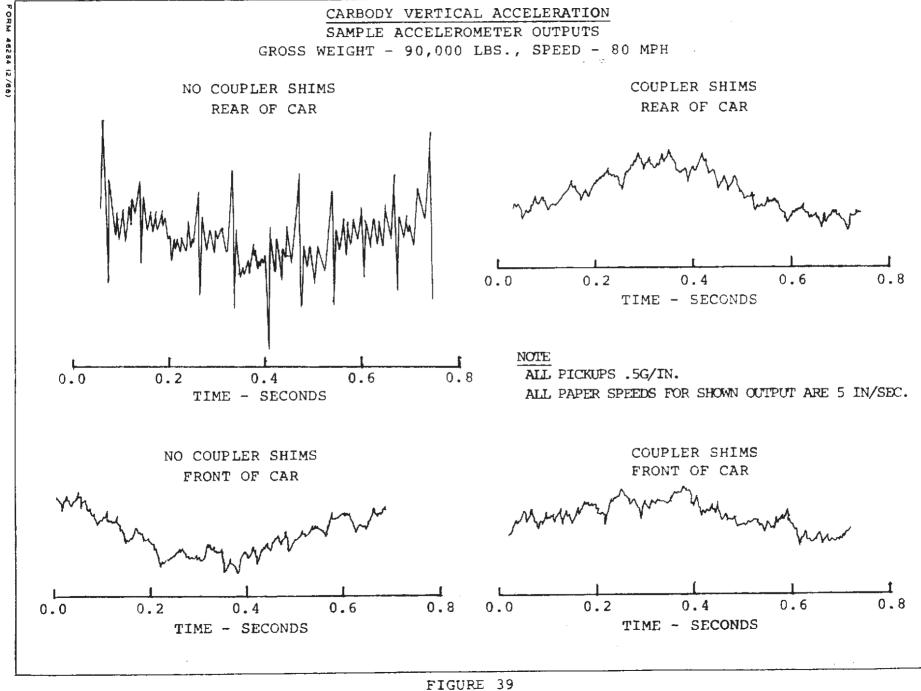












SHEET

63

WHEEL CONCENTRICITY AND LATERAL RUN-OUT



FIGURE 40

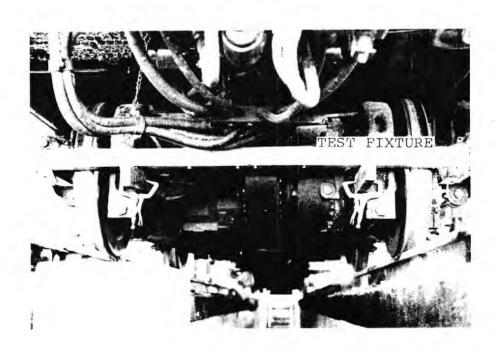
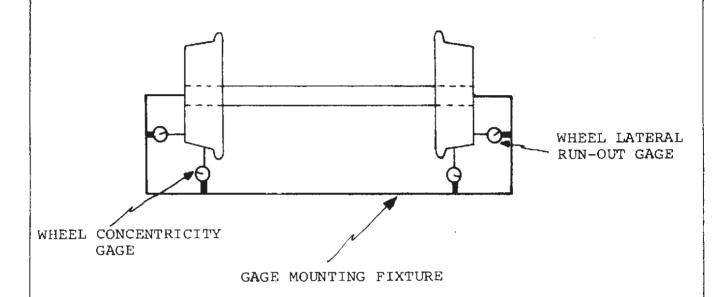


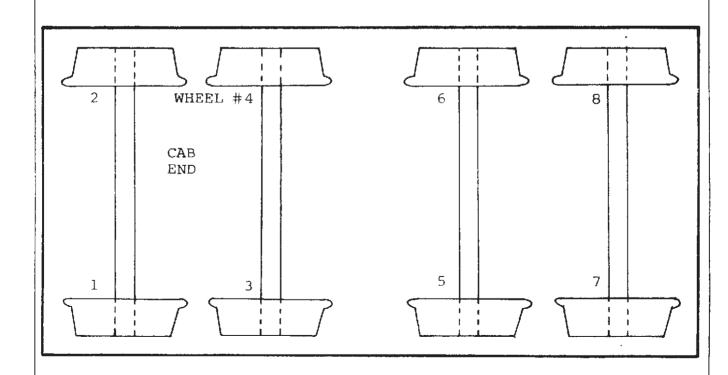
FIGURE 41

WHEEL CONCENTRICITY TEST APPARATUS AND

WHEEL IDENTIFICATION DIAGRAM

VIEW LOOKING DOWN





WHEEL IDENTIFICATION DIAGRAM

FIGURE 42

FORM 46284 (2766)



SUMMARY OF TEST RESULTS

WHEEL CONCENTRICITY AND LATERAL RUN-OUT TEST

	WHEEL No.	T.I.R.	T.I.R.
		Concentricity	Lateral Run Out
	1	.005	.012
•	2	.008	.011
	3	.006	.012
SOAC 1	4	.005	.006
	5	.006	.005
	6	.004	.008
	7	.005	.008
	8	.003	.007
	ł	.002	.021
	2	.003	.004
	3	.005	.014
	4	.003	.011
SOAC 2	5	.006	,00G
	6	.010	,010
	7	,008	.007
	8	.007	.014

WHEEL SPECIFICATIONS

			NORTH			
	AAR	SOAC	JERSEY	N.H.R.R.	SEPTA	I.C.
Eccentricity at Tre a d	.030	.0156	.00 7	.007	.030	.03
Unbalance at Rim	2.Lb	3 02.	-	. –	_	2. Lb
Lateral Run-Out	.090	.032		.015	.090	. 090

DATA - WHEEL CONCENTRICITY TEST

SOAC # 1

	WHEEL			WHEEL	<u> 3</u>
Wheel Position (Clock)	Concentricity	Run Out	Wheel Position (Clock)	Concentricity	Run Out
9:00	0.0	0.0	4:00	.000	.000
7:30	003	002	3:00	002	001
3:00	,001	.008	2:30	002	003
6:00	001	.001	1:45	-,003	006
4:30	003	003	1:00	-,003	009
12:00	.002	,010	11:30	006	012
2:00	.002	,010	10:30	-,005	012
11:00	.001	.007	9:15	-,004	-,011
7:30	-201	.001	8:15	-,004	008
9:00	.000	,001	7:/5	~.003	005
			6:00	003	001
			5:00	001	,000
<u> </u>			4:00	-,001	,000

WHEEL 2

3:00	0.0	0.0		WHEFI	- 4
.4:30	.002	.000			
9:00	.008	010	8:00	.000	,000
6:00	.005	010	9:00	001	002
7:30	,008	011	9:30	001	-,003
12:00	.004	- ,008	10:15	-202	006
10:00	20G	- ,011	11:00	003	-,005
1:00	.001	004	12:30	005	003
4:30	.002	002	1:30	-,004	,000
3:00	,001	001	2:45	-,004	.000
			3:45	-,004	001
	<u> </u>		4:45	004	002
	Ì		6:00	-:001	002
			7:00	001	-,002
		•	8:00	,000	-,002
			_		
			ļ		
			!		
L	<u> </u>				



DATA - WHEEL CONCENTRICITY TEST SOAC #1

	WHEE	5		WHEE	L 6
wheel Position (Clock)	Concentricity	Run Out	Wheel Position (Clock)	Concentricity	Run Out
6:00	.000	.000	6:00	.000	.000
7:30	.002	002	4:30	001	-, <i>0</i> 03
8:00	202	002	4:00	,000	005
9:00	,004	003	3:00	.001	004
10:00	.005	004	2:00	.003	006
11:00	.004	004	1:00	<i>.0</i> 03	003
12:00	.003	005	12:00	203	-,002
1:00	.002	005	11:00	.003	7,002
2:00	.001	005	10:00	.002	001
3:00	,000	-,004	9:00	.002	.000
4:00	001	-, <i>0</i> 03	8:00	.001	.002
5:00	001	003	7:00	2000	.002
6:00	.000	-,003	6:00	,000	.001
7:30	.001	004	4:30	-,001	,000

WHEEL 7

WHEEL 8

7:45	.000	.000	4:15	.000	.000
7:00	7.002	001	5:00	.000	.000
€:00	7.002	002	6:00	.001	002
5:00	003	003	7:00	.000	004
4:00	003	003	8:00	.000	006
3:00	.000	001	9:00	.000	007
1:45	<i>-002</i>	.002	10:15	.001	005
1:00	.002	.004	11:00	2000	005
12:00	.002	.004	12:00	.000	003
10:45	201	.005	1:15	001	003
9:45	.001	.005	2:15	002	002
9:00	.000	.003	3:00	001	002
7:45	001	.001	4:15	.000	-,002
6:45	0 03	.000	5:15	.000	002
•			-		
				New York	
					1

DATA - WHEEL CONCENTRICITY TEST

SOAC #2

	WHEEL			WHEEL	2
Wheel Position (Clock)	Concentricity	Run Out	Wheel Position (Clock)	Concentricity	Run Out
6:30	.000	.000	5:30	.000	.000
7:30	.001	00/	4:30	.000	.000
8:30	,000	006	3:30	.000	<i>0</i> 02
10:00	.000	-,02/	2:00	001	.000
1/100	.001	02/	1:00	002	.002
12115	001	016	11:45	002	.002
1:00	.001	-,012	11:00	002	.002
2:00	.001	-,007	10:00	003	.001
3:00	.000	004	9:00	003	.000
4:00	2000	~.001	B:00	002	.000
5:30	.000	003	6:30	002	001
6:30	,001	-,004	5:30	-,002	.000

WHEEL 3

WHEEL 4

4:00	.000	.000	8:00	,000	.000
2:45	.002	010	9:15	.000	002
2:00	.002	010	10:00	.000	-,002
1:00	.002	7,014	11:00	.001	-,005
12:00	,001	013	12100	.002	007
11:00	.000	012	1:00	,003	-209
10:00	002	01/	2100	.003	010
9:00	003	-,009	3:00	.003	009
8:00	003	00 8	4:00	.002	007
7:00	-,002	006	5:00	.001	003
5:45	.000	004	6:15	.000	001
4:00	.001	~,004	8:00	.000	.001
3:30	201	006	8:30	.000	.000
			[



DATA - WHEEL CONCENTRICITY TEST

SOAC #2

	WHEEL	<u>. 5</u>		WHEE	<u>L 6</u>
Wheel Position (Clock)	Concentricity	Run Out	Wheel Position (Clock)	Concentricity	Run Out
12:30	.000	.000	11:30	. 000	.000
2:00	,001	002	10:00	002	~.002
3:30	.004	-,005	8:30	002	-205
4:30	.006	004	7:30	1001	~004
6:00	.006	003	6:00	.005	-,003
8:00	.004	.000	4:00	.008	.000
9:00	.002	001	3100	.008	001
6:30	.006	002	5130	.006	002
10:30	,000	001	1:30	.005	001
12:00	,000	.001	12:00	.001	.001

WHEEL 7

WHEEL 8

3:00 1:30 12:00 10:45 9:00 7:30 6:00 4:30 3:00	.000 001 003 007 008 007 005 002	.000 002 005 007 006 002 .000 001	9:00 10:30 12:00 1:15 3:00 4:30 6:00 7:30 9:00	.000 002 004 005 003 001 .002 .002	.000 .002 001 .000 005 008 .006 003

SUMMARY OF TEST RESULTS

WHEEL FLAT AND BUILD-UP DATA

SOAC #1

WHEEL #	WHEEL POSITION	FLAT	BUILD-UP
1 2 3	No Data No Data 9:30 o'clock 11:00 o'clock	.018	.007
4 5	9:30 o'clock 11:00 o'clock 12:00 o'clock	.018 .016 .010	
7	8:00 o'clock 12:00 o'clock 8:00 o'clock 5:00 o'clock	.005 .005 .012 .005	
8	12:00 o'clock 6:00 o'clock 7:00 o'clock 12:00 o'clock 1:15 o'clock	.012 .003 .008 .009	
	SOAC #2		
1 2	No Flats 8:30 o'clock 3:00 o'clock	.006 .010	
3 4 5	11:00 o'clock 8:00 o'clock 11:00 o'clock No Flats	.008 .007 .007	
7	3:30 o'clock 4:30 o'clock 3:00 o'clock	.010 .005 .005	
8	l2:00 o'clock 9:00 o'clock No Flats	.010	.011

		•
		•
		•

APPENDIX IV

EMI MEASUREMENT TEST REPORT

(Project WOll52-T)
April 10, 1973
(Revised Edition)

		ie.
		•



FINAL TEST REPORT

ELECTROMAGNETIC INTERFERENCE

ON

STATE OF THE ART CAR (SOAC)

FOR

THE BOEING COMPANY, VERTOL DIVISION

GOVERNMENT CONTRACT NO. US/DOT-UT-10007

PROJECT: WO 1152-T

APRIL 10, 1973

PALO ALTO, CALIFORNIA

NOTICES AND SIGNATURES

The test data presented herein, refer only to the particular test sample tested. Changes in circuit design, components, grounding, lead routing or bonding, regardless how insignificant they may seem, may negate the test results presented herein.

Prepared by:

Peter F. Spencer

Test Engineer

Electro Magnetic Filter Company, Inc.

Witnessed by: Mr. M. C. Bucher

B - Y Engineer

The Boeing Company

ADMINISTRATIVE DATA

PURPOSE OF TEST: The purpose of this test was to determine the conformance of the described specimen to the electromagnetic interference requirements of the applicable specification.

TEST COORDINATOR: THE BOEING COMPANY, VERTOL DIVISION
Boeing Center
Philadelphia, Pennsyvlania 19142

MANUFACTURER'S MODEL NUMBER: State of the Art Car

SECURITY CLASSIFICATION: Unclassified

SPECIFICATION OR EXHIBIT: Boeing Purchase Order Number CT 885569, Appendix A

DATE TEST COMPLETED: April 3, 1973

NUMBER OF ITEMS TESTED: Two (2) cars operating as one unit

TEST CONDUCTED BY: ELECTRO MAGNETIC FILTER COMPANY, INC.

4083 Transport Street
Palo Alto, California 94303

TEST CONDUCTED FOR: THE BOSING COMPANY, VERTOL DIVISION
Boeing Center, Post Office Box 16867
Philadelphia, Pennsylvania 19142

ABSTRACT: The test described herein was performed at the High Speed Test Center, Pueblo, Colorado.

The results of this testing demonstrate complete conformance to the radiated emission requirements of the specification.

FACTUAL DATA

1.0 DESCRIPTION:

1.1 The jest specimen was two state of the art cars coupled together and operating as a unit.

2.0 TEST INSTRUMENTATION:

- 2.1 Radio Interference Field Intensity Meter, Stoddart Model 1M-37-PRM-1A, Serial Number 215. Next calibration due July 1, 1973.
- 2.2 Radio Frequency Field Intensity Moter, Stoddart Model IM-88/URM-47, Serial Number 33. Next calibration due June 1, 1973.
- 2.3 Dipele Antenna Stoddart, Model Number AB-371/U.
- 2.4 Biconical Antenna, per MIL-STD-461A, Paragraph 5.2.3.

3.0 TEST PROCEDURE:

- 3.1 The test equipment was first set up inside one of the SOAC cars, at approximately the midpoint. Test equipment power was provided by a small auxiliary generator situated in the other car. All SOAC systems and third rail power were deenergized, and a complete scan of the frequency range (150 KHz to 400 MHz) was performed for the purpose of selecting those frequencies (approximately four per decade) at which radio interference field intensity would be monitored throughout the remaining tests. A second frequency scan was performed after third rail power and all SOAC systems had been energized, in order to identify any emission frequencies (high interference peaks) for later checking during radiated emission tests with the instrumentation at a wayside location. There were none.
- 3.2 The test equipment was then set up adjacent to the tracks at a distance of 100 feet from the tracks on April 2 and 3, 1973, wayside measurements began at approximately 1:00 P.M. on the 2nd. Prior to testing the vehicle a complete scan of the frequency range was performed for the purpose of determining ambient interference levels.
- 3.3 Measurements were then performed with the test vehicle passing through a zone approximately 300 feet long directly in front of the

antenna location at speeds of 20, 40 and 80 miles per hour. See Figure 1. One north and one south pass was made for each frequency speed combination, except at 80 miles per hour, all runs were made in a southerly direction to take advantage of the slight down grade.

- 3.3.1 Additional measurements were then performed under conditions of maximum acceleration and braking.
- 3.3.2 Since the revised specification limits are derived from Specification MIL-STD-461A, the antennas prescribed by that specification were used for this testing. The resulting corrected data is then in standard units of dB >1 µV/M/MHz.
- 3.4 Based on previous testing experience, obtained on similar transit cars, which indicated horizontally polarized interference levels from the vehicle to be higher than vertically polarized levels at all frequencies above 30 MHz, all testing performed on the SOAC was with the biconnical and dipole antennas horizontally polarized. Antennas were located approximately five feet above ground level and approximately twelve feet above track grade.
 - 3.4.1 Toward the end of trackside measurements a powerful gust of wind toppled the biconical antenna and damaged it beyond repair. Further measurements were then performed using a 21" dipole antenna. Correction factors shown on data sheet 2 were found empirically in the lab by direct comparison of radiated fields using the two antennas.

4.0 TEST RESULTS:

- 4.1 Internal radiated emission measurements of ambient conditions and with all systems on were performed with the test equipment at only one location, for these reasons:
 - 4.1.1 There were no substantial noise peaks to necessitate tracking down a source.
 - 4.1.2 Because of the physical size and layout of the car, no significant differences could be expected between measurements that were taken in the middle of the car and measurements that might be taken elsewhere in the same car.
- 4.2 Internal and wayside radiated emission test results are presented in tabular form on data sheets 1 and 2. Wayside test results, plotted as a composite graph on Figure II, demonstrate complete conformance to specification limits.

4.2.1 Although readings at 32 MHz exceed specification limits by 2 dB, it should be noted that the ambient level corrected also exceeded the limit by the same amount. In addition, normal accepted tolerance limits for this type of testing are plus or minus 3 dB; therefore, the 32 MHz readings must be interpreted as complying with specification requirements.

5.0 CONCLUSIONS:

When tested as described herein, the SOAC demonstrated complete conformance to the radiated interference emission requirements of Booing purchase order No. CT 885569, Appendix A.

N. L. WELLINS	ang di manang kalaman ang laga lagan di sebebah atau manahan na manahan sa kalaman.		CRIPTION OF CHANGES		DY	- E D D	ATE
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	1						•_ •
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ENGINEERING TEST REPORT

	AMBIENT	ALL SYS. ON	OUTSIDE	20	MPH		401	MPH	80	MPH	AC	CEL,	DE	CEL.
	dBMV/MHZ	dB MV/MH2	AMBIENT	d <i>Bµ</i> √		FREQ. M.C			dBµ 5	V/MHZ S	dBr N	N /MAG	d8 µ	V/MHZ
	9L	96	91	Z96	496	i	696			196				496
31	92	95	91	291	691	į	<91			491	291	<91		1491
6	90	94	87		77		77	77	79		79	79	79	. 79
10	94	92	72	65	65		72	73	73	73	73	67	69	69
2	94	97	72	7/	72		73	73	75	77	76	75	76	77
4	8/	86	66	70	74		76	77	78	76	77	77	75	75
4 8	86	94	7/		73		72		71	76	74	73	77	15
16	84	83	62	73	71_		76	75	77		74	76	7/	73
32	43	52	47_	43	42		44		4.2		42		47	47
60	54	61	39		35		44	38				1° 34	40	36
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	} 		1	1			1						1	

COMMENTS

Very high noise signal @ = 195 MHZ (ambient)

* Readings @ 205 MHZ

Recorded levels at .16 & .31 MHz as 296 \$ 291 dB are ambient
levels of Dc to Ac power converter.

	CICNED	DATE	ENGINEER	DATE	DEPT. ENGIR.	DATE	CHIEF ENGR	DATE A
1					IV-8		it is a some	1.7.1.6



ENGINEERING TEST REPORT

		50 A	STATE C) O EMIS					1					2 -73		
PRESS.	AN7 FA	CORR	AMBIENT CORR.	بر مد <i>دهه</i> ط8ها	PH P/MHZ		M PH CRA: M / MHZ	<u>.</u>	80	PAP H PAP MAINS	ACC.	F MIL	DE CE	e Z' M / AM Z	SPEC.
	d		dBpV/N/MAZ		5	N	ی ا		5	5	N	#	<u>~</u>		dBuV/MM
116		<u>6</u>	97	1	2/02	1	1						4/02		1
.31		· · · · · · ·	97	497	297		<97		297		497	<97		497	106
. 6			83	83	83	83	83		85	85	85	85	85	85	102
1.0	<u> </u>		78	ZL	7/	78	179	-	79	79	79	75	75	75	106
2_			78	77	78	77_	78		81	83	92	83	82	83	97
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8	ļ <u>-</u> !		77	76_	78	78	78	 	72	79	80	79	73	70	9/
16			68	79		82	81		83	56	55	58	80	60	87
32		3 2	48	56	55	2	56	<u> </u>	119	4.9	58	52	49	45	58 58
120	9	+5	46	44	52	53	49	l	43	46	47	43	71	73	68
200	17	- 2	32	51	51	53	50		49	49	51	47	رسير	51	68
100	1.1.	0	32	32	32	32	32	<u> </u>	32	32	35	35	31	31	68
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